

# **Quantum Measurement Approach to a Non-Markovian Master Equation\***

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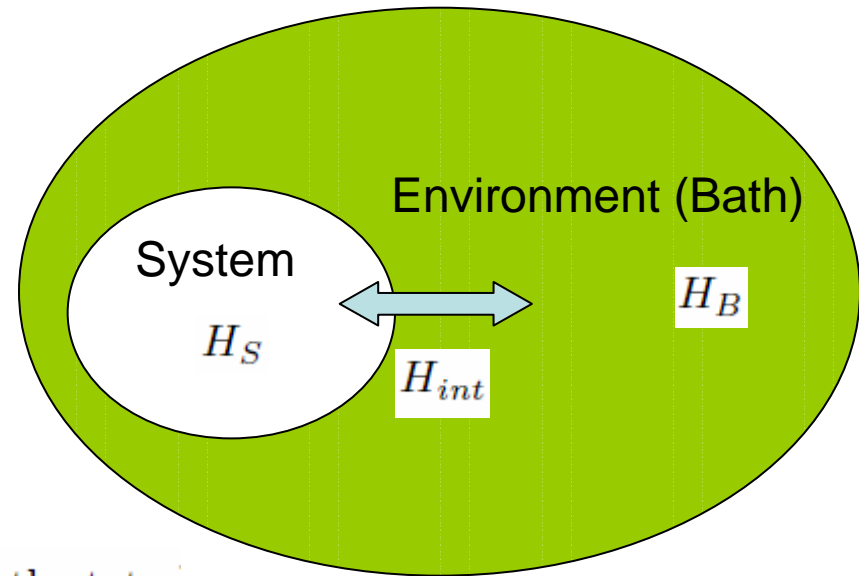
# Open System Dynamics

Exact Solution (Kraus Rep.):

$$\rho_S(t) = \sum_{\alpha} E_{\alpha}(t) \rho_S(0) E_{\alpha}^{\dagger}(t),$$

$$\sum_{\alpha} E_{\alpha}^{\dagger}(t) E_{\alpha}(t) = I.$$

$$E_{\alpha}(t) = \sqrt{\nu} \langle \mu | U(t) | \nu \rangle, \quad |\nu\rangle \text{ and } |\mu\rangle \text{ are bath states.}$$



Markovian Regime (Lindblad Eq.):

$$\frac{\partial \rho_S}{\partial t} = \mathcal{L} \rho_S = -\frac{1}{2} \sum_{\alpha} a_{\alpha} ([F_{\alpha}, \rho_S F_{\alpha}^{\dagger}] + [F_{\alpha} \rho_S, F_{\alpha}^{\dagger}]), \quad \rho_S(t) = e^{\mathcal{L}t} \rho_S(0).$$

## *Dynamics in Two Limits*

	<i>Exact Solution</i>	<i>Markovian Approximation</i>
<i>Advantages</i>	No approximation	1. Closed form of dynamical map. 2. Effective numerical solution.
<i>Disadvantages</i>	Analytically solvable only for simple models.	Inadequate description for a bath with a significant memory effect.

### *Goal of the presented work:*

“ To develop a dynamical master equation beyond the Markovian regime that is analytically solvable and the resulting map is completely positive.”



# Measurement Theory Picture of Dynamics

Kraus Sum Representation:  $\rho_{out} = \sum_k M_k \rho_{in} M_k^\dagger$ ,  $\sum_k M_k^\dagger M_k = I$ .

Non-Selective Generalized Measurement (GM):  $\rho_{out} = \sum_k p_k \rho_k$ , k'th outcome:  $\rho_k = \frac{M_k \rho_{in} M_k^\dagger}{\text{Tr}(M_k^\dagger M_k \rho_{in})}$

probability:  $p_k = \text{Tr}(M_k^\dagger M_k \rho_{in})$

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Exact Solution:  $\rho_S(t) = \sum_\alpha E_\alpha(t) \rho_S(0) E_\alpha^\dagger(t)$ . GM operators:  $\{E_\alpha\}$

Lindblad (Quantum Jump):

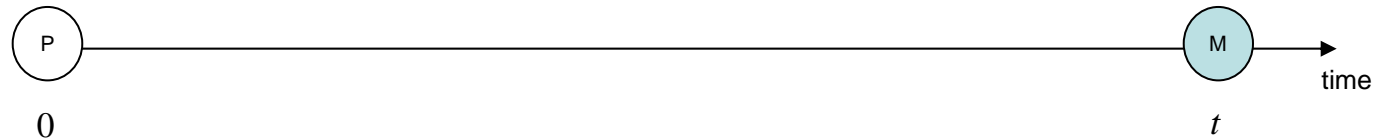
$$\tau \ll \|\mathcal{L}\|^{-1}, \quad \rho_S(t + \tau) \approx \left(I - \frac{\tau}{2} \sum_\alpha F_\alpha^\dagger F_\alpha\right) \rho_S(t) \left(I - \frac{\tau}{2} \sum_\alpha F_\alpha^\dagger F_\alpha\right) + \tau \sum_\alpha F_\alpha \rho_S(t) F_\alpha^\dagger.$$

GM operators:  $\{\sqrt{\tau} F_\alpha, I - \frac{\tau}{2} \sum_\beta F_\beta^\dagger F_\beta\}$



# Single-Shot Measurement Process

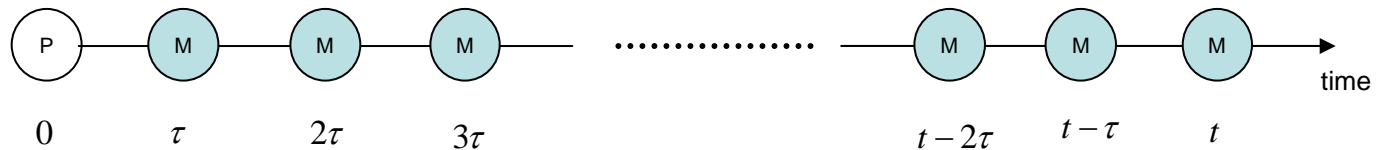
Exact Solution:





Single-Shot Measurement:



Markovian Approximation (Quantum Trajectories):



Measurement: 

Preparation: 



# Non-Markovian Master Equation



## Probabilistic Procedure:

Probability of an extra measurement at time  $t_1$  :  $w(t_1)$  ,

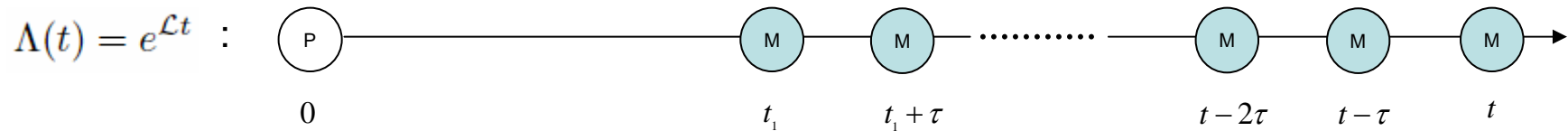
$$\rho_S(t = N\epsilon) = \sum_{m=1}^{N-1} w(m\epsilon)\Lambda(m\epsilon)\rho_S(t_1 = (N - m)\epsilon)$$

## Non-Markovian Master Equation ( Newton Iteration Method ):

$$\frac{\partial \rho_S}{\partial t} = \int_0^t dt' k(t') \Lambda(t') \dot{\Lambda}(t') \Lambda^{-1}(t') \rho_S(t - t') .$$



# Post-Markovian Master Equation



Post-Markovian Master Equation:

$$\frac{\partial \rho_S}{\partial t} = \mathcal{L} \int_0^t dt' k(t') e^{\mathcal{L}t'} \rho_S(t - t')$$

— Markovian approximation can be recovered by choosing:  $k(t) = \delta(t)$  ,

— The intuitively<sup>(1,2)</sup> addressed memory function could also be retrieved in the limit of  $\|\mathcal{L}\| \ll \mathbf{T}^{-1}$

$$\frac{\partial \rho_S}{\partial t} = \mathcal{L} \int_0^t dt' k(t') \rho_S(t - t')$$



## Example: Single Qubit Dephasing

Spin-Boson Hamiltonian:  $H_{SB} = \sum_k \sigma_z \otimes (\lambda_k \mathbf{b} + \lambda_k^* \mathbf{b}^\dagger)$

$$\rho(t) = \frac{1}{2}(I + f(t)\alpha_x\sigma_x + f(t)\alpha_y\sigma_y + \alpha_z\sigma_z)$$

Exact Solution

Markovian Regime

$$f(t) = \exp\left[-\sum_k |\lambda_k|^2 \frac{\sin^2(\omega_k t)}{\omega_k^2} \coth\frac{\hbar\omega_k}{2k_B T}\right]$$

$$f(t) = \exp\left[-\frac{t}{\tau} \sum_k |\lambda_k|^2 \frac{\sin^2(\omega_k \tau)}{\omega_k^2} \coth\frac{\hbar\omega_k}{2k_B T}\right] \triangleq e^{-at}$$

Post-Markovian Equation Result:

Memory Function:  $k(t) = (1 - \theta)\frac{1}{\gamma}e^{-\gamma t} + \theta\delta(t)$

$$f(t) = (1 - \theta)e^{-(\gamma/2+a)t} \cos(\sqrt{2a\gamma - (\gamma/2 + a)^2}t + \varphi) + \theta e^{-at}$$





# Quantum Dynamical Map

Laplace Transformation:  $s\tilde{\rho}_S(s) - \rho_S(0) = [\tilde{k}(s) * \frac{\mathcal{L}}{s - \mathcal{L}}]\tilde{\rho}_S(s)$

Eigenvalue, right and left eigenoperators of the superoperator  $\mathcal{L} : \{\lambda_i, R_i, L_i\}$ .

$$\begin{cases} \mathcal{L}\rho_i = \lambda_i\rho_i \\ \rho_S(t) = \sum_i \mu_i(t)R_i \end{cases} \Longrightarrow s\tilde{\mu}_i(s) - \mu_i(0) = \lambda_i\tilde{k}(s - \lambda_i)\tilde{\mu}_i(s)$$

Dynamical Map:

$$\Phi(t) : \rho \longmapsto \sum_i \xi_i(t) \text{Tr}[L_i\rho] R_i, \quad \xi_i(t) = \text{Lap}^{-1}\left[\frac{1}{s - \lambda_i\tilde{k}(s - \lambda_i)}\right]$$



## Complete Positivity:

$$\Phi((|i\rangle\langle j|))_{1 \leq i, j \leq n} \geq 0 \quad \Longrightarrow \quad \sum_k \xi_k(t) L_k^T \otimes R_k \geq 0 .$$

## Experimental Determination of the Kernel Function:

Quantum state tomography result:  $\rho(t)$  .

Kernel function:

$$k(t) = \text{Lap}^{-1}[(s - 1/\text{Lap}[\xi_i(t)])]e^{-\lambda_i t} / \lambda_i$$

$$\xi_i(t) = \text{Tr}[L_i \rho(t)] / \text{Tr}[L_i \rho(0)]$$



## *Conclusion and Possible Extensions:*

### **We have introduced:**

- Phenomenological picture of a non-Markovian master equation in the measurement theory.
- A post-Markovian master equation which can be analytically solved by applying the Laplace transform.
- A condition on the memory function to preserve the complete positivity of the corresponding dynamical map.

### **We like to present in the future:**

- Improving the introduced non-Markovian equation by going to higher steps of Newton iteration method.
- Exploring the memory function for a set of performed experiment results.

