

Moving from Nonlinear Evolution Equations
 Nonlinear Heat Flow: Steepest Descent Into a
 Convex Valley

may be written
 Conservative Hamiltonian
 friction dominated
 Dissipation; Gradient Flow

bounded!

eg. fluids

$$\rho u \left(\frac{\partial v_i}{\partial t} + v_i \frac{\partial u}{\partial x_i} \right) = - \partial_i (P(u))$$

$$\frac{\partial u}{\partial t} + \text{div} [u \vec{v}_i] = 0$$

$$\frac{\partial u}{\partial t} = \Delta (P(u))$$

$$= \Delta (u^m)$$

$$\frac{\partial u}{\partial t} + \text{div} [u^{m+1} \vec{v}_i] = 0$$

BOUNDARY CONDITIONS

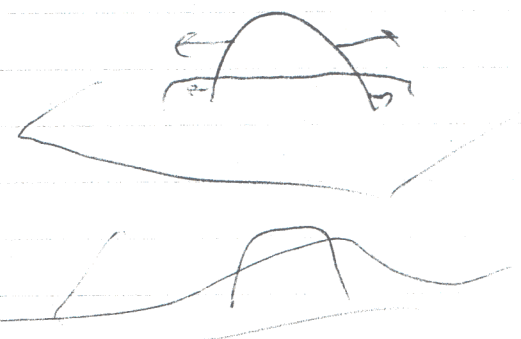
$m > 1$

$m = 1$

$m < 1$

$$\left[C_m + \frac{1-m}{2m} x^2 \right]_{t=0}^{t=\infty}$$

minimizes $\int u^m$ at fixed mass



$u(x,t) = \frac{1}{\sqrt{t}} e^{-\frac{x^2}{4t}} \rightarrow 0$ as $t \rightarrow \infty$
 more any more dissipation

WHY PRIGONIN DOMINATES?

mechanical analogy

WHY PRIGONIN?

Behavior of PDE:

① Conserves 0th and 1st moments; for COM

② 2nd Moments grow $R^2 := \int x^2 dx$

③ Rate of convergence of $\hat{u} =$

$$u(x) = \frac{1}{R^n} \hat{u}\left(\frac{x}{R}\right)$$

$$d_2(\hat{u}(t), \hat{v}(t)) \leq \frac{d_2(u_0, v_0)}{(1+kt)^{\frac{1}{2-n-m}}}$$

if $m \geq 1 - \frac{1}{n}$

Fluid Dynamics: Friction Dominated

Form

Compressible
Euler's equations

$$\left\{ \begin{aligned} \rho \frac{dv_i}{dt} + v_k \frac{\partial v_i}{\partial x^k} &= -\frac{1}{\rho} \frac{\partial p}{\partial x^i} - \beta v_i(x) u \\ \frac{\partial \rho}{\partial t} + \text{div} [\rho \vec{v}(x)] &= 0 \\ p(\rho, T) & \end{aligned} \right. \quad \text{eq. of state}$$

Poiseuille Law:
neglect friction
term

$$v_i = -\frac{1}{\beta \mu} \frac{\partial p}{\partial x^i}$$

$$\begin{aligned} \frac{\partial u}{\partial t} &= \frac{1}{\beta} \text{div} [\mu \nabla p] = \frac{1}{\beta} \text{div} [\mu \nabla p] \\ &= \frac{1}{\beta} \text{div} [\mu \nabla p] \\ \mu &= m \beta u^{m-1} \\ &= A(p) \end{aligned}$$

increasing decreasing

Internal Energy
Associated

$$\int A(p) dx \quad \text{where} \quad A(p) = \int_0^p p(s) ds$$

$$A' = \frac{d}{dp} \int_0^p p(s) ds = p(p)$$

$$A'' = \frac{d}{dp} p(p) = \frac{dp}{dp} = 1$$

$$A(p) = \frac{p^{m+1}}{m+1}$$

D.w.f. for a bar

$$p = \frac{M}{V} \quad dW = - \frac{M}{\rho^2} dp$$

$$u = \int_0^{\infty} p\left(\frac{M}{V}\right) dV$$

$$= M \int_0^{\infty} p\left(\frac{M}{V}\right) \frac{dV}{V^2}$$

$$u(p) = \int_0^{\infty} p\left(\frac{M}{V}\right) \frac{dV}{V^2}$$

What is good about Wasserstein Distance? (Guessing expected warm up problem (m=1): 3 facts

- ① translation: $d_2(u, v) = |z|$ if $d_1(x) = v(x+z)$
- ② dilation: $d_2(u, v)^2 = |R_1 - R_2|^2 + R_1 R_2 d_2(\hat{u}, \hat{u})^2$
- ③ contraction: $d_2(u, v, u, v) \leq d_2(u, v)$

TAKAF

Proof of 2: $|x_1 - x_2|^2 = (|x_1| - |x_2|)^2 + |x_1| |x_2| \left| \frac{x_1}{|x_1|} - \frac{x_2}{|x_2|} \right|^2$

$$(x, y) \xrightarrow{F} (R, x, R, y)$$

$$\gamma \in \Gamma(\hat{u}, \hat{u}) \xrightarrow{F\#} \gamma \in \Gamma(u, u)$$

$$\begin{aligned} \int |x - y|^2 d\gamma &= \int |R, x - R, y|^2 d\gamma \\ &= R_1^2 \int |x|^2 d\hat{u}_1 + R_2^2 \int |y|^2 d\hat{u}_2 + 2R_1 R_2 \int |x - y|^2 d\gamma \\ &= (R_1^2 + R_2^2) \int |x - y|^2 d\gamma \end{aligned}$$

$$\begin{aligned} \frac{d}{dt}(R(t)^2) &= \int x^2 \text{sum} = 2n \int u^m \\ &= 2n \int u^m \geq 2n R(t)^{m-1} \min_{i=0, \dots, m} \int u_i^m \end{aligned}$$

$$R(t)^2 = R(0)^2 + 2nt \geq 2nt$$

$$\begin{aligned} d_2(u, v, u, v) &\geq d_2(u, v, u, v) \\ &\geq \sqrt{R_1(t) R_2(t)} d_2(\hat{u}, \hat{u}) \\ &\geq \sqrt{2nt} d_2(\hat{u}, \hat{u}) \end{aligned}$$

Guess correct exponent. $m \neq 1$.

$$\frac{d}{dt} (R(t)^2) = 2R(t)\dot{R}(t) \geq 2n R^{n(1-m)}(t) \min_{1 \leq i \leq n} \int \dot{u}_i^m$$

$$\frac{R^{2-n(1-m)}}{2-n(1-m)} \Big|_0^t \geq nk_0 t$$

$$R(t) \geq (R(0)^\alpha + nk_0 t)^{1/\alpha}$$

$$\alpha = 2 - n(1-m)$$

$$\Rightarrow d_2(\hat{u}_1(t), \hat{u}_2(t)) \leq \frac{1}{(nk_0 t)^{1/\alpha}} d_2(\hat{u}_1(0), \hat{u}_2(0))$$

if its still true that: $d_2(u_1(0), u_2(0)) \geq d_2(u_1(t), u_2(t))$

Friction Dominated Dynamics: Mechanical Analogy

Newton's
2nd Law

$$m\ddot{x} = -\nabla V(x) - \beta \dot{x}(t)$$

$\beta=0 \Rightarrow$ conservative $\frac{1}{2}m\dot{x}^2 + V(x(t)) = \text{const}$

rate of dissipation

$$\beta \dot{x} = -\nabla V(x)$$

= rate of dissipation

~~friction dominated~~
friction dominated

either
a.

$$\Rightarrow \beta \ddot{x} = -\nabla^2 V(x) \dot{x}(t)$$

$$m \ddot{x} = -\frac{m}{\beta^2} \nabla^2 V(x) \nabla V(x)$$

$$\nabla^2 V(x) \leq \frac{\beta^2}{m} \Rightarrow \text{self consistent.}$$

Global
Contraction:

LEMMA: If $V: \mathbb{R}^n \rightarrow \mathbb{R}$ is convex, then two solutions to $\dot{x} = -\nabla V(x(t))$ satisfy $\frac{d}{dt} |x_1(t) - x_2(t)| \leq 0$.

If $\nabla^2 V(x) \geq k$, then $|x_1(t) - x_2(t)| \leq e^{-kt} |x_1(0) - x_2(0)|$.

Proof: Let $f(t) = |x_1(t) - x_2(t)|^2 / 2$. Then

$$\begin{aligned} f'(t) &= \langle x_1(t) - x_2(t), \dot{x}_1(t) - \dot{x}_2(t) \rangle \\ &= -\langle x_1(t) - x_2(t), \nabla V(x_1(t)) - \nabla V(x_2(t)) \rangle \\ &= -\left[\frac{d}{ds} V((1-s)x_2(t) + sx_1(t)) \right]'_0 \leq 0 \text{ by convexity.} \\ &= -\frac{d^2 V((1-s)x_2 + sx_1)}{ds^2} (1-0) |x_1 - x_2|^2 \\ &= -\langle x_1(t) - x_2(t), \text{Hess}_x V(x_1(t) - x_2(t)) \rangle \\ &\leq -2k f(t) \end{aligned}$$

$$\Rightarrow f(t) \leq e^{-2kt} f(0)$$

$$\Rightarrow |x_1(t) - x_2(t)| \leq e^{-kt} |x_1(0) - x_2(0)|$$

□

where $d_L^2(u, v) = \inf_{\gamma \in \Gamma} \int |\dot{\gamma}|^2 dV(\gamma)$ ✓

$$\Gamma = \left\{ 0 \leq \gamma \in \mathbb{R}^n \times \mathbb{R}^n : |\dot{\gamma}(x)| = \int_{\mathbb{R}^n} f(x) V(x, y) dx dy = \int g(y) V(x, y) dy \right.$$

3

How to Prove: 3 central ingredients in the proof. (3)

① $\mathcal{M}_{2,0}(\mathbb{R}^n) = \left\{ 0 \leq u \in \mathbb{R}^n : 1 = \int u \quad \left\{ \text{see ex} \right\} \right\}$

has an infinite dimensional Riemannian manifold, which d_L gives the geodesic distance.

② Dynamics represent steepest descent of the ("Mountain") functional on the manifold pt. 2.7.

$$E(u) = \frac{1}{n-1} \int (u^n - u) dx$$

McLain ~~(1)~~ $E|u|$ is geodesically convex on the manifold M
 $M \geq 1 - \frac{1}{n}$
 $\Rightarrow$ gradient flow should be non-singular

Motivation: finite dimensional convex gradient flow
 ① Global existence proof.

PHYSICAL ENIGMA

~~WHERE~~ DOES NEUMANN-ROBEU ENIGMA COME FROM?

Minimization But Slow III: Steepest Descent into a Convex Valley Oct 30, 2002

RECAP

$$\begin{cases} \frac{\partial u}{\partial t} = \Delta(u^m) \\ u(0, x) = u_0(x) \end{cases}$$

Defining an evolution in $M(\mathbb{R}^n) = \{0 \leq u \text{ on } \mathbb{R}^n : \int u < \infty, \int x^2 u < \infty\}$
in fact in $M_{1,0}(\mathbb{R}^n) = \{u \in M(\mathbb{R}^n) : 1 = \int u, \int x^2 u = 0\}$

① $M_{1,0}(\mathbb{R}^n)$ is a "Riemannian" manifold where geodesic dist is

$$d_2(u, v)^2 := \inf_{\gamma \in \Gamma(u, v)} \int |x - \gamma|^2 d\gamma(x, y)$$

cut $\left\{ \begin{aligned} \Gamma(u, v) &= \{0 \leq \gamma \text{ on } \mathbb{R}^n, \mathbb{R}^n : \int_{\mathbb{R}^n} \gamma dV(x, y) = \int_{\mathbb{R}^n} u dx = \int_{\mathbb{R}^n} v dy \\ \int \gamma(x) d\gamma(x, y) &= \int \gamma(y) d\gamma(x, y) = \int \gamma(x, y) d\gamma(x, y) \end{aligned} \right.$

② evolution is steepest descent of the "action"

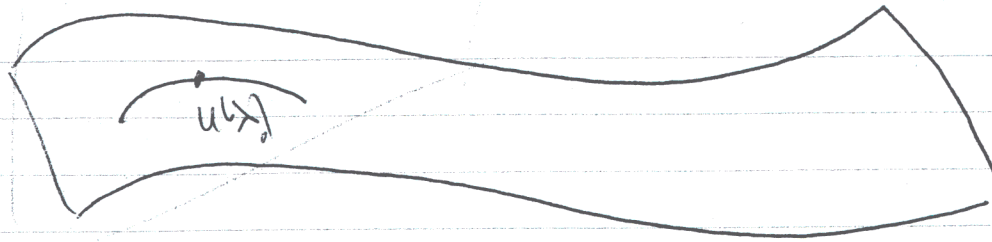
$$E(u) = \frac{1}{m+1} \int u^{m+1}(x) - u(x) \quad \text{on } (M, d_2)$$

③ $E(u)$ is geodesically convex i.e.

$$\begin{cases} d(u_0, u_1) = s d(u_0, u_1) \\ d(u_1, u_2) = (1-s) d(u_0, u_1) \end{cases} \Rightarrow E(u_s) \leq (1-s) E(u_0) + s E(u_1)$$

①②③ $\Rightarrow d(u_1(t), u_2(t)) \leq d(u_0(t), u_1(t)) \quad R: |A| \leq \int x^2 u$

cut $\left\{ \begin{aligned} \hat{u}_i &= \frac{1}{R_i} \gamma \left(\frac{\cdot}{R_i} \right) \Rightarrow d(\hat{u}_1, \hat{u}_2(t)) \leq \frac{C_0}{t} O\left(\frac{1}{t^{2-n(m-1)}}\right) \\ &\leq O\left(t^{-\frac{1}{2-n(m-1)}}\right) \end{aligned} \right.$



$$M = \mathcal{M}_{1,0}(\mathbb{R}^n)$$

Object	Representation Abstract	Formulas $u \in H^1$	Diagram
curve	$\lambda \in [0,1] \rightarrow u(\lambda)$	$\int_{\gamma} u(\lambda, x) d\lambda$	normal coord.
tangent vector	$\frac{du}{d\lambda} \propto \dot{u}(\lambda)$	$\frac{\partial u}{\partial \lambda}(\lambda_0, x)$	$\psi(x)$
length	$\ \dot{u}(\lambda)\ ^2_{T_{u(\lambda)}} = \int_{\mathbb{R}^n} u(\lambda, x) \partial_x \psi(x) ^2 dx$	$\int_{\mathbb{R}^n} u(\lambda, x) \partial_x \psi(x) ^2 dx$	$\frac{\partial u}{\partial \lambda} \Big _{\lambda_0} + \text{div}(u \partial \psi) = \Delta_\psi u$

def. CLAIM 1: $d_2(u_0, u_1) = \inf_{\lambda \mapsto u(\lambda) \in \gamma, u(0)=u_0, u(1)=u_1} \int_0^1 \|\dot{u}(\lambda)\|^2 d\lambda$

CLAIM 2. Gradient flow of $E(u)$ wrt $u \in H^2_{+M}$ is $\frac{\partial u}{\partial t} = \text{div} \left[u \frac{\delta E}{\delta u} \right]$

e.g. $\frac{\delta E}{\delta p} = \sum_{m=1}^n u^{m-1}$
 $\frac{\delta E}{\delta q} = \sum_{m=1}^n u^{m-2} \partial u$

$\text{div} \left[u \frac{\delta E}{\delta p} \right] = \text{div} \left[\sum_{m=1}^n u^m \partial u \right] = \Delta u$

DEFIN: (Push-forward) Given measurable spaces $(X, \mathcal{X})$ and $(\tilde{X}, \tilde{\mathcal{X}})$, and a mble map $T: X \rightarrow \tilde{X}$, any probability measure μ on X induces a measure $\tilde{\mu}$ on $\tilde{X}$ defined

$$\tilde{\mu}(\tilde{B}) = \mu(T^{-1}(\tilde{B})) \quad \forall \tilde{B} \in \tilde{\mathcal{X}}$$

LEMMA: (COV) $\int_{\tilde{X}} f(\tilde{x}) d\tilde{\mu}(\tilde{x}) = \int_X f(T(x)) d\mu(x)$

THM: (Greenwood-McLaurin) Given $u_0, u_1 \in \mathcal{D}(\mathbb{R}^n)$ $\exists! T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ s.t. $T_{\#} \mu_0 = \mu_1$, $T = \nabla \phi$ for some $\phi: \mathbb{R}^n \rightarrow \mathbb{R}$ concave

e.g. not T continuous w.r.t. x

$$\int_{\mathbb{R}^n} u_0 = \int_{\mathbb{R}^n} u_1$$

$$u_0(x) = T^{-1}(x) u_1(T(x))$$

CLAIM: $d_2^2(u_0, u_1) = \int_{\mathbb{R}^n} u_0(x) |T(x) - x|^2$

Proof: $\leq$ take $\gamma_T = \text{id} \times T \# u_0$

check $\gamma_T \in \Gamma(u_0, u_1)$ using COV. and compute $\int |x-y|^2 d\gamma$

$$\int_{\mathbb{R}^n \times \mathbb{R}^n} f(x, y) d\gamma_T(x, y) = \int_{\mathbb{R}^n} f(x, T(x)) u_0(x)$$

$$= \begin{cases} \int |y-x|^2 u_0 & \text{if } f(x, y) = |y-x|^2 \\ \int f u_0 & \text{if } f(x, y) = f(x) \\ \int f(T(x)) u_0(x) & \text{if } f(x, y) = f(y) \end{cases}$$

$$= \int f(T(x)) u_0(x) = \int f \cdot T_{\#} u_0 = \int f u_1 \text{ if } f(x, y) = f(y)$$

Logarithm
Rechnung

Sei $\phi: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\phi(x, y) := \sup_{x, y \in \mathbb{R}^n} x \cdot y - \phi(x)$$

if ϕ convex and $\phi^*(\phi^*(x)) = x$ then $\phi^*(\phi(x)) = x - \phi(x) - \phi(x)$

if ϕ is convex then $x, y \in \mathbb{R}^n$ $\phi(x, y) \leq \phi(x) + \phi(y)$

if $x \in \mathbb{R}^n$ then $\sup_{y \in \mathbb{R}^n} (x \cdot y - \phi(y)) \leq \phi(x) + \sup_{y \in \mathbb{R}^n} \phi(y)$

Reversing $x, y \in \mathbb{R}^n$ $\int x \cdot y d\mu = \int x \cdot \phi(x) d\mu$
 $= \int \phi(x) + \phi^*(\phi(x)) d\mu$
 $= \int \phi(x) + \phi^*(x) d\mu$

if $\int |\phi(x)|^2 d\mu = \int |\phi(x)|^2 - 2\phi(x) + \phi(x)^2 d\mu$
 $= R_1^2 + R_2^2 - 2\phi(x) \int \phi(x) d\mu$

Inspektion
"Korollar"

$u_s := E_s \in \mathbb{R}^n$ $E_s(x, y) = \phi(x) + \phi(y)$
 $= E_s \in \mathbb{R}^n$ $[x, y, s, t] \in \mathbb{R}^n$

Claim u_s is a minimal geodesic segment.

Of: $d_L(u_0, u_s) \leq s \sqrt{\int |\tau - \phi|^2 d\mu}$
 $d_L(u_s, u_1) \leq (1-s) \sqrt{\int |\tau - \phi|^2 d\mu}$

$d_L(u_0, s) + d_L(s, u_1) \leq d_L(u_0, u_1)$

triangle inequality $\Rightarrow$ u_s is a geodesic segment.

Proof 2: Along any curve $u(x)$ with tangent $x'(s)$ in our case

$$\frac{d}{ds} E(u(x)) = \int_{\mathbb{R}^n} \frac{\delta E}{\delta u} \frac{\partial u}{\partial x} = \int_{\mathbb{R}^n} \frac{m}{m-1} u^{m-1} \frac{\partial u}{\partial x}$$

$$= - \int_{\mathbb{R}^n} \frac{\delta E}{\delta u} \operatorname{div} [u \phi]$$

$$= \int_{\mathbb{R}^n} u \operatorname{div} \left(\frac{\delta E}{\delta u} \phi \right) ds$$

$$= \int_{\mathbb{R}^n} \frac{\delta E}{\delta u} = -c \phi$$

$$\geq - \left\| \frac{\delta E}{\delta u} \right\|_{W^{1,2}_u} \|\phi\|_{W^{1,2}_u}$$

$$= -c^2 \|x\|_{W^{1,2}_u}^2$$

Also for a gradient flow $\frac{d}{dt} E(u(t)) = \langle \operatorname{grad}_u E, u(t) \rangle = - \|\operatorname{grad}_u E\|^2$

$0 \leq \phi \Rightarrow \operatorname{grad}_u E$ then $c=1$ and $\phi = \frac{\delta}{\delta}$

After Brezis-McCom, below proof:

Morgan,
Lecture
eq.

$$\int_{\mathbb{R}^n} \phi(x) f(x) = \int_{\mathbb{R}^n} \phi(x) f(\phi(x)) dx \quad \forall \phi \in \mathcal{U}(\mathbb{R}^n)$$

$$= \int_{\mathbb{R}^n} \phi(x) f(\phi(x)) \det D\phi(x) dx$$

$$\text{also } u(\phi(x)) = \det((1-s)I + sD\phi(x)) \quad u_s((1-s)x + s\phi(x))$$

$$\frac{d}{ds} \Big|_{s=0} = 0 = \operatorname{tr}(D^2 \phi(x) - I) u_0(x) + \nabla u_0 \cdot (\phi(x) - x) + 2u_0$$

$$= \Delta u_0(x) - \frac{\partial u_0}{\partial x} \cdot \frac{\partial \phi}{\partial x}(x) - \frac{\partial u_0}{\partial x} \cdot \frac{\partial \phi}{\partial x}(x) + 2u_0$$

Nonlinear Heat Flow IV: Steepest Descent into a Convex Valley Nov 6, 2002

RECAP

$$\frac{\partial u}{\partial t} = \Delta(u^m)$$

$$u(0, x) = u_0(x)$$

$$\in \mathcal{M}_{1,0}(\mathbb{R}^n) = \{u \in \mathcal{M}(\mathbb{R}^n) : 1 = \int u \quad 0 = \int xu \quad \int x^2 u < \infty\}$$

① a Riemannian manifold w/ geodesic distance is given by

$$d_2(u, v)^2 = \int_{\mathbb{R}^n} |x - \nabla \phi(x)|^2 u(x) \quad \text{where } \phi \text{ is convex}$$

$$\text{and } \nabla \phi : \mathbb{R}^n \rightarrow \mathbb{R}^n \quad \dots \quad \nabla \phi \# u = v \quad (\text{here } u \ll v)$$

or, finally measurable a.e.!

$$u(x) = \det D^2 \phi(x) \quad \forall (\nabla \phi(x)) \quad \text{More generally}$$

② evolution is steepest descent of the entropy w.r.t d_2

$$E(u) = \frac{1}{m} \int u^m(x) dx \quad \text{More generally } \frac{\partial u}{\partial t} = \nabla \cdot \left[u \nabla \frac{\delta E}{\delta u} \right]$$

③ $m \geq 1 - \frac{1}{n} \Rightarrow$ geodesically convex, $E(u_s) \leq (1-s) E(u_0) + s E(u_1)$

whenever u_0, u_1 w.r.t ϕ convex

$$u_s := [(1-s)x + s \nabla \phi] \# u$$

$$\Rightarrow \int g(x) d u_s(x) = \int g((1-s)x + s \nabla \phi(x)) u_0(x) dx$$

$$= \int g((1-s)x + s \nabla \phi(x)) \underbrace{u_0((1-s)x + s \nabla \phi(x))}_{\text{in } \{ \text{arbitrary} \}} dx \quad (1-s) E(u_0) + s E(u_1)$$

I
Local v.
Global
metric

Recall: ① was based on tangent metric $\neq$ to any curve $u(\gamma, b)$ having length

$$\| \psi \|_{W^{1,2}} = \left(\int_{\mathbb{R}^n} |\psi(b)|^2 u_{\gamma}^2 dx \right)^{1/2}$$

Here $\frac{\partial u}{\partial x} + \text{div} [u \psi]$

Connection to $d_2(u, v)$? Consider our geodesic curves

a.e.

$$u_s((1-s)x + sD\phi(\gamma)) \det(1-sI + sD^2\phi(\gamma)) = u_{\gamma}^2$$

$\frac{d}{ds} \Big|_{s=0}$

$$\rightarrow \frac{\partial u}{\partial s} \Big|_{s=0} + \nabla u_0 \cdot (D\phi(\gamma) - x) + u_0 \gamma \cdot (D^2\phi - I) = 0$$

$$\frac{\partial u}{\partial s} (0, x) + \text{div} [u_0(0, x) \left(\frac{D\phi - I}{2} \right)] = 0$$

"tangent metric"

$$\psi(b) = \phi(b) - \frac{1}{2}|b|^2$$

$$d_2^2(u_0, u_1) = \int_{\mathbb{R}^n} |\nabla \psi(b)|^2 du_0(b) \leq \| \psi \|_{W^{1,2}}^2$$

II. Displacement Convexity:

$$\begin{aligned} E(u_s) &= \frac{1}{n} \int_{\mathbb{R}^n} u_s(x)^n dx = \frac{1}{n} \int_{\mathbb{R}^n} u_s((1-s)x + sD\phi(\gamma))^n \det(1-sI + sD^2\phi(\gamma)) dx \\ &= \frac{1}{n} \int_{\mathbb{R}^n} \left(\frac{u_0(b)}{\det(1-sI + sD^2\phi(\gamma))} \right)^n \det(1-sI + sD^2\phi(\gamma)) dx \\ &= \frac{1}{n} \int_{\mathbb{R}^n} u_0(b) \det^{1-n}((1-s)I + sD^2\phi(\gamma)) dx \end{aligned}$$

multilinear
④ symmetric form

Recall: ① $\det^n((1-s)I + sB)$ is concave in s provided $B^+ = B \geq 0$

② $\perp$ Sign ∇ determines concavity

③ Hesse-Green $D^2\phi(\gamma) = D^2\psi(b) \geq 0$

Proof: OAIM: $\left(\frac{1}{n} \sum_{i=1}^n (1-s)z_i + sb_i \right)^n \geq (1-s) + s \left(\frac{1}{n} \sum_{i=1}^n b_i \right)^n$

Proof: $(1-s) \left(\frac{1}{n} \sum_{i=1}^n (1-s)z_i + sb_i \right)^n + s \left(\frac{1}{n} \sum_{i=1}^n b_i \right)^n$
 $\leq (1-s) \frac{1}{n} \sum_{i=1}^n \frac{1}{(1-s)z_i + sb_i} + s \frac{1}{n} \sum_{i=1}^n \frac{b_i}{(1-s)z_i + sb_i}$
 $= 1$

IV Rescaled
Müller

$u(t, x) = \frac{1}{(1+2t)^{n/2}} V\left(\log(1+2t)^{1/2}, \frac{x}{(1+2t)^{1/2}}\right)$
 $u_0(x) = u(0, x)$

$\frac{\partial \eta}{\partial t} = \operatorname{div} u \Leftrightarrow \frac{\partial v}{\partial \tau} = \Delta V^m + \operatorname{div} [Y v(x, \tau)]$

gradient flow of $F(u) = E(u) + \frac{1}{2} \int_{\mathbb{R}^n} |y|^2 v^2$
 with d_1

$\frac{\partial F}{\partial v} = \frac{\partial E}{\partial v} + \frac{1}{2} |y|^2$
 $\frac{\partial F}{\partial y} = \frac{\partial E}{\partial y} + y$

Convergence of F ? $F(u_s) \leq F(u_0) + \epsilon E(u_0) + \frac{1}{2} \int_{\mathbb{R}^n} |(1-s)y + s \phi(x)|^2 v_0^2$

$F(v_s) = E(v_s) + \frac{1}{2} \int_{\mathbb{R}^n} |y + s \phi(x)|^2 v_0^2 dx$

$\frac{d^2 F}{ds^2}(v_s) = \frac{d^2 E}{ds^2} + \frac{1}{2} \int_{\mathbb{R}^n} |\phi(x)|^4 v_0^2 dx \geq 0 \Rightarrow d_2^2(v_s, v_0)$

unf...

$\Rightarrow d_2(v_s, \tilde{v}_0) \leq e^{-\epsilon} d_2(v_0, \tilde{v}_0) = d_2(v_0, \tilde{v}_0)$
 $\Rightarrow d_2(u_t, \tilde{u}_t) \leq \text{degenerate}$

HWI: 3 Basic Consequences of Uniform Convexity.

LEMMA: If $f: \mathbb{R} \rightarrow [0, \infty)$ satisfies $f(0) = 0$ $f''(x) \geq \lambda$
 then

Parabola
 Area below

$$\textcircled{1} \quad \frac{1}{2} |w|^2 \leq f(w) \leq \frac{1}{2\lambda} |f'(w)|^2 \quad \text{log Sobolev}$$

and $\textcircled{3} \quad f(w) \leq \frac{1}{2\lambda} |f'(w)|^2 - \frac{1}{2} w^2 \quad \text{HWI}$

Proof: $\textcircled{1}$ Let $g(w) = f(w) - \frac{\lambda}{2} w^2$. Then $g(w)$ is convex and $g'(0) = 0$, whence $g(w) \geq g(0) = 0$.

e.g. $g'(w) = f'(w) - \lambda w$
 $g''(w) = f''(w) - \lambda \geq 0$

$\textcircled{2}$ Let $g(w) = f'(w)^2 - 2\lambda f(w)$. Then $g(w)$ has only one critical point and it is a local (hence global) minimum:
 $g(w) \geq g(0) = 0$.

e.g. $g'(w) = 2f'(w)f''(w) - 2\lambda f'(w)$
 $= 2f'(w)(f''(w) - \lambda) = 0 \Leftrightarrow w=0$.
 $g''(0) = 2f''(0)(f''(0) - \lambda) + 2f''(0) \times (f''(0))$
 $\geq 2\lambda(f''(0) - \lambda) + 0$

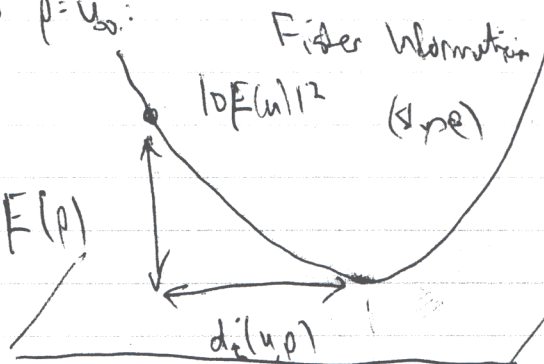
$\textcircled{3}$ Let $g_{\pm}(w) = \pm w f'(w) - \frac{1}{2} w^2 - f(w)$. Then $g_{+}(w)$ has a unique critical point: namely a local (hence global) minimum at $g_{+}(w) \geq g_{+}(0) = 0$.
 ~~$g_{+}(w) = w f'(w) - \frac{1}{2} w^2 - f(w)$~~

e.g. $g'_{+}(w) = f'(w) + w f''(w) - \lambda w - f'(w) = 0 \Leftrightarrow w=0$
 $g''_{+}(w) = f''(w) + w f'''(w) - \lambda \Big|_{w=0} = f''(0) - \lambda > 0$.

If only concerned about distance to $p = u_\infty$:
 3 senses of convergence

Relative Entropy

$$F(u) - F(p)$$



Relationships

Hess $E \geq \lambda$

$$\frac{\lambda}{2} d_2^2(u, u_\infty) \leq F(u) - F(u_\infty) \leq \frac{1}{2\lambda} |dF(u)|^2$$

Talagrand's
transportation $\neq$

$\downarrow 2\lambda$
relative
log Sobolev $\neq$

Wasserstein distance
 $p = u_\infty$

eg. $F(u) = \int u \log u + \frac{1}{2} x^2 u$

$$u_\infty = p = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$

$\lambda = 1$

$$|dF(u)|^2 = \int u \left| \frac{\delta F}{\delta p} \right|^2 = \int u \left| \log u + 1 + \frac{1}{2} x^2 \right|^2$$

let $u = f u_\infty$

$$= \int p f \left| \log f + \log p + \frac{1}{2} x^2 \right|^2$$

$$= \int p f \log^2 f$$

$$F(f p) - F(p) = \int p f (\log f + \log p + \frac{1}{2} x^2) - p \log p - \frac{1}{2} p x^2$$

$$= \int p f \log f - \frac{f}{2} - \log p + \frac{1}{2} x^2 p - \frac{p}{2} - p \log p - \frac{1}{2} p x^2$$

$$= \int p f \log f$$

$\therefore$

$$\leq \frac{1}{2} \int p \frac{|dF|^2}{f}$$

let $f = g^2$

$$\int_{\mathbb{R}^n} e^{-x^2/2} g^2 \log g^2 \leq 2 \int_{\mathbb{R}^n} e^{-x^2/2} \frac{g^2}{g^2} \log^2 g^2 = 2 \int_{\mathbb{R}^n} e^{-x^2/2} \log^2 g^2$$

Bakery-Energy

LEMMA: $D^2V \geq k \Rightarrow |\nabla V(x(t))| \leq e^{-kt} |\nabla V(x(0))|$

Convergence
to minimum
only.

COROLLARY: $V(x(t)) - V_{\min} \leq \frac{|\nabla V(x(0))|^2}{2k} e^{-2kt}$

NO GRADIENT
COMPARISON
RESULT.

Proof of Lemma: Let $f(t) = V(x(t))$ and $g(t) = |\nabla V(x(t))|^2$

$$\begin{aligned} f'(t) &= \langle \nabla V(x(t)), \dot{x}(t) \rangle \\ &= -|\nabla V(x(t))|^2 = -g(t) \end{aligned}$$

$$\begin{aligned} f''(t) &= -2 \langle \nabla V(x(t)), D^2V(x(t)) \dot{x}(t) \rangle \\ &= +2 \langle \nabla V, D^2V \nabla V \rangle \\ &\geq 2k |\nabla V(x(t))|^2 = 2kg(t) \end{aligned}$$

$$\therefore -g'(t) \geq 2kg(t)$$

$$\Rightarrow g(t) \leq g(0) e^{-2kt}.$$

□

Proof 1 of Corollary: Apply log Sobolev $V(x) - V_{\min} \leq \frac{|\nabla V(x)|^2}{2k}$
 $\leq \frac{g(0)}{2k} e^{-2kt}$

Proof 2 of Corollary: $g(t) \rightarrow 0$ as $t \rightarrow \infty$ implies $x(t) \rightarrow x_{\text{argmin}}$

$$-f'(t) = g(t) \leq g(0) e^{-2kt}$$

$$\Rightarrow -f(t) \Big|_T^\infty \leq g(0) \frac{e^{-2kt}}{2k} \Big|_T^\infty$$

$$f(0) - f(\infty) \leq \frac{g(0)}{2k} e^{-2kt}$$

$$V(x(0)) - V(x_{\text{argmin}})$$

□