

Achieving Mass Conservation in Adaptive Semi-Lagrangian Advection Schemes

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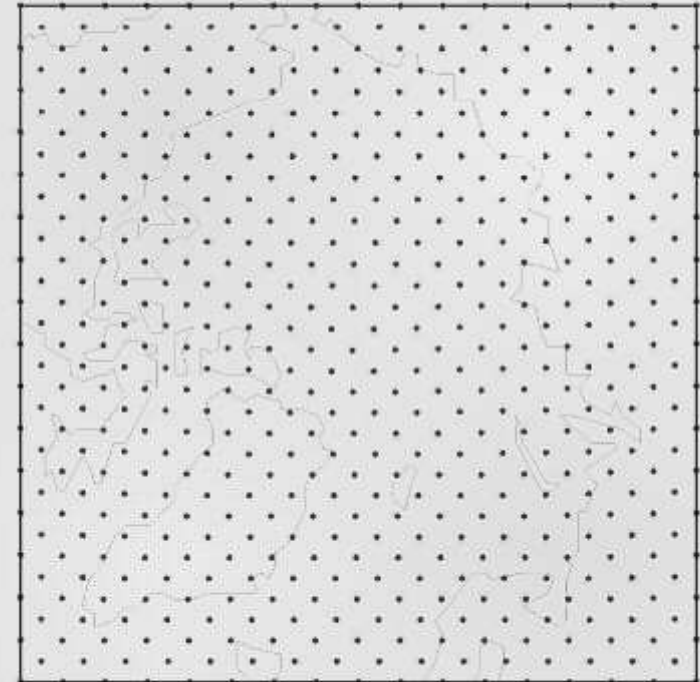
Adaptive Semi-Lagrangian Simulation I

Adaptive simulation of Trace Gas Transport in the Arctic Stratosphere



PLOT: tracer variable

(c) Jörn Behrens, 1998



PLOT: semi-Lagr. trajectories

(c) Jörn Behrens, 1998

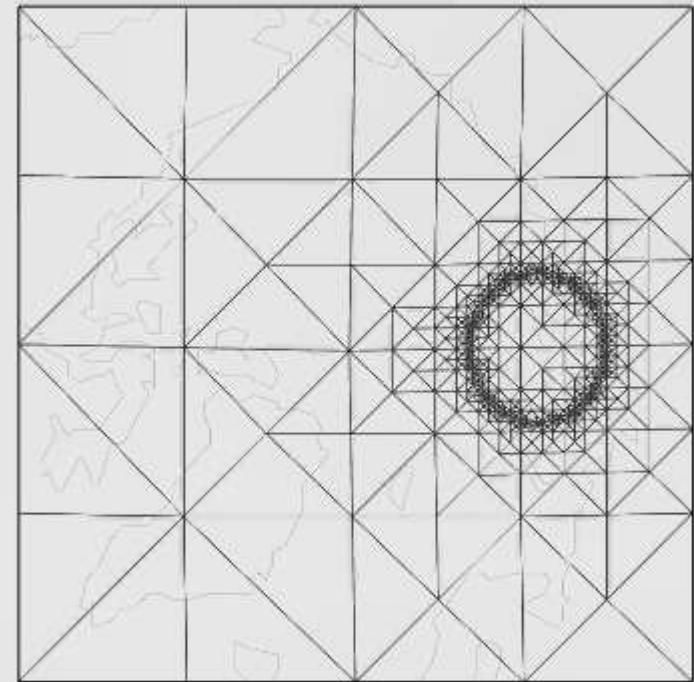
Adaptive Semi-Lagrangian Simulation II

Adaptive simulation of Trace Gas Transport in the Arctic Stratosphere



PLOT: tracer variable

(c) Jörn Behrens, 1998

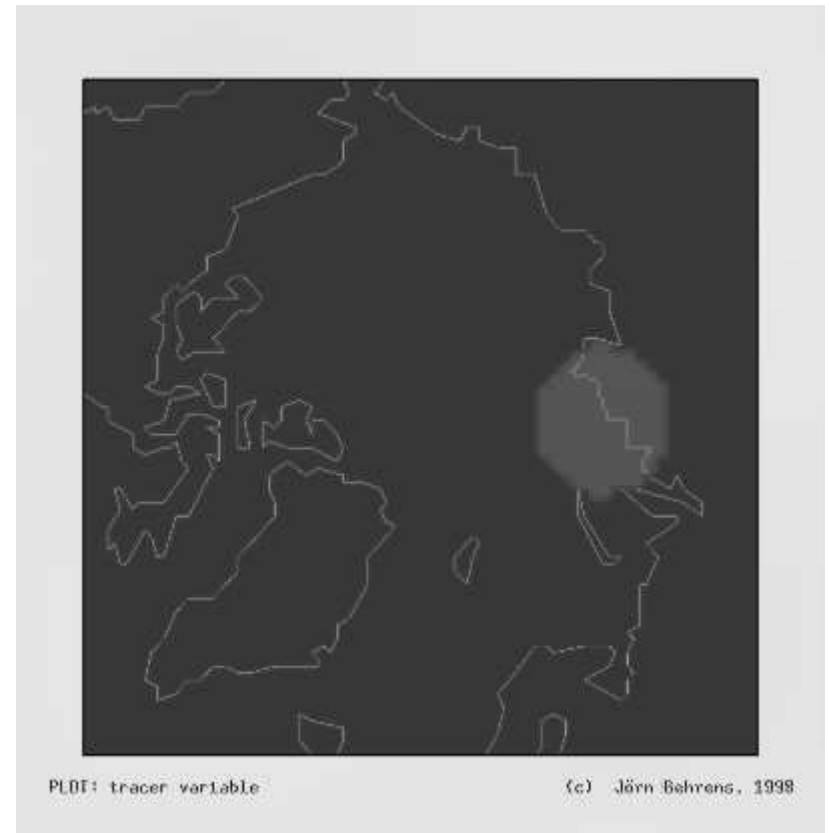


PLOT: discretization mesh

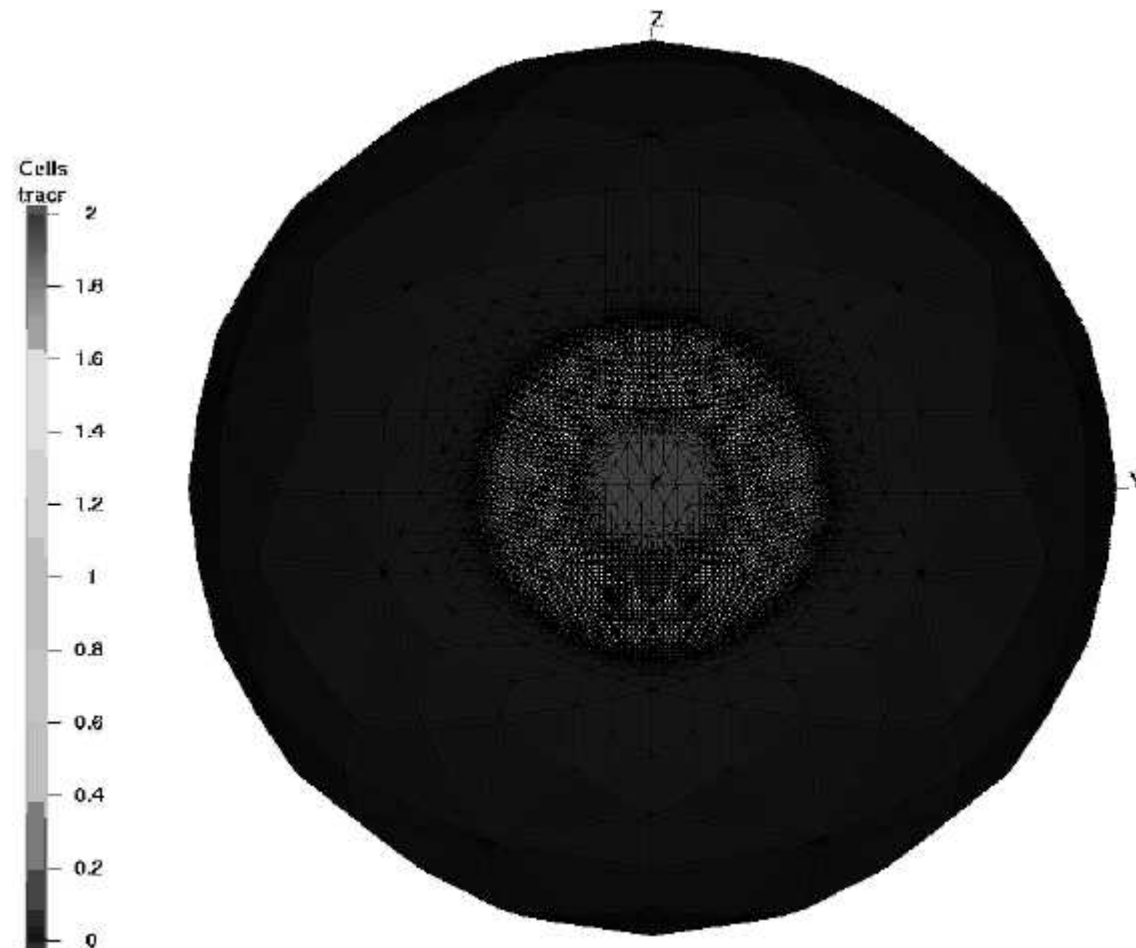
(c) Jörn Behrens, 1998

Adaptive Semi-Lagrangian Simulation III

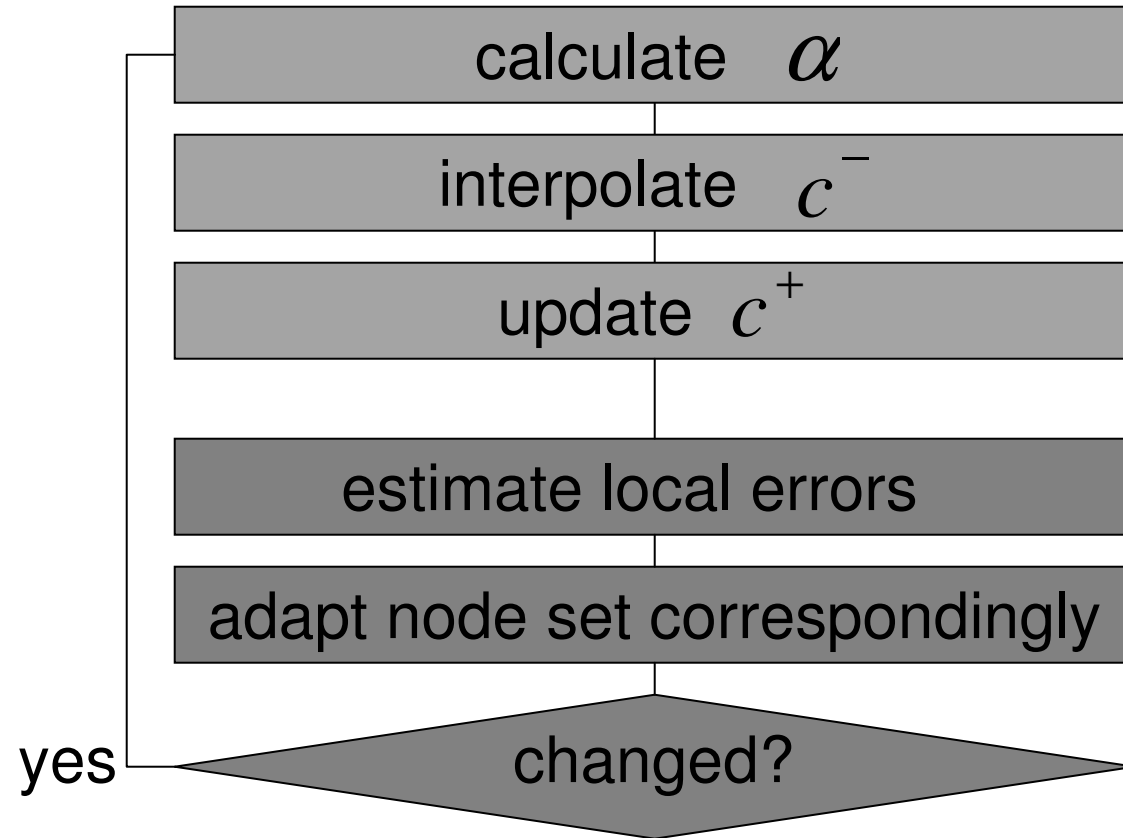
Adaptive simulation of Trace Gas Transport in the Arctic Stratosphere



Adaptive Semi-Lagrangian Simulation IV



Adaptive Semi-Lagrangian Algorithm



Features of SLM

- Suitable for adaptivity
- Stable – no time step control for stability
- Parallelizable – each trajectory independent

Not conservative by construction

→ Objective: Construct Conservative Scheme

Existing Work

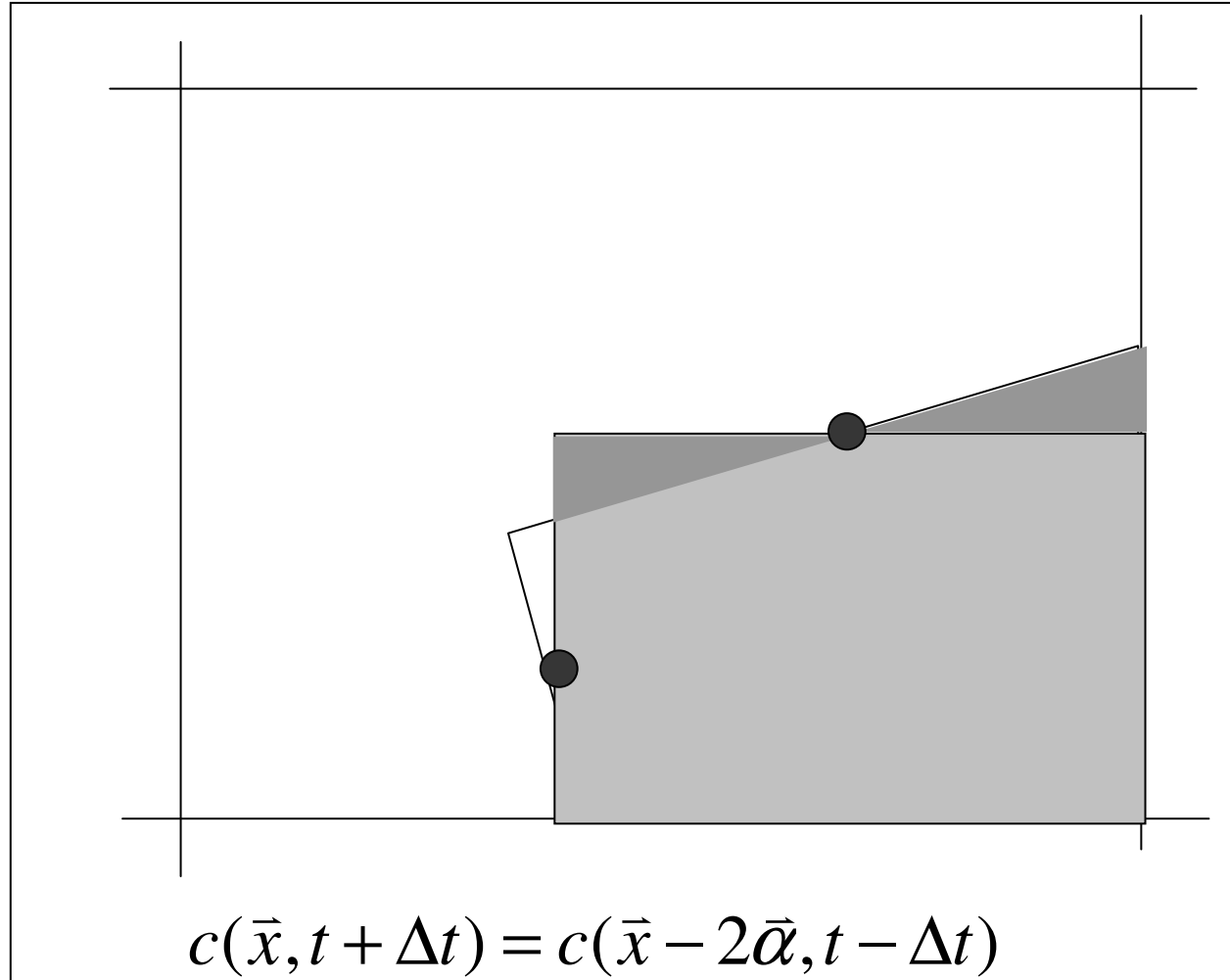
Priestley's Scheme

- Based on conserving mass globally
- Linear programming approach
- Exact conservation
- Possibly non-physical

Xiao/Yabe Scheme

- Based on geometry
- Exact conservation
- Locally exact

Cell Integrated Scheme



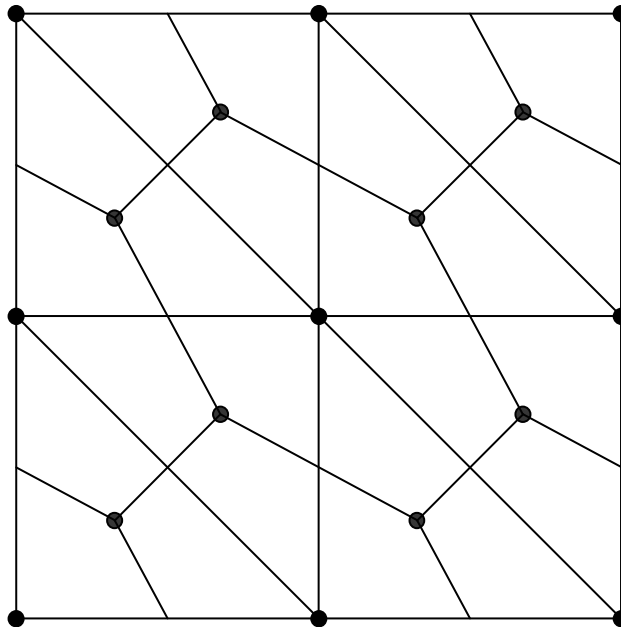
$$c(\bar{x}, t + \Delta t) = c(\bar{x} - 2\bar{\alpha}, t - \Delta t)$$

$$c(\bar{x}, t + \Delta t) = Vol(\text{ } \square \text{ }) \cdot c(\bar{x}^*, t - \Delta t)$$

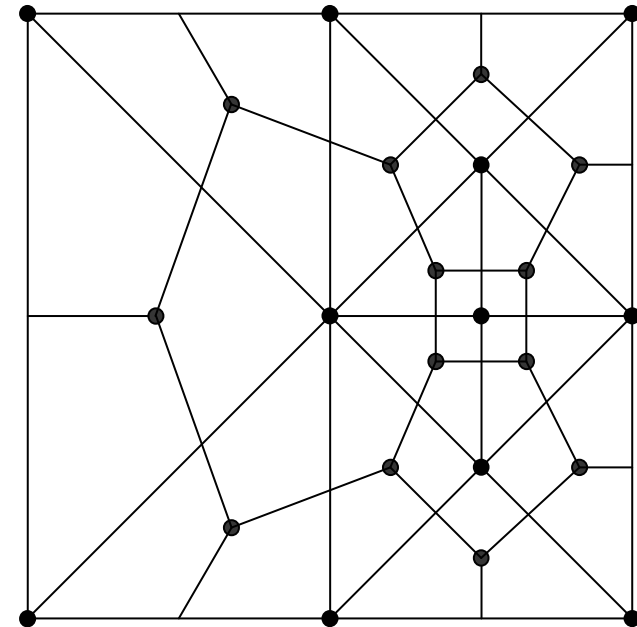
Modification to Cell Integrated Scheme

Dual Mesh

• Dual grid point
 $\cong$
 Primary grid cell

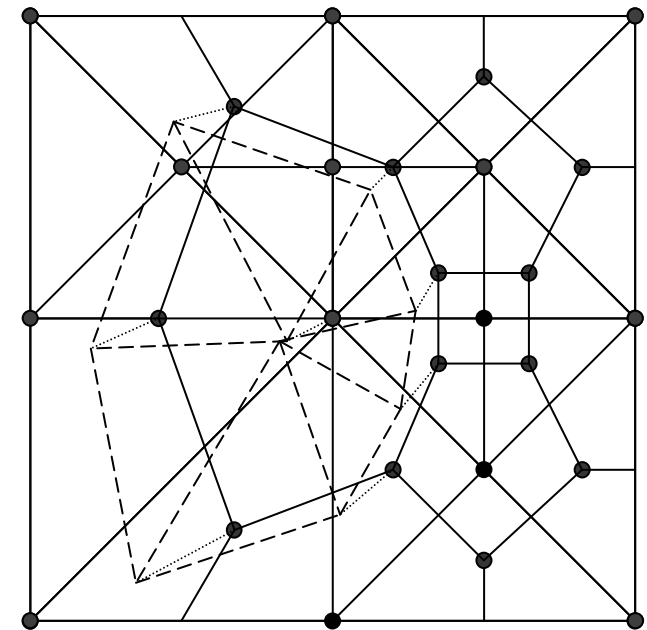


• Primary grid point
 $\cong$
 Dual grid cell



Modification to Cell Integrated Scheme

1. Look at **dual cell**, corresponding to **gridpoint**
2. **Advect** dual nodes
3. Create **upstream dual cell**
4. Create **local Triangulation**
5. Intersect with **old mesh**



Polygon/Triangle Intersection

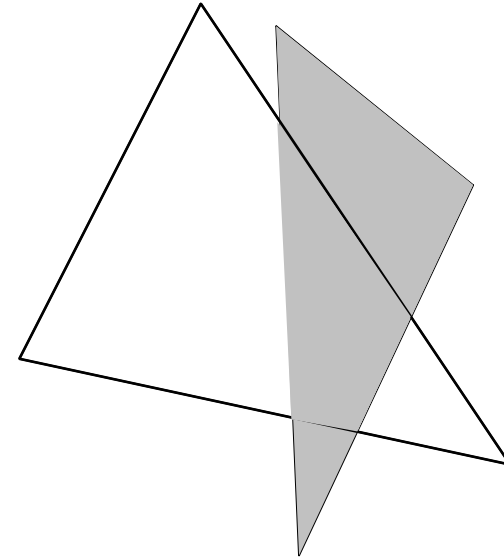
Algorithm:

INPUT: two oriented
AND convex polygons

For all edges:
 clip what's to the right
End

OUTPUT: Intersection polygon

$O(3(3 \cdot 2 + 3)) = O(27)$ Crossproducts



1st Order Cell Integrated Scheme

Let λ the dual cell corresponding to $\vec{x}$

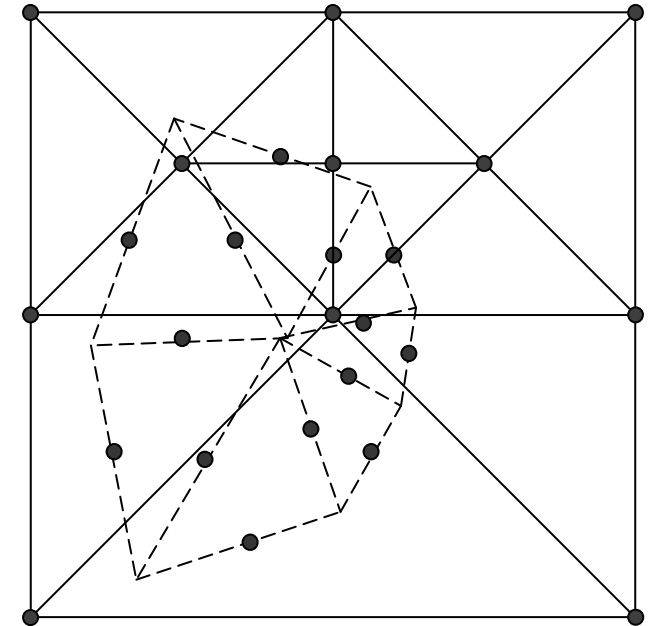
$$c(\vec{x}, t + \Delta t) = \sum_{\substack{\tau \in T \\ \tau \cap \lambda \neq \emptyset}} Vol(\tau \cap \lambda) \cdot \bar{c}(\tau)$$

For higher order:

$$c(\vec{x}, t + \Delta t) = \sum_{\substack{\tau \in T \\ \tau \cap \lambda \neq \emptyset}} Vol(\tau \cap \lambda) \cdot I(\tau \cap \lambda)$$

$$I(\tau \cap \lambda) = \int_{\tau \cap \lambda} c(\xi, t - \Delta t) d\xi$$

Quadrature Based Scheme



Create **upstream dual cell**

Interpolate at **quadrature points**

$$c(\bar{x}, t + \Delta t) = \sum_{\tau \in P} Vol(\tau) \sum_{\xi \in \tau} c(\xi, t - \Delta t)$$

Dual Mesh Correction

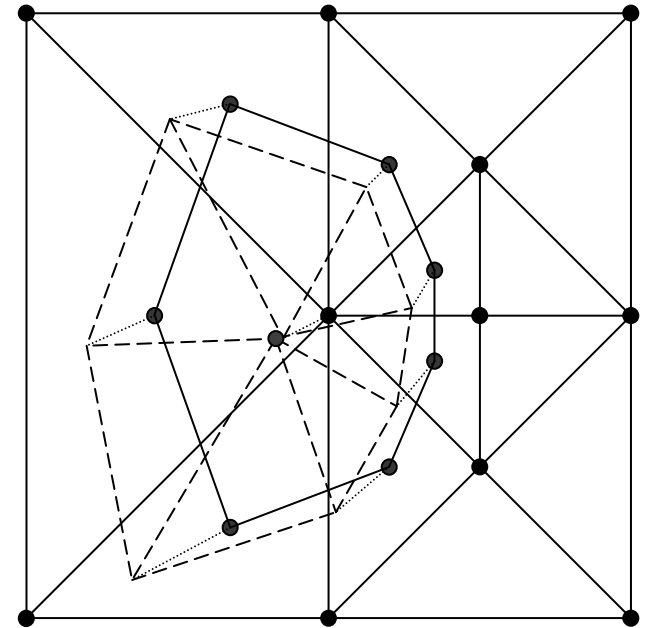
Create **dual cell**

Create **upstream dual cell**

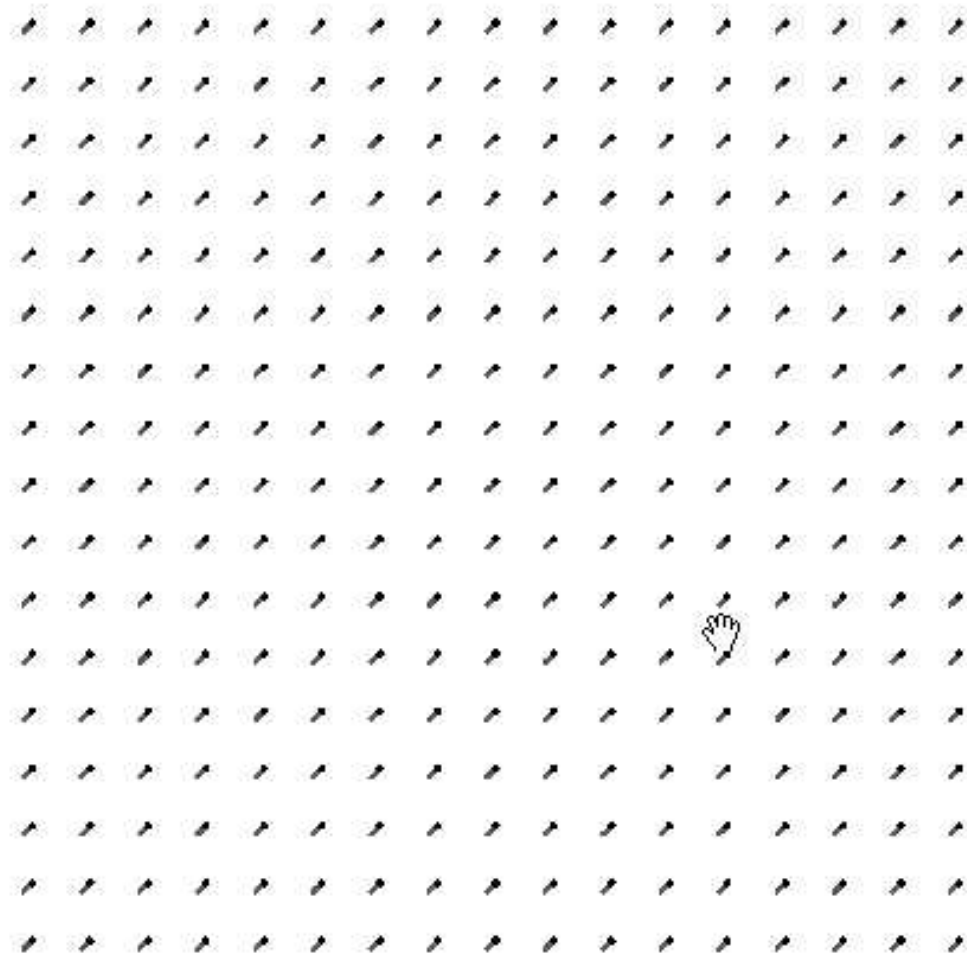
Interpolate **upstream value**

Correct value by:

$$c(\bar{x}, t + \Delta t) = c(\bar{x} - \bar{\alpha}, t - \Delta t) \cdot Vol(\diamond) / Vol(\diamond)$$



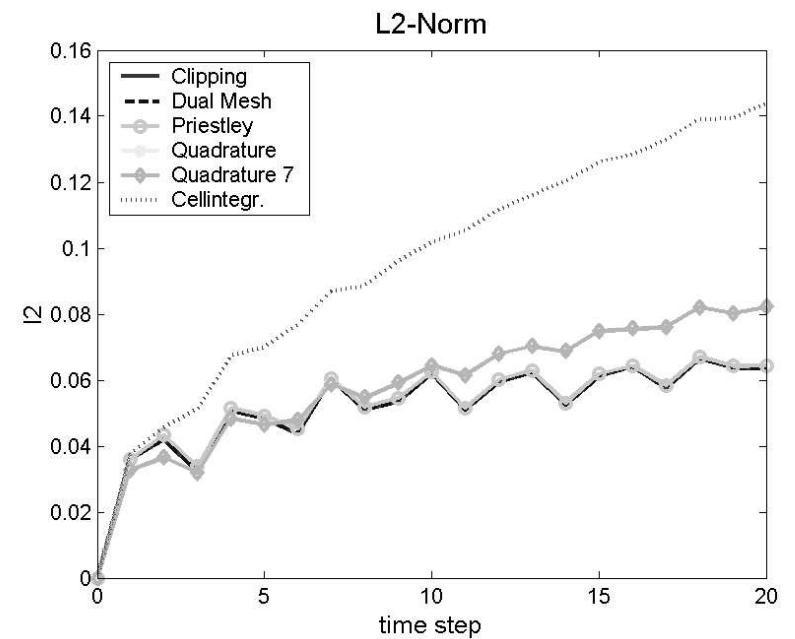
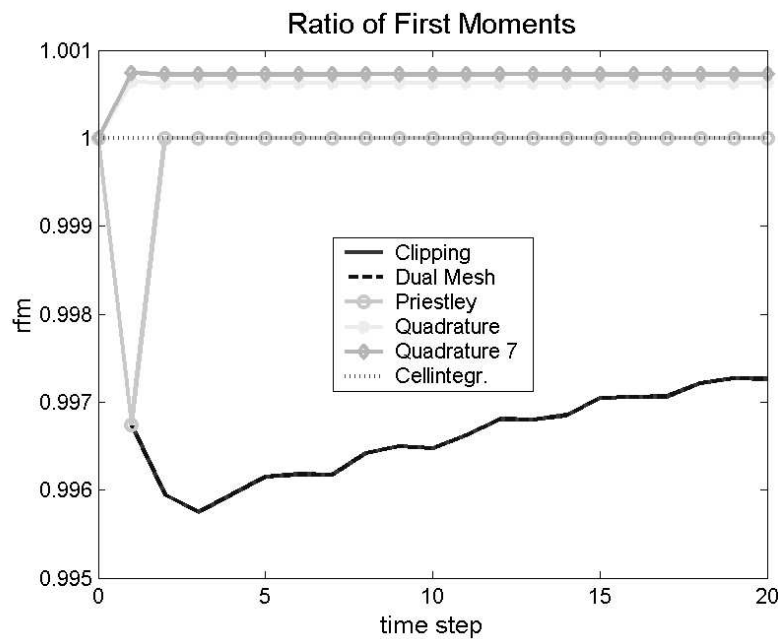
Testcases: Monotone Wind I



Time (h): 0.50
 (c) J. Behrens 2002
 Program: Flash90

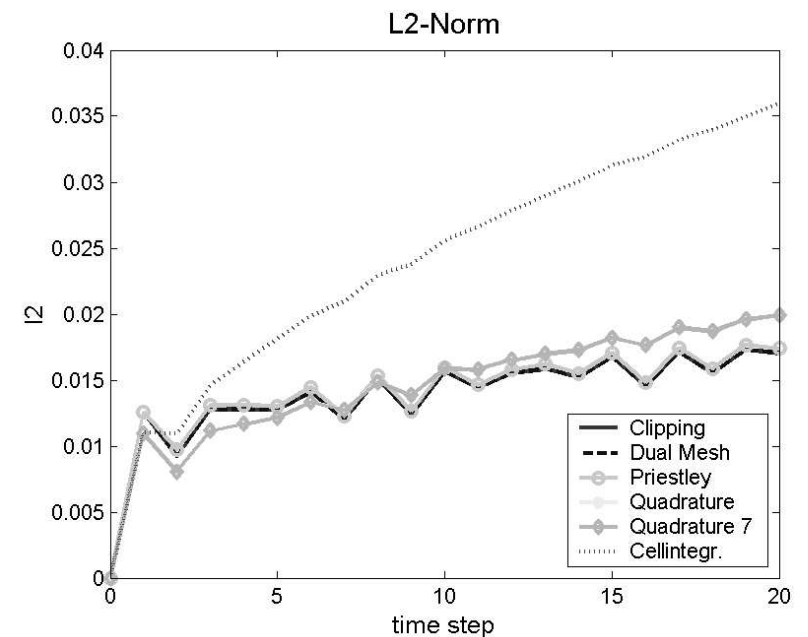
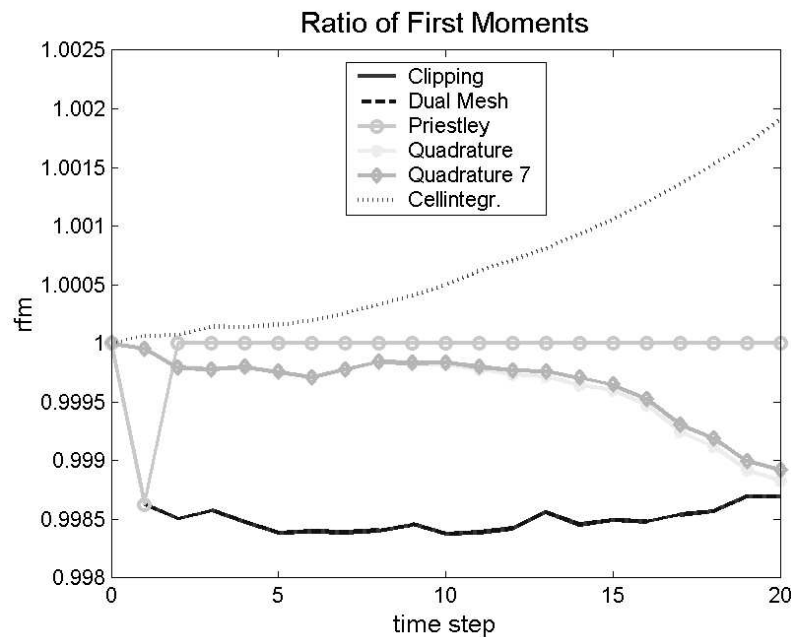
Testcases: Monotone Wind II

Non-Adaptive Case

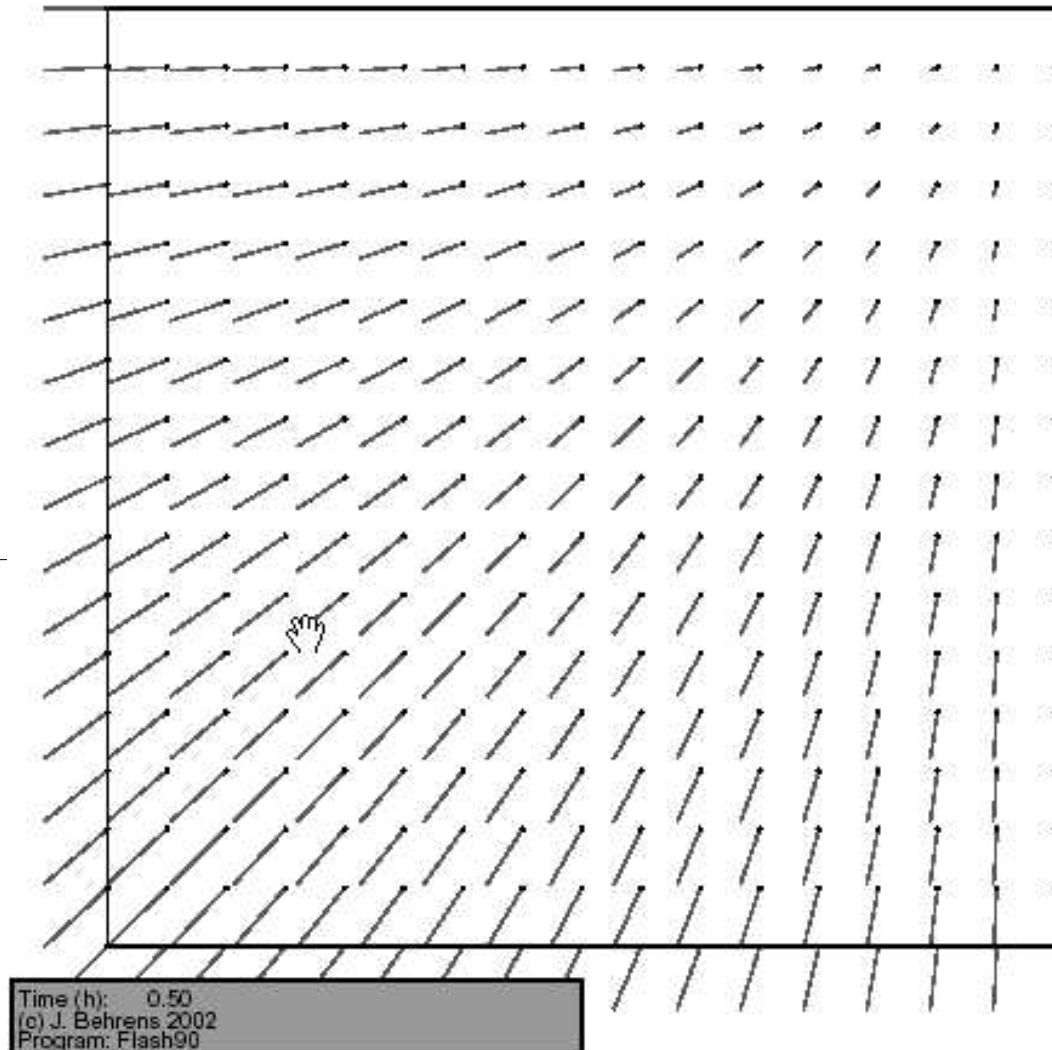


Testcases: Monotone Wind II

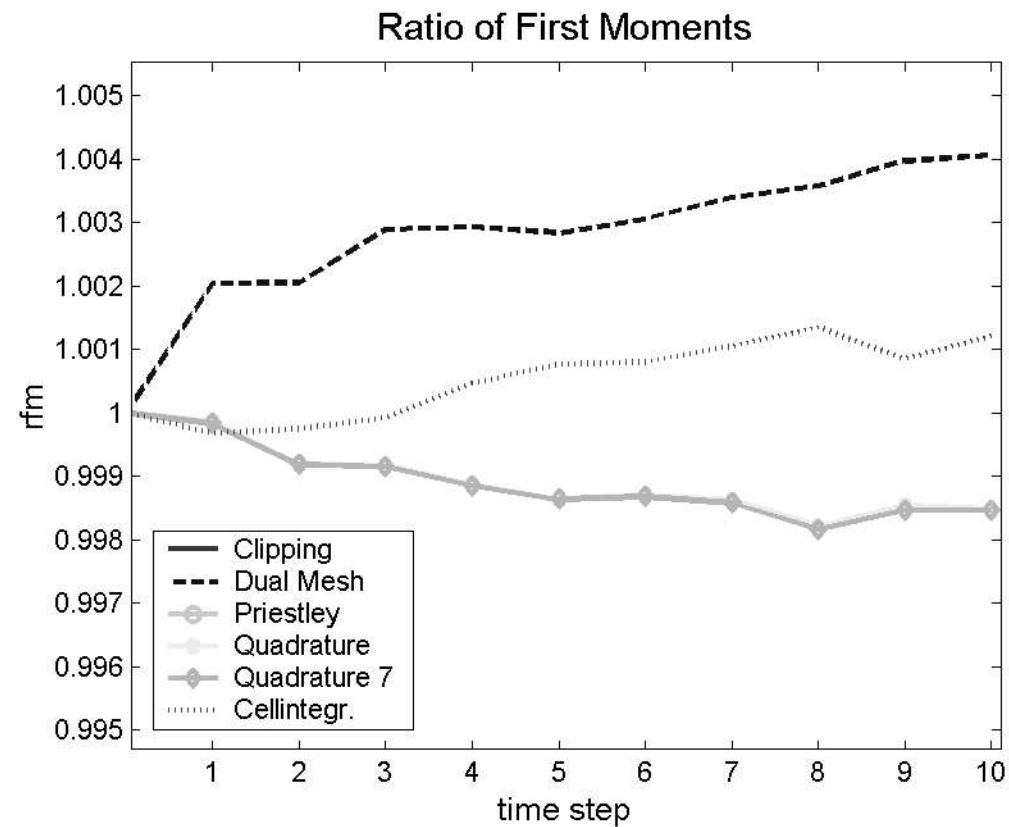
Adaptive Case



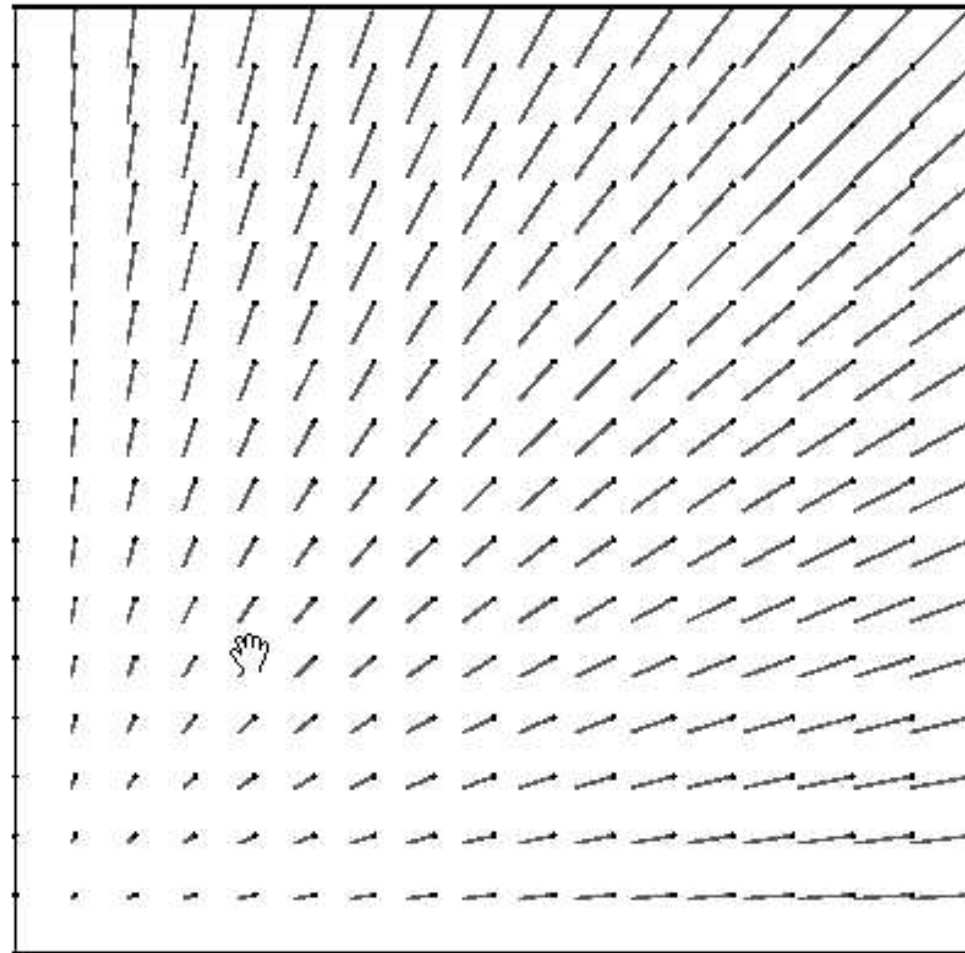
Testcases: Converging Wind I



Testcases: Converging Wind II

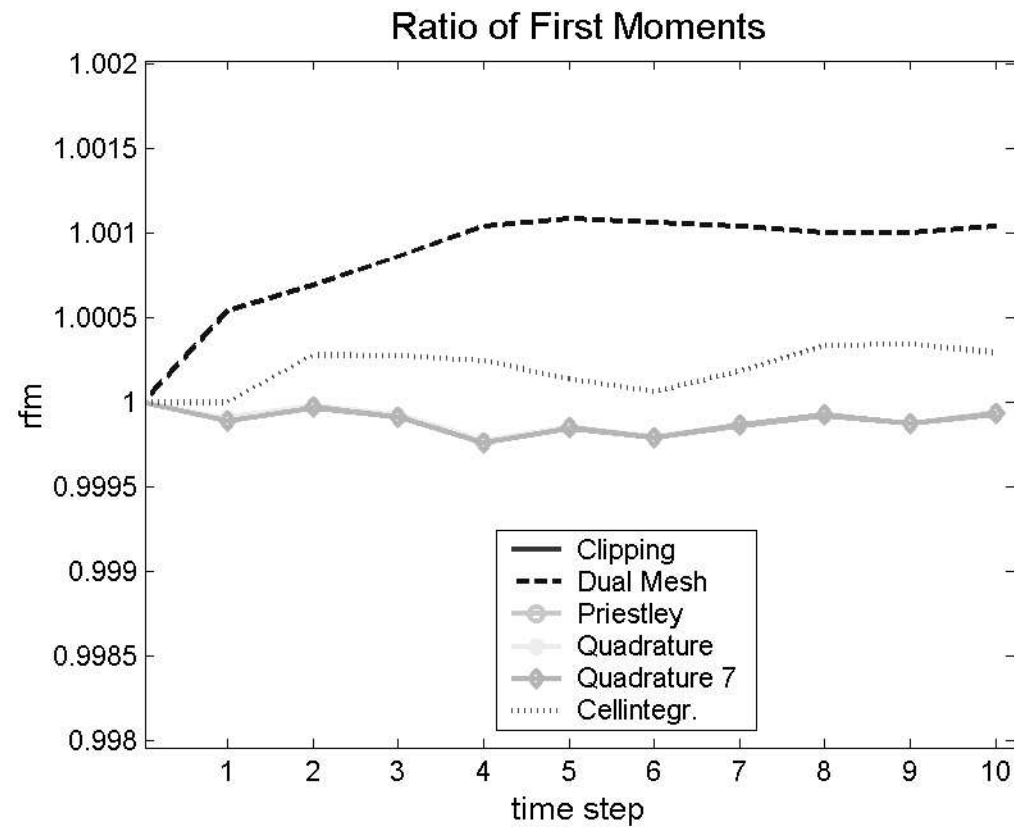


Testcases: Diverging Wind I

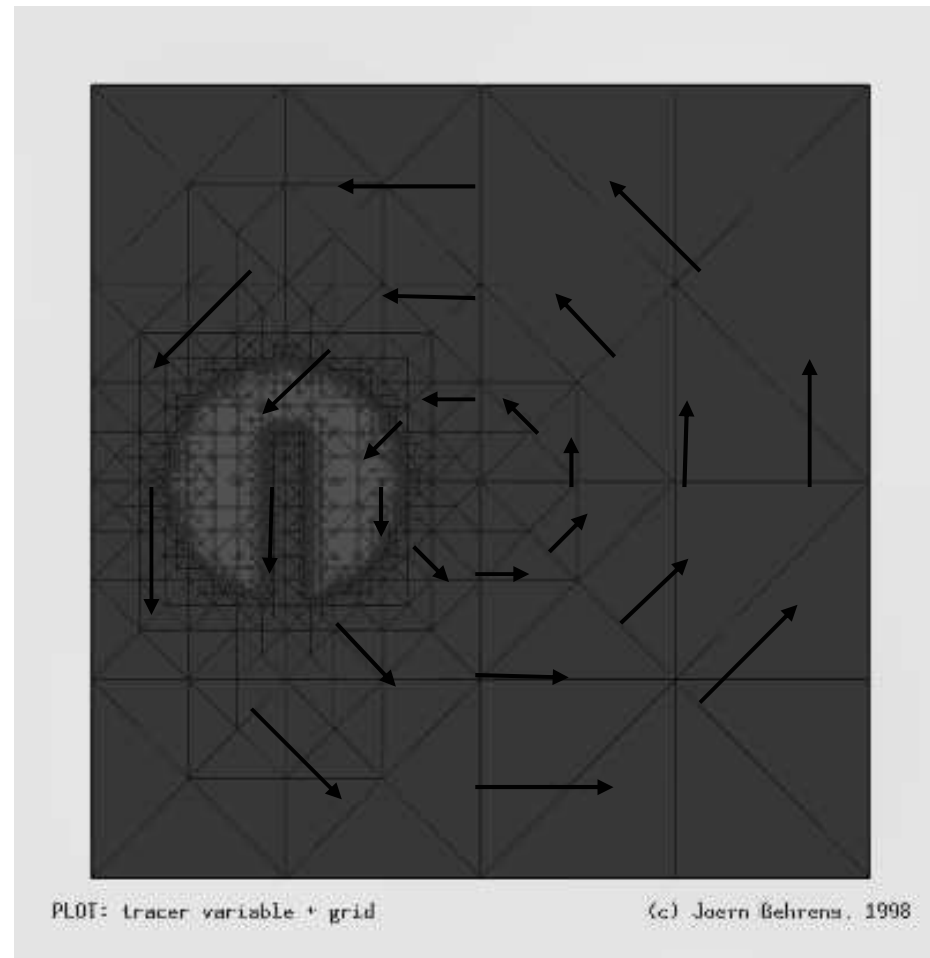


Time (h): 0.50
 (c) J. Behrens 2002
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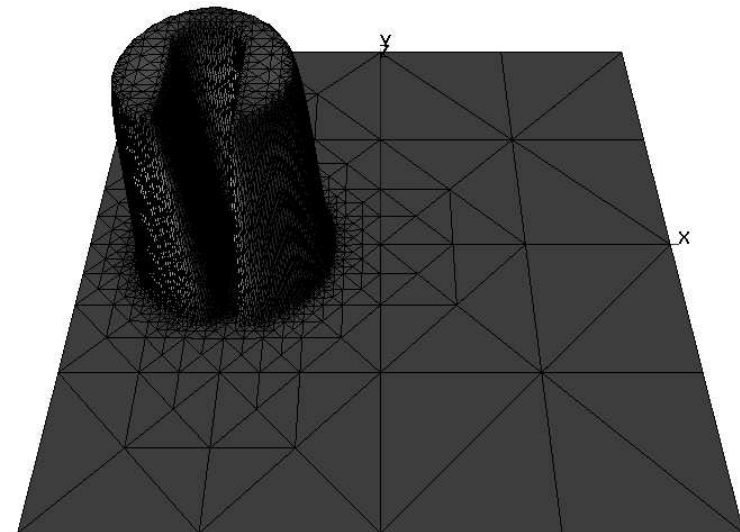
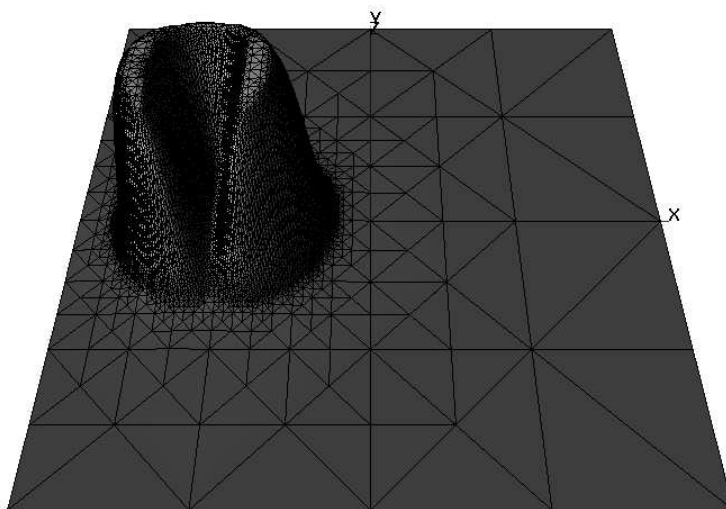
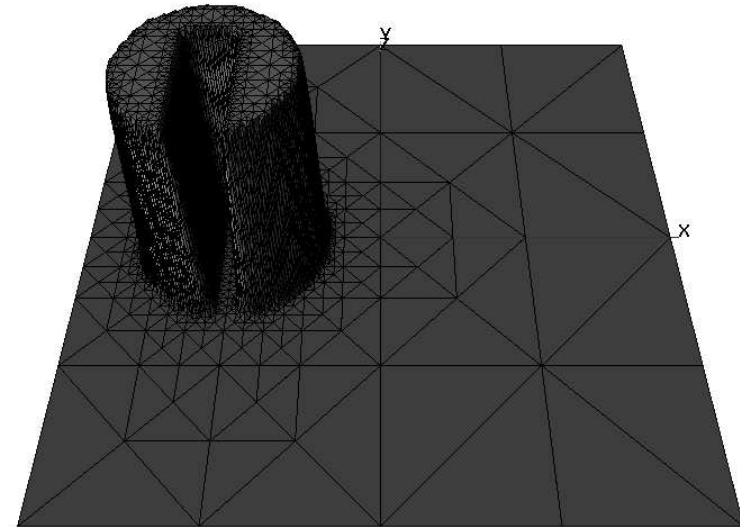
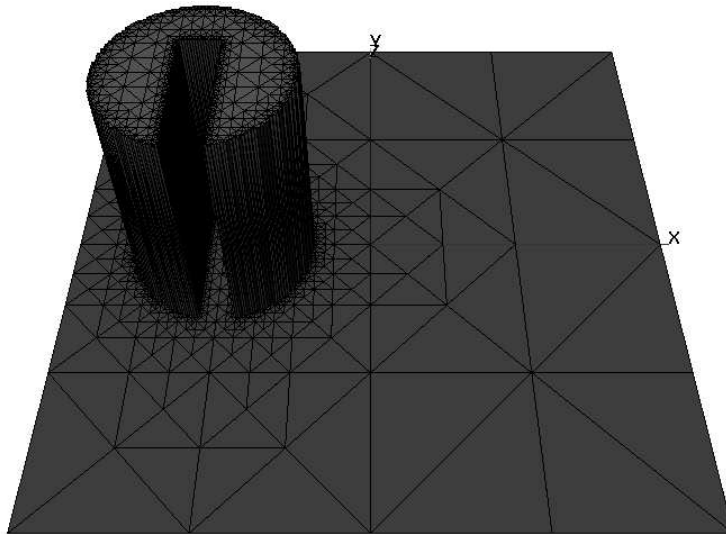
Testcases: Diverging Wind II



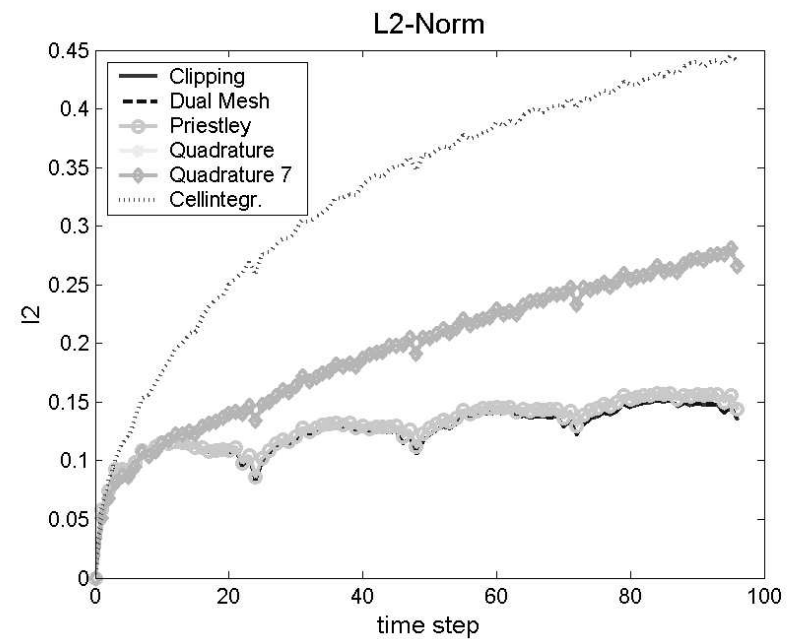
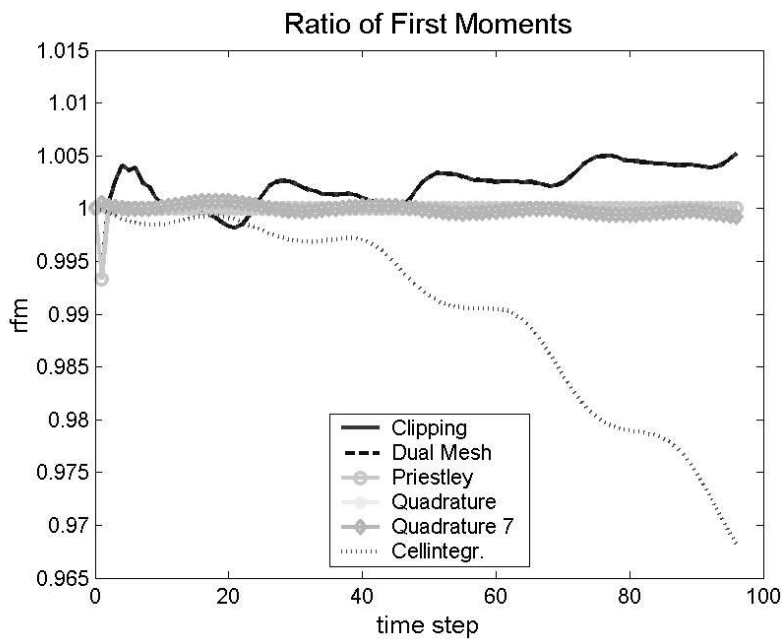
Slotted Cylinder



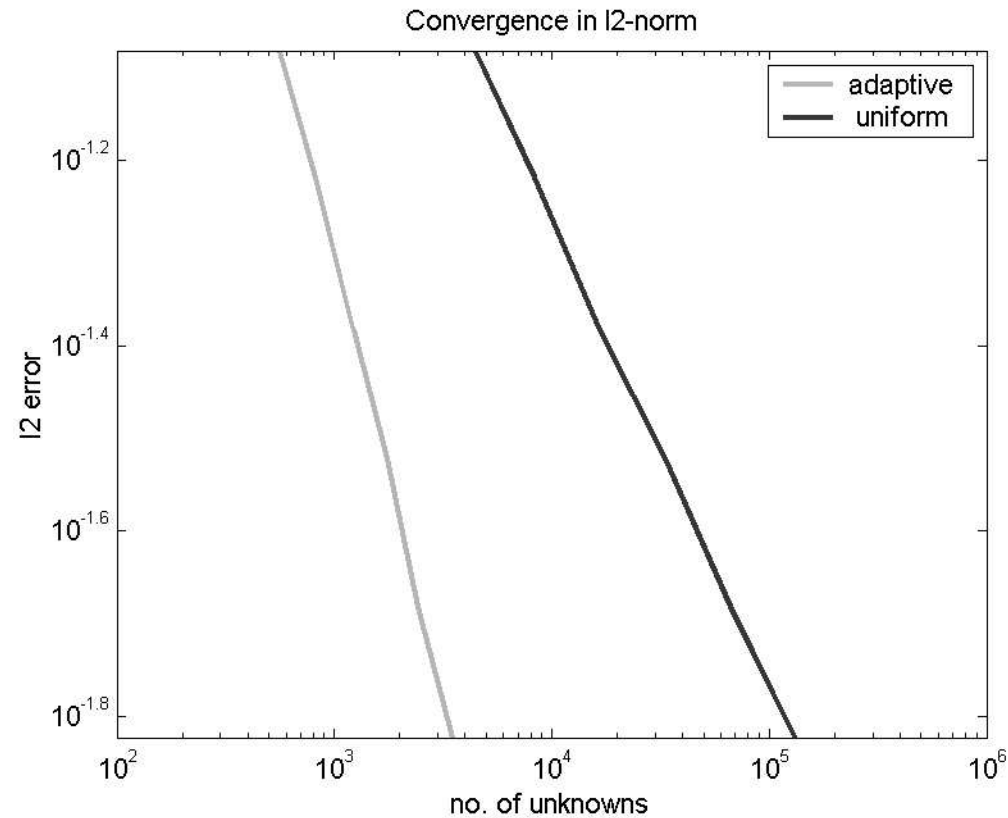
Testcases: Slotted Cylinder II



Testcases: Slotted Cylinder III



Testcases: Slotted Cylinder IV



Conclusions

- Several (almost) mass conserving Semi-Lagrangian Schemes presented
- Computational geometry helps solve the problem
- Adaptivity helps to improve order of convergence
- Not complete yet: boundary, sphere, etc.



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