

BODIL BRANNER

A HOLOMORPHIC TALE

GLIMPSES of HOLOMORPHIC DYNAMICS
in the light of JOHN MILNOR's
INFLUENCE on its DEVELOPMENT.

BOOK:

DYNAMICS in ONE COMPLEX VARIABLE

Vieweg 1999, 2000.

Princeton Univ. Press 2006.

PAPERS:

expositories

preprint $\rightarrow$ publication

Renowned for:

- clarity
- elegance
- completeness
- beautiful computer pictures
- appropriate acknowledgement of others work

THREE THEMES:

- MODULI SPACES of cubic polynomials and quadratic rational maps ^{suggesting} non-local connectivity
- The combinatorial method for quadratic polynomials described by ORBIT PORTRAITS
- MATINGS and LATTÈS MAPS

CUBIC POLYNOMIALS

$$P_{a,b}(z) = z^3 - 3a^2z + b$$

critical points : $\pm a$

PARAMETER SPACE : $\mathbb{C}^2$

$$P_{a_1,b_1} \sim_{\text{hol. conj.}} P_{a,b} \Leftrightarrow (a_1, b_1) = (\pm a, \pm b)$$

MODULI SPACE : $\mathcal{M}(3) = \mathbb{C}^2$

$$(A, B) \quad A = a^2, \quad B = b^2$$

one representative for each holomorphic conjugacy class.

REAL CUBIC POLYNOMIALS

$$(A, B) \in \mathbb{R}^2$$

If $B < 0$, a representative with real coefficients is

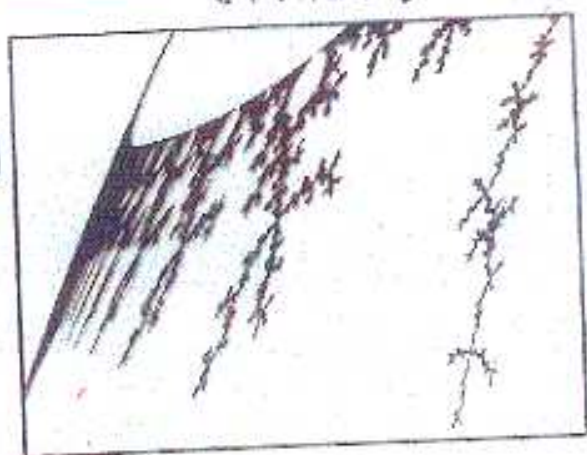
$$-x^3 - 3Ax + \sqrt{|B|}$$

Hence, two complex conjugate crit. points with complex conjugate orbits.

on iterated cubic maps.

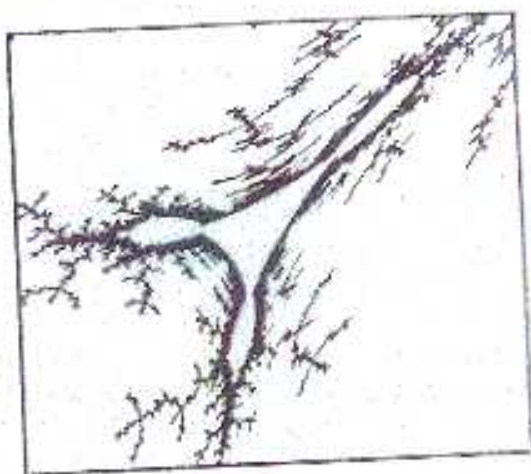
Experiment. Math. 1
(1992), 5-24.

of the
connectedness locus $\mathcal{C}(3)$
 $\mathbb{R}^2$, in the quadrant
 $A > 0, B < 0$



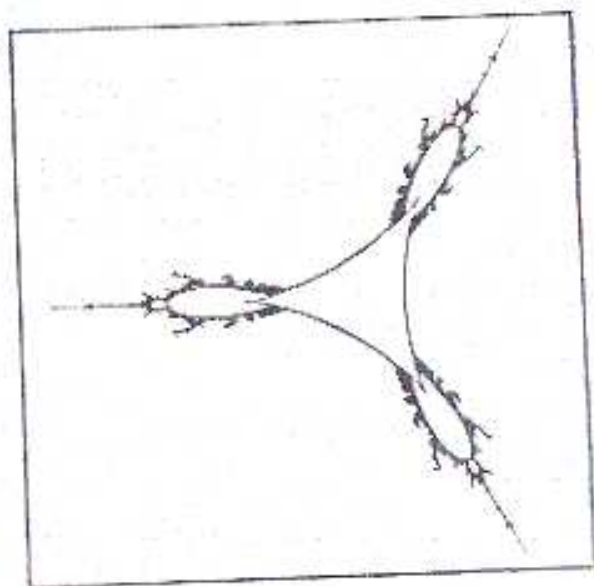
$\mathcal{C}(3) \subset \mathbb{R}^2$
connected and
 n -locally connected

Enlargement



totipole model for
transitive case:

connectedness locus,
a tricorn, of the
-quadratic family
 $z \mapsto (z^2 + c)^2 + \bar{c}$



QUADRATIC RATIONAL MAPS Rat_2

Strong analogy between the theory of quadratic rational maps and cubic polynomials.

In both cases :

- * two free critical points
- three fixed points
(counted in $\hat{\mathbb{C}}$ for rat.
in $\mathbb{C}$ for pol.)

The MODULI SPACE is $\mathbb{C}^2$.

There are many different normal forms, for instance

$$f(z) = a\left(z + \frac{1}{z}\right) + b$$

- * ± 1 c.p., • ∞ fixed

Geometry and dynamics of quadratic rational maps.

Experiment. Math. 2 (1993),
37-83

ORBIT PORTRAITS of quadratic polynomials.

Periodic orbits, external rays and the Mandelbrot set

Géométrie complexe et systèmes dynamiques
(Orsay, 1995), Astérisque, No. 261 (2000), 277-333.

Fixed point portraits, with Lisa Goldberg

Ann. Sci. Ecole Norm. Sup. 26 (1993), 51-98.

The main purpose is to give an alternative and simplified proof of the landing of parameter rays $R_M(t)$, for t periodic under doubling.

The proof is based on orbit portraits.

MOTIVATION

Suppose $\mathcal{O} = \{\tilde{z}_1, \dots, \tilde{z}_p\}$ is a repelling or parabolic orbit of period p of some quadratic pol. $z \mapsto z^2 + c$. Let A_j denote the set of angles of the dynamic rays landing at $\tilde{z}_j$. Then $\{A_1, \dots, A_p\}$ is called the orbit portrait $\mathcal{P} = \mathcal{P}(\mathcal{O})$ of $\mathcal{O}$.

PROPERTIES and DEFINITION of an ORBIT PORTRAIT

- PROPERTIES**
- (1) A_j is a finite subset of $\mathbb{Q}/\mathbb{Z}$.
 - (2) $A_j \xrightarrow{2} A_{j+1}$ is a bijection under doubling, preserving cyclic order.
 - (3) $\exists r \geq 1$ s.t. any $t \in \bigcup_{j=1}^p A_j$ has period rp under doubling.
 - (4) $A_1, \dots, A_p$ are pairwise unlinked.

DEF Any $\{A_1, \dots, A_p\}$ satisfying the above is called an orbit portrait, $\mathcal{P}$.

$|A_j| = v$ is called valence. We have $r \leq v$.

REALIZATION

Any orbit portrait $\mathcal{P}$ is realized by some quadratic polynomial.

EXAMPLES of ORBIT PORTRAITS $\mathcal{P}$

SATELLITE TYPE:

unit: $\frac{1}{63}$

$$\left\{ \begin{array}{cc} \{22, 25, 37\}, & \{44, 50, 11\} \\ A_1 & A_2 \end{array} \right\}$$

$$p=2, v=3, r=3$$

$$I_{\mathcal{P}} = \left] \frac{22}{63}, \frac{25}{63} \right[$$

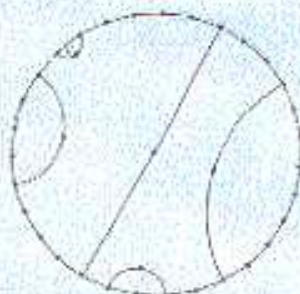
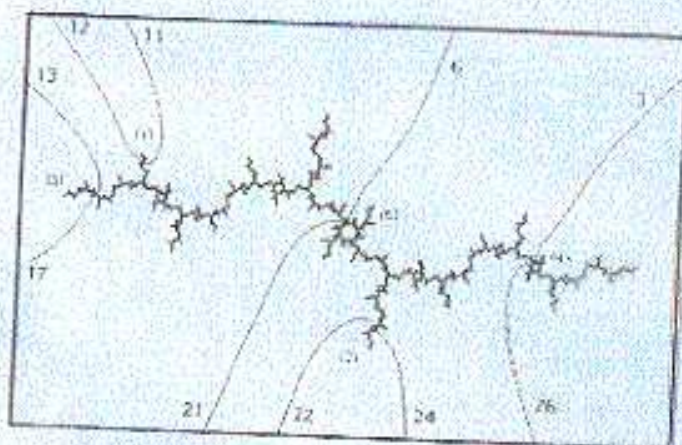
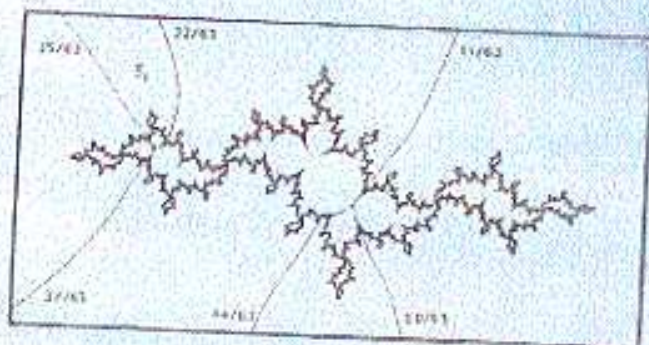
PRIMITIVE TYPE:

unit: $\frac{1}{31}$

$$\left\{ \begin{array}{ccc} \{11, 12\}, & \{22, 24\}, & \{13, 17\}, \\ A_1 & A_2 & A_3 \\ \{26, 3\}, & \{21, 6\} \\ A_4 & A_5 \end{array} \right\}$$

$$p=5, v=2, r=1$$

$$I_{\mathcal{P}} = \left] \frac{11}{31}, \frac{12}{31} \right[$$



25 22 11
37 44 50

TWO POSSIBILITIES

① PRIMITIVE CASE:

If $\alpha < \nu$, then $\alpha = 1$, $\nu = 2$,
so P contains two orbits of angles.

② SATELLITE CASE:

$\alpha = \nu$, so P contains one orbit of angles.

Each P has a unique smallest arc

$$I_P =]t_-(P), t_+(P)[$$

among the complementary arcs to $\bigcup_{j=1}^p A_j$,
the characteristic arc for P .

MAIN THEOREM in PARAMETER PLANE

Given $\mathcal{P}$.

The two parameter rays $R_M(t_{\pm}(\mathcal{P}))$ land at a common parabolic point $r_{\mathcal{P}} \in M$.

PREPARATION, for $c \notin M$.

- a rational dynamic ray $R_{K_c}(\theta)$ lands if it does not bounce at precritical points

⌊

- if $c \in R_M(t(c))$ then $R_{K_c}(\theta)$ bounces $\iff t(c) \in \{2\theta, 4\theta, 8\theta, \dots\}$

KEY LEMMA for $c \notin M$

f_c admits a periodic orbit with portrait $\mathcal{P}$

$\iff$

$$t(c) \in I_{\mathcal{P}} =]t_-(\mathcal{P}), t_+(\mathcal{P})[$$

SKETCH of proof of MAIN THEOREM.

① For any $t \in \bigcup_{j=1}^p A_j$ let $c_0 \in \overline{R_M(t)} \setminus R_M(t)$.

 Any neighborhood of c_0 contains c s.t. $R_{K_c}(t)$ bounces.

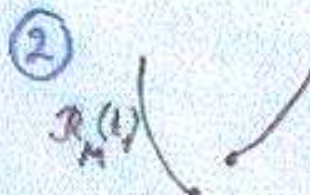
Therefore c_0 must have the following property:

$$\left[\begin{array}{l} \exists x_0 \in J_{c_0} \text{ s.t. } f_{c_0}^{\text{TP}}(x_0) = x_0 \text{ and} \\ (f_{c_0}^{\text{TP}})'(x_0) = +1. \end{array} \right.$$

If not, all $t \in \bigcup_{j=1}^p A_j$ would land at repelling periodic points with a stable portrait. — A contradiction.

There are only finitely many c -values with this property.

Hence, $R_M(t)$ lands at c_0 .

②  $R_M(t_-) \in \mathbb{C} \setminus \bigcup_{t \in \bigcup A_j} \overline{R_M(t)}$ is open.

If $R_M(t_-)$ and $R_M(t_+)$ would land at different points, this would violate the key lemma.

MATINGS.

Pasting together Julia sets:
a worked out example of matings

Experiment. Math. 13 (2004), 55-92.

Topological mating of two quadratic polynomials f_1 and f_2 with connected and locally connected Julia set.

Connect $R_{K_1}(t)$ with $R_{K_2}(-t)$.

Let $\sim_{\text{ray}}$ be the smallest equivalence relation so that $\overline{R_{K_1}(t)}$ and $\overline{R_{K_2}(-t)}$ lie in one equivalence class.

Thm of R.L. Moore

$S^2 / \sim_{\text{ray}}$ is homeomorphic to S^2

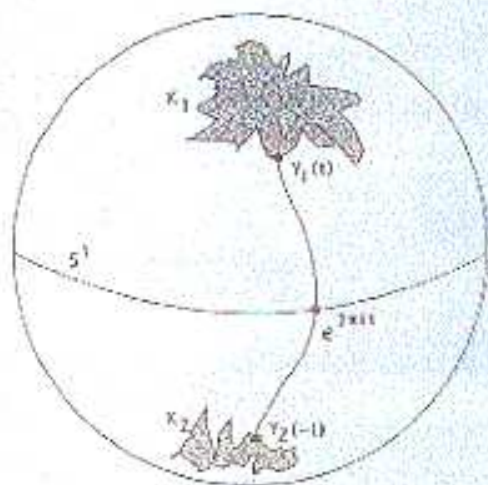
$\Updownarrow$ no equivalence class separates S^2 into two or more connected components.

If so, we define $f_1 \amalg f_2 : S^2 \rightarrow S^2$.

$F \in \text{Rat}_2$ is a geometric mating of f_1 and f_2

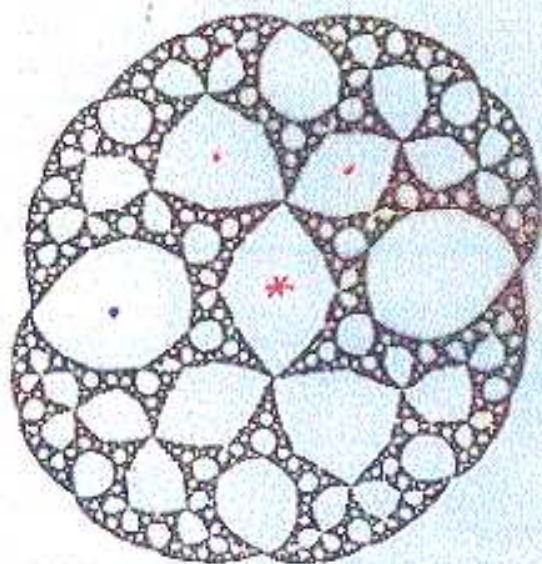
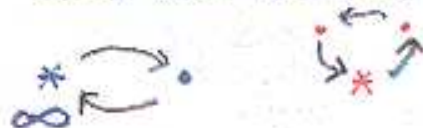
if $F \sim_{\text{top}} f_1 \amalg f_2$

Illustration of
topological mating
 of f_1 and f_2
 and ∞
 ray



From the cover of
 the Stony Brook
preprint series

mating of
 the basilica
 and the rabbit





THE WORKED OUT EXAMPLE

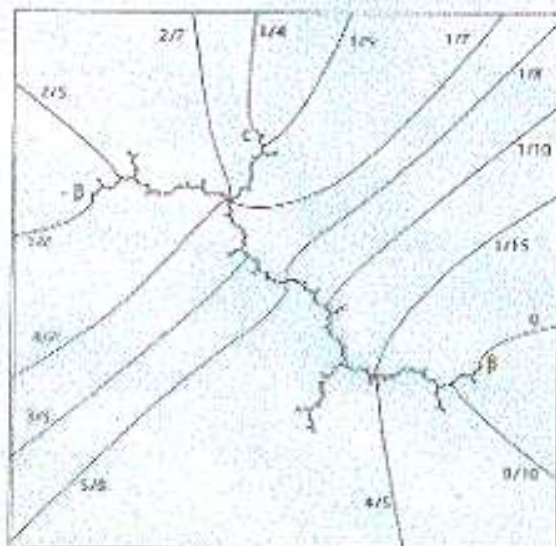
$$f = f_{c_{\frac{1}{4}}} : z \mapsto z^2 + c_{\frac{1}{4}}$$

where $c_{\frac{1}{4}} = \text{landing point of } P_M(\frac{1}{4})$.

critical orbit:

$$0 \mapsto c_{\frac{1}{4}} \mapsto -\beta \mapsto \beta \mapsto \infty$$

$J_{c_{\frac{1}{4}}}$ is a dendrite



critical orbits of $f \perp f$:

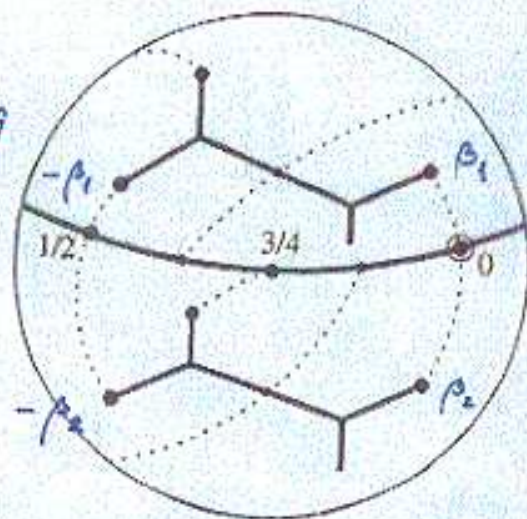
$$\begin{aligned} 0_1 &\mapsto c_1 \mapsto -\beta \mapsto \beta \mapsto \infty \\ 0_2 &\mapsto c_2 \mapsto -\beta \mapsto \beta \mapsto \infty \end{aligned}$$

The geometric mating exists:

$$F \sim_{\text{top conj}} f \perp f$$

$$F(z) = \frac{i}{2} \left(z + \frac{1}{z} \right)$$

$$\begin{aligned} +1 &\mapsto +i \\ -1 &\mapsto -i \end{aligned} \mapsto 0 \mapsto \infty$$



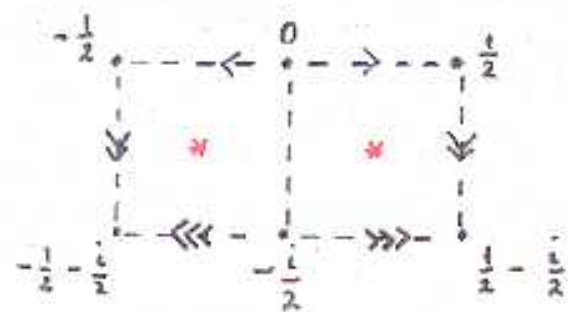
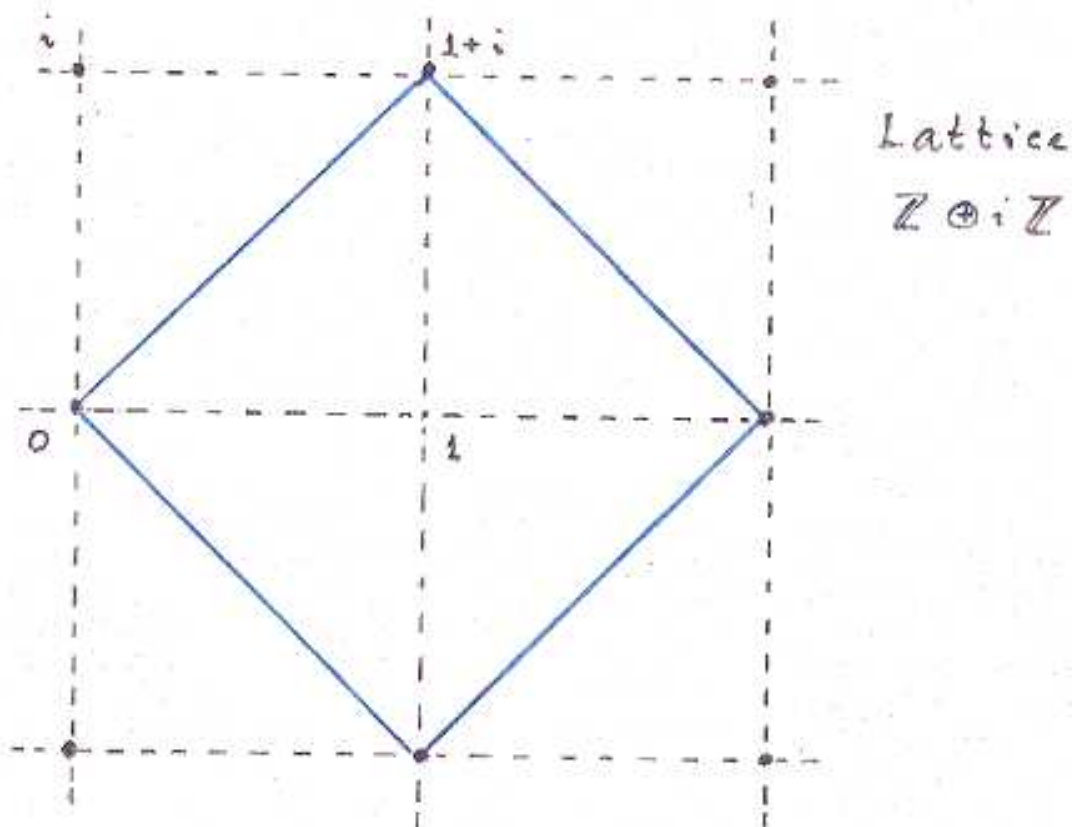
A LATTÈS MAP of deg 2

THE LATTÈS MAP.

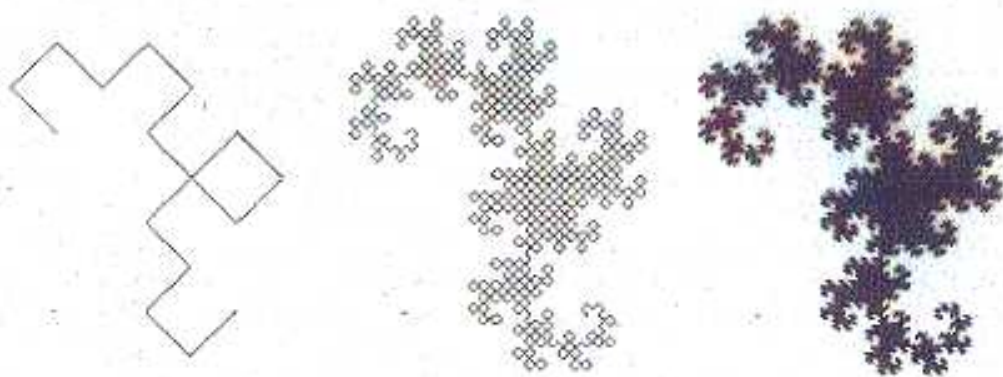
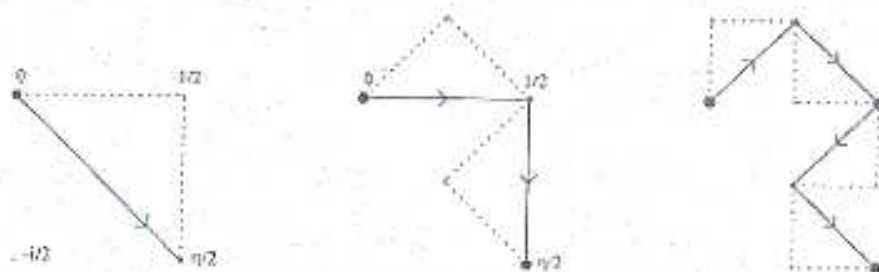
$$\mathbb{T} = \mathbb{C}/\mathbb{Z} \oplus i\mathbb{Z} \xrightarrow{L} \mathbb{C}/\mathbb{Z} \oplus i\mathbb{Z}$$

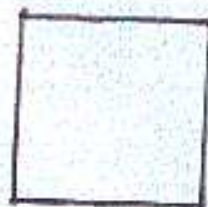
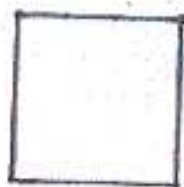
$$\begin{array}{ccc} \mathbb{T}/\pm & \xrightarrow{F} & \mathbb{T}/\pm \\ \downarrow p & & \downarrow p \\ \hat{\mathbb{C}} & & \hat{\mathbb{C}} \end{array}$$

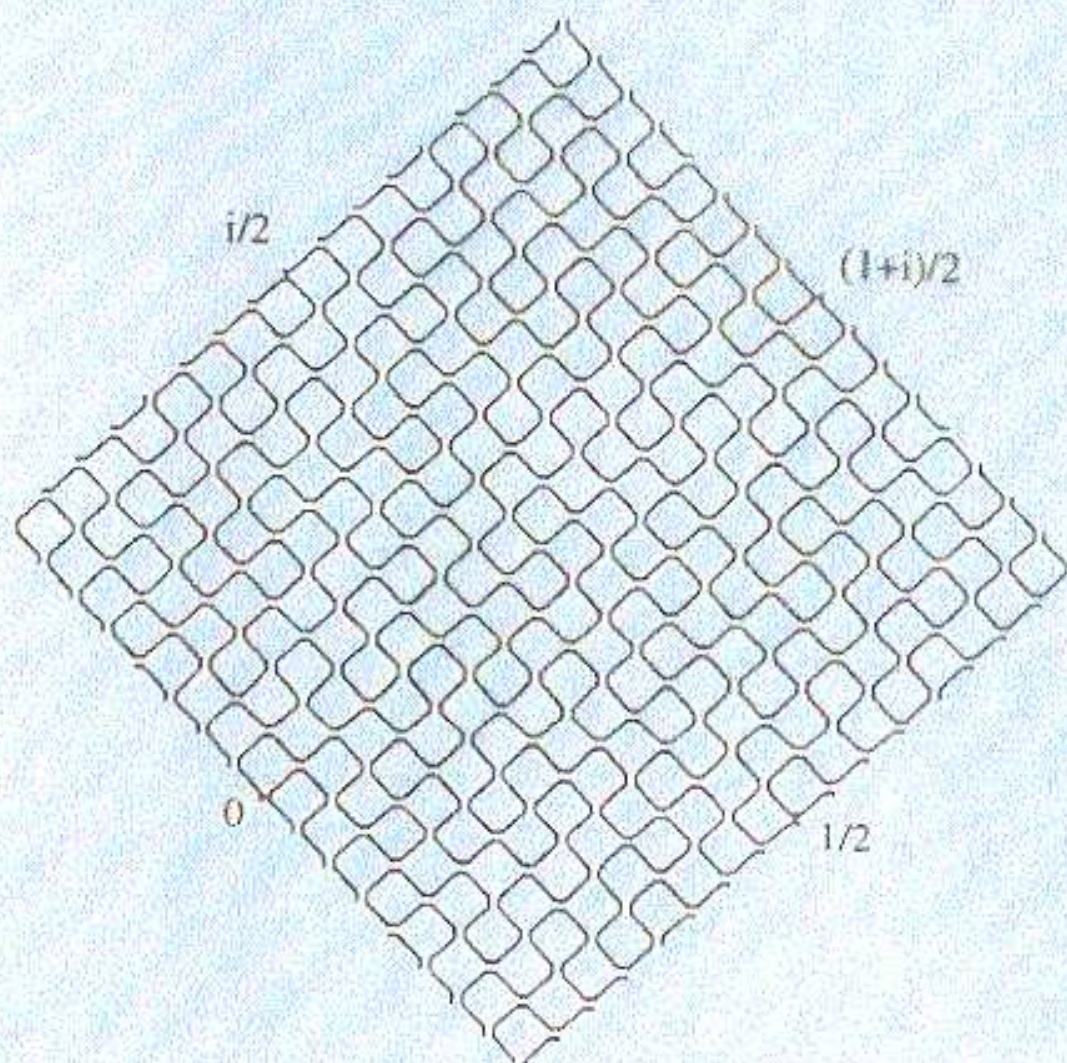
$L(w) = (1-i)w$



The Heighway Dragon construction

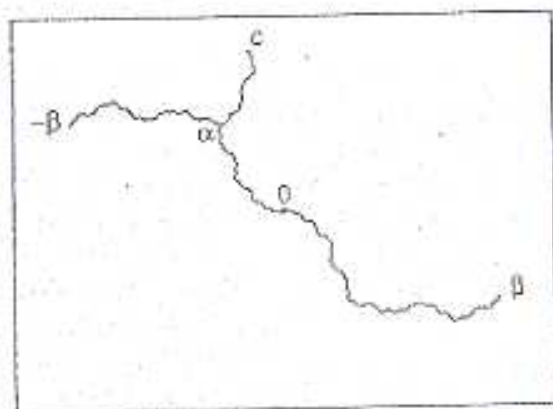




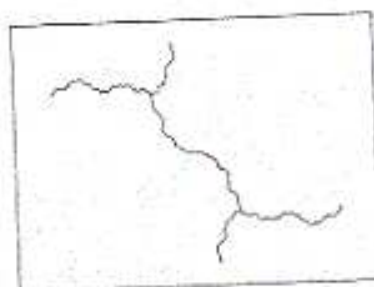


A fundamental domain of

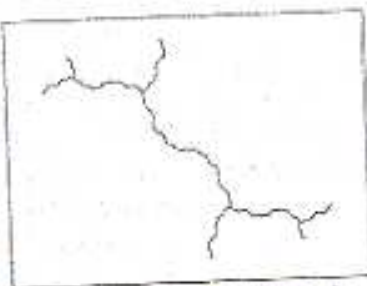
$$\mathbb{H} / \Gamma_2$$



The Hubbard tree of f
the spine $[-\beta, \beta] = S_0$



$$S_1 = f^{-1}(S_0)$$

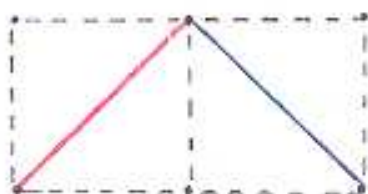


$$S_2 = f^{-1}(S_1)$$



$$S_3 = f^{-1}(S_2)$$

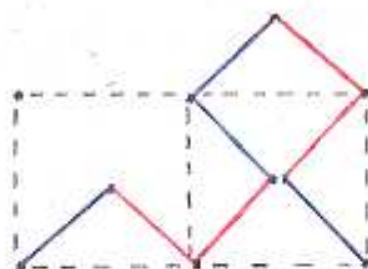
Successive preimages of the spine,
the limit S_∞ is dense in $J(f)$.



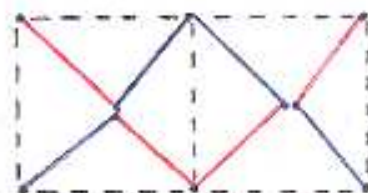
$$L(W) = (1-i)W$$



$$L$$



redrawn in
a fundamental
domain



On Lattès
Maps

pp. 9-43
(2006)

Dynamics on the Riemann Sphere

A Bodil Branner Festschrift

Poul G. Hjorth
Carsten Lunde Petersen

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