

# A NOVEL METHOD FOR MOTION CORRECTION IN CARDIAC MRI

Marshall S. Sussman

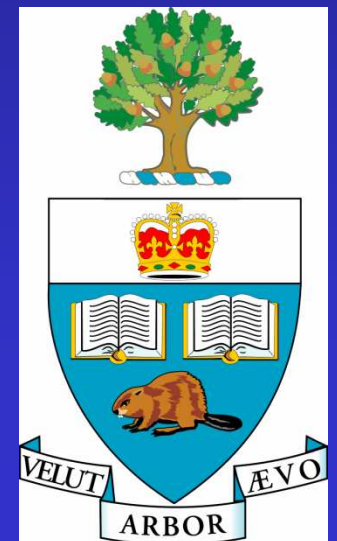
[marshall.sussman@utoronto.ca](mailto:marshall.sussman@utoronto.ca)

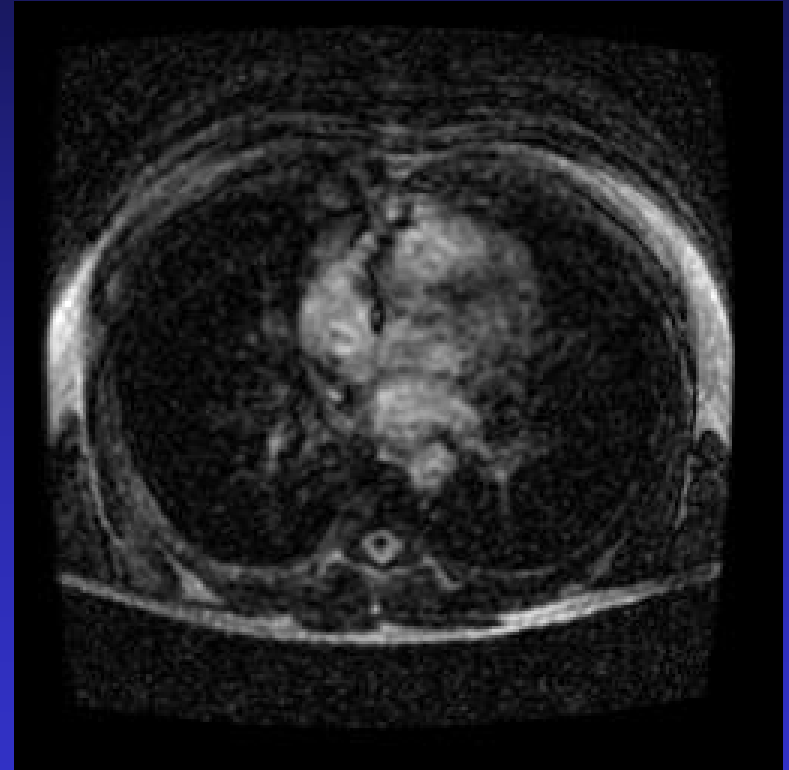
Department of Medical Imaging,  
University Health Network,  
University of Toronto

MITACS-Fields Conference on the  
Mathematics of Medical Imaging  
June 21, 2011



University Health Network





# OUTLINE

- Basic MR image formation

Motion-related errors

- Motion compensation methods

Challenge:

- § Complex cardiac motion

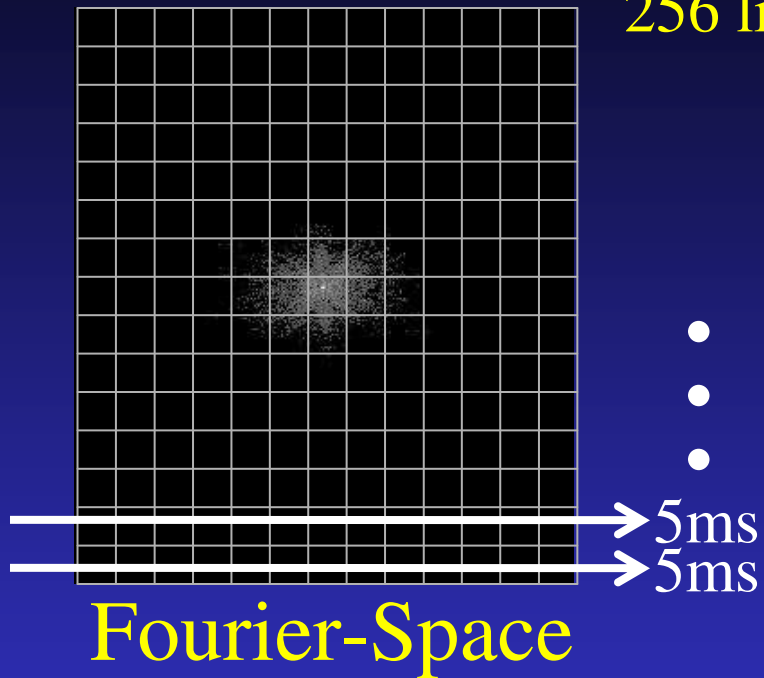
- § Limited information about that motion

New method

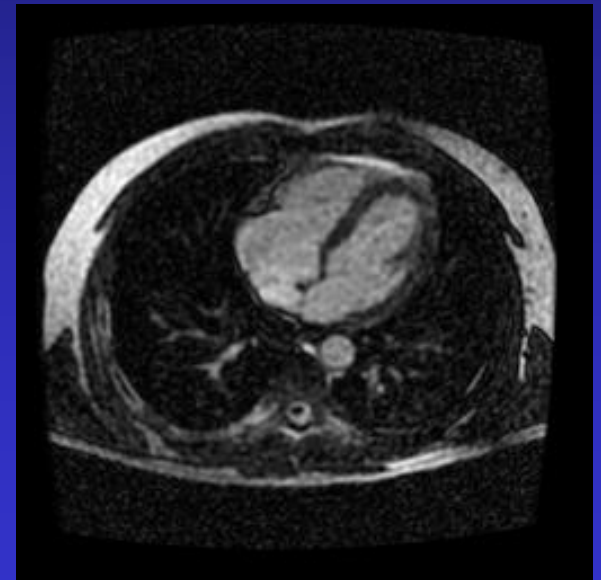
# MR IMAGE FORMATION

256 lines: ~ 1 second

- Multiple slices: ~ minute



Fourier Transform



Image

# ANATOMICAL MOTION

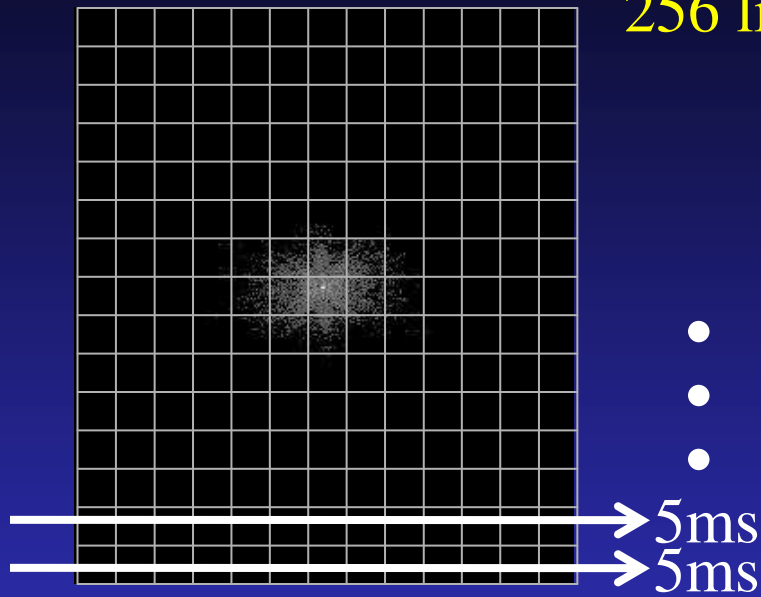
- MR scans: ~ seconds – minutes



- Motion
  - Cardiac: ~1 beat/s
  - Respiratory: ~5s per breath

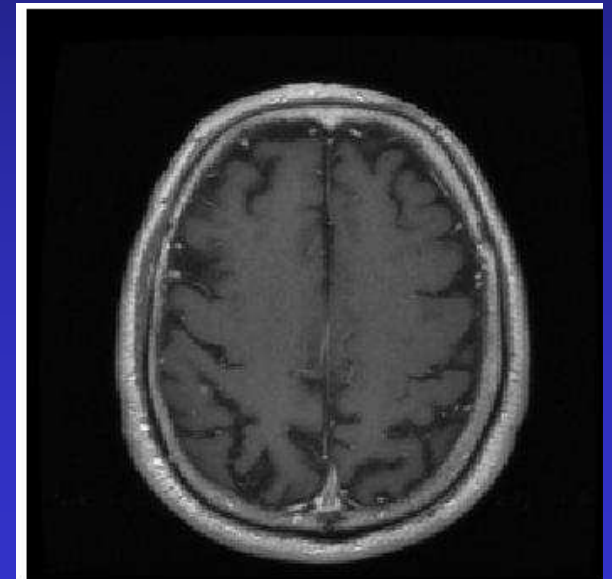
# WHY IS MOTION A PROBLEM?

256 lines: ~ 1 second



Fourier Space

Fourier Transform



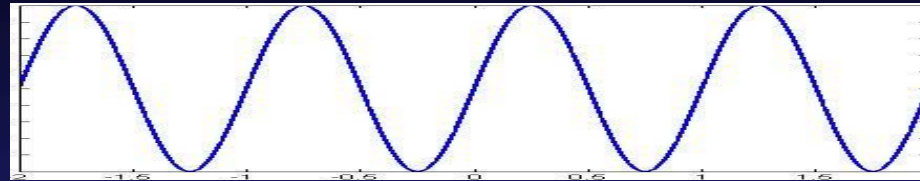
Image

- Data in different parts of Fourier space will be inconsistent

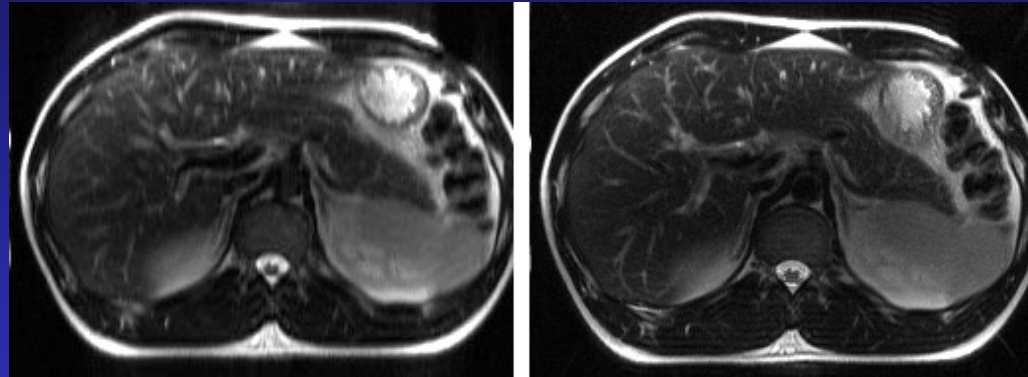
Artifacts (errors) in the images

# NATURE OF MRI ARTIFACTS

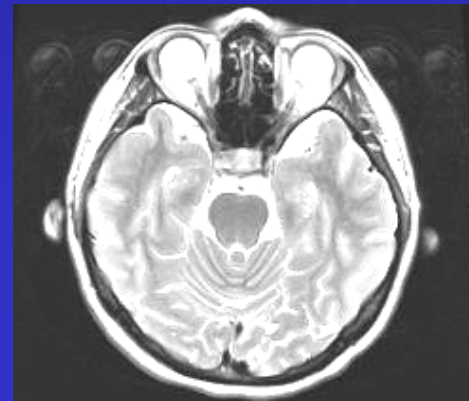
- Periodic motion
- Two types of artifacts



1) Blurring



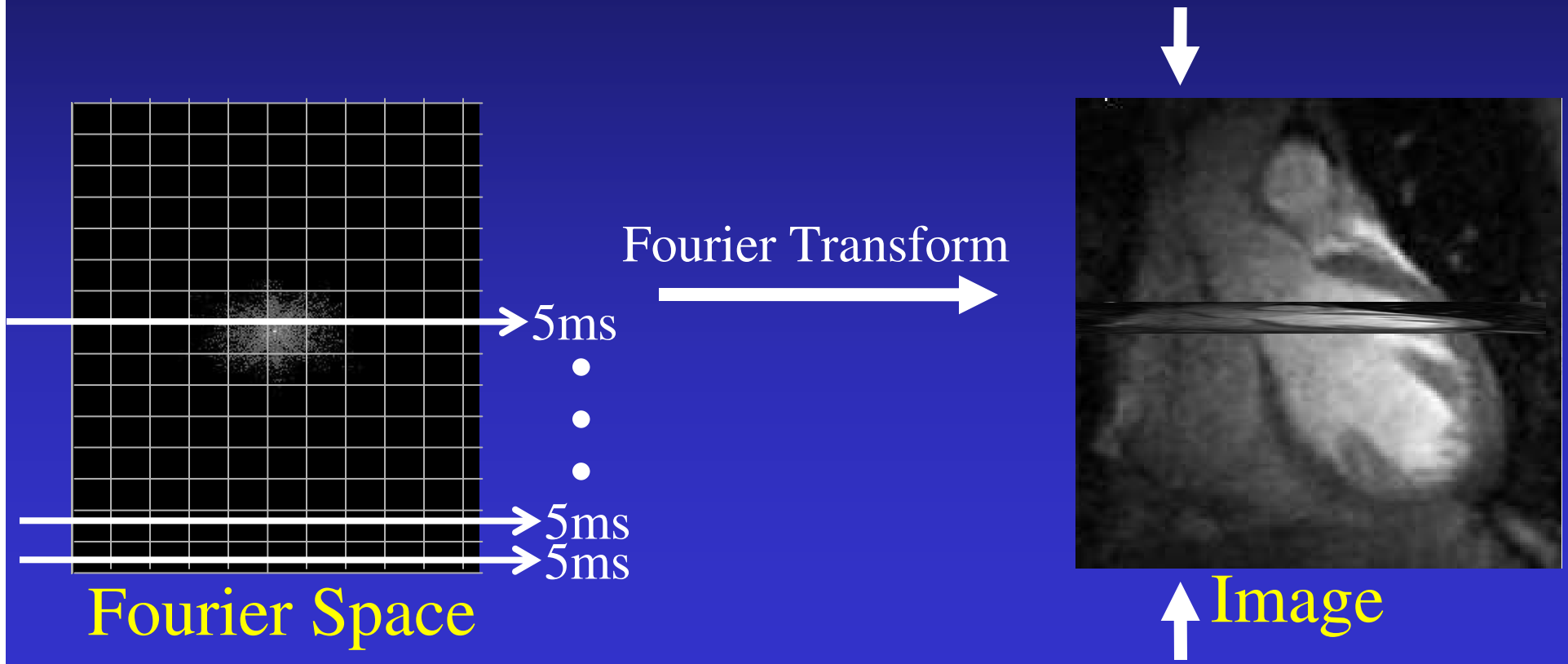
2) Ghosting



# CORRECTING FOR MOTION

- Navigator echoes

1D Fourier Transform central line of Fourier space  
~5ms



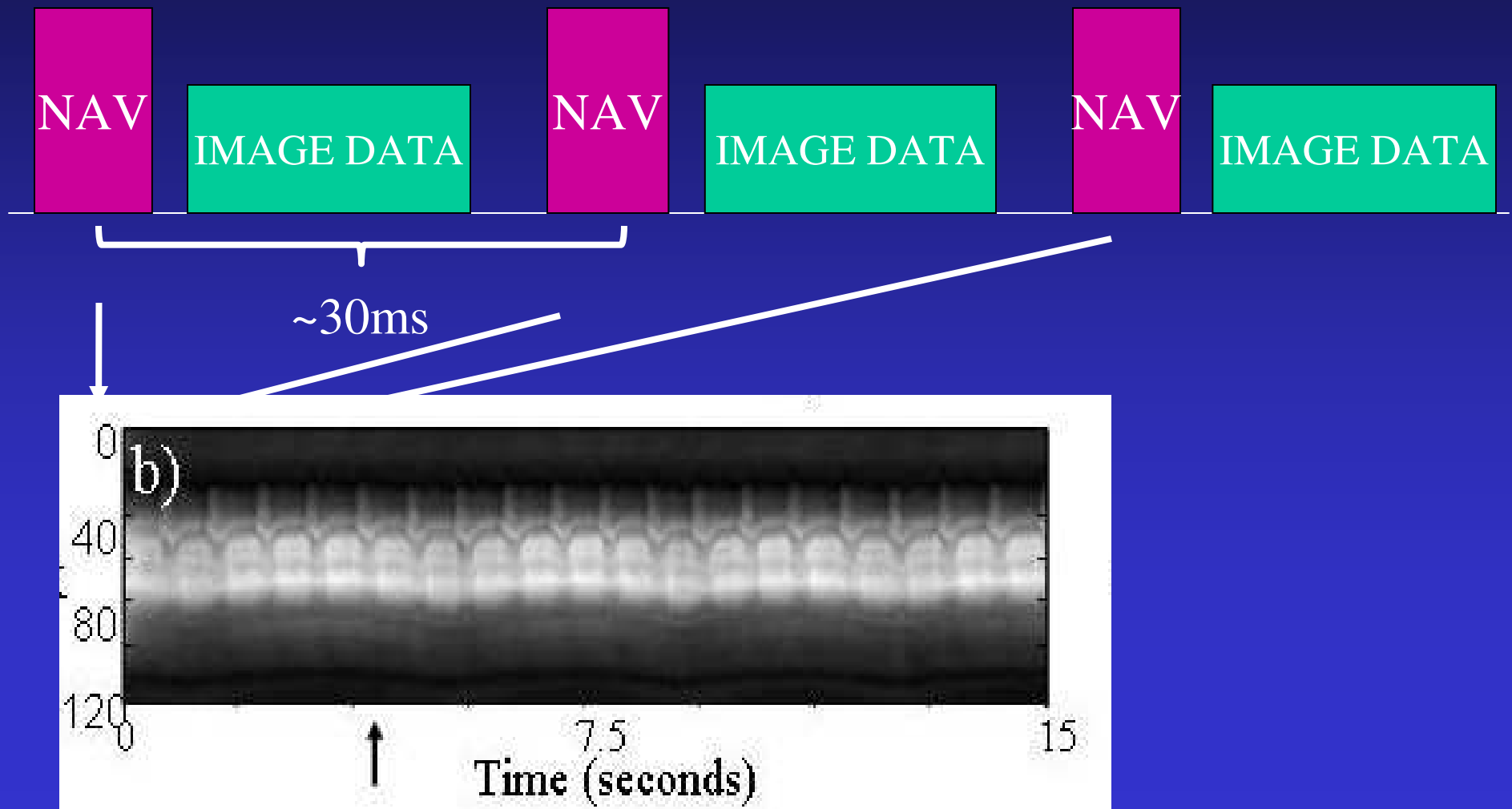


# NAVIGATOR ECHOES

- Interleave navigator echo with image data acquisition

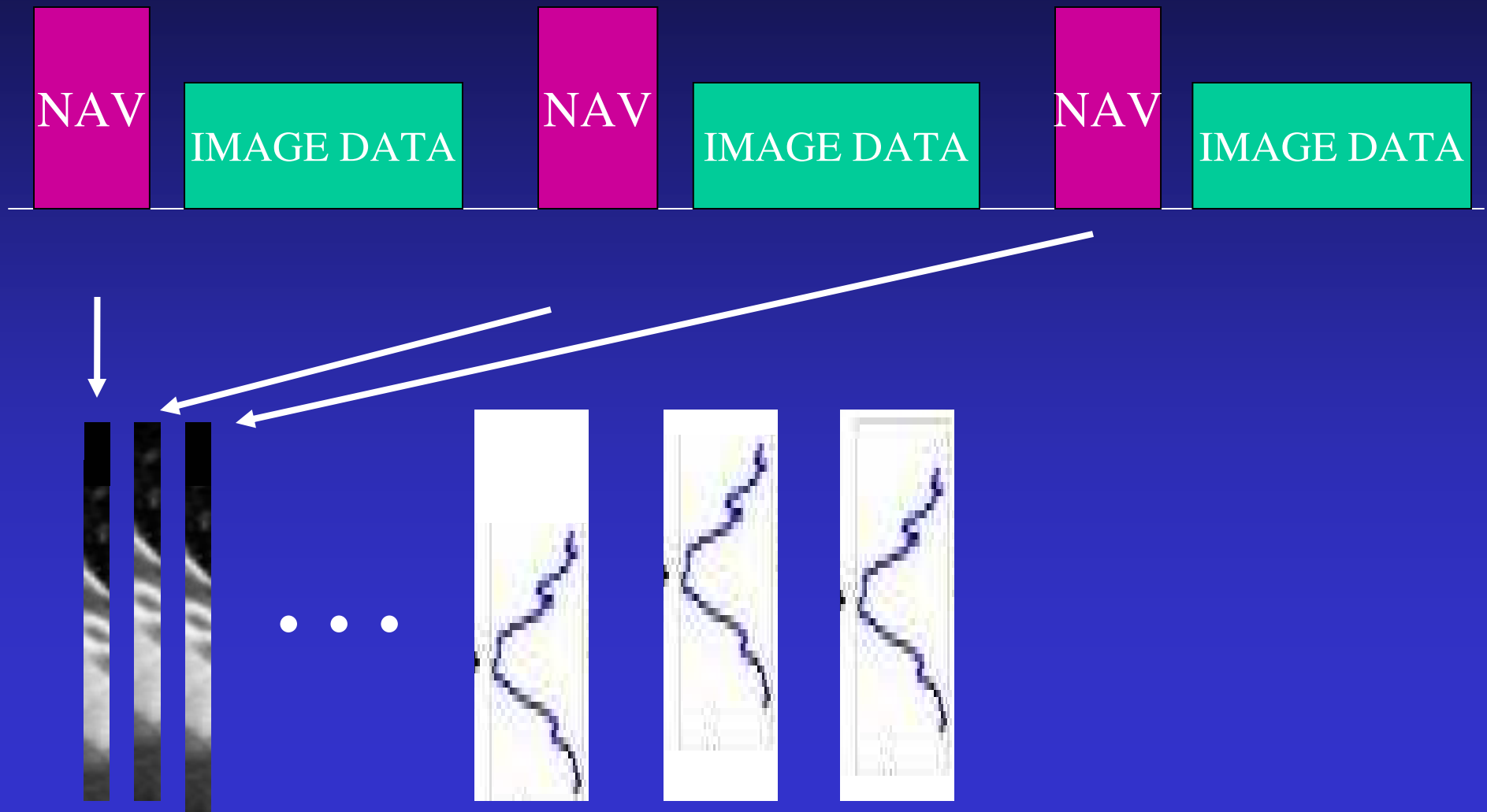
Obtain 1D projections every ~30ms (vs. 1 second for 2D image)

Use projections to monitor and correct for motion in the image data

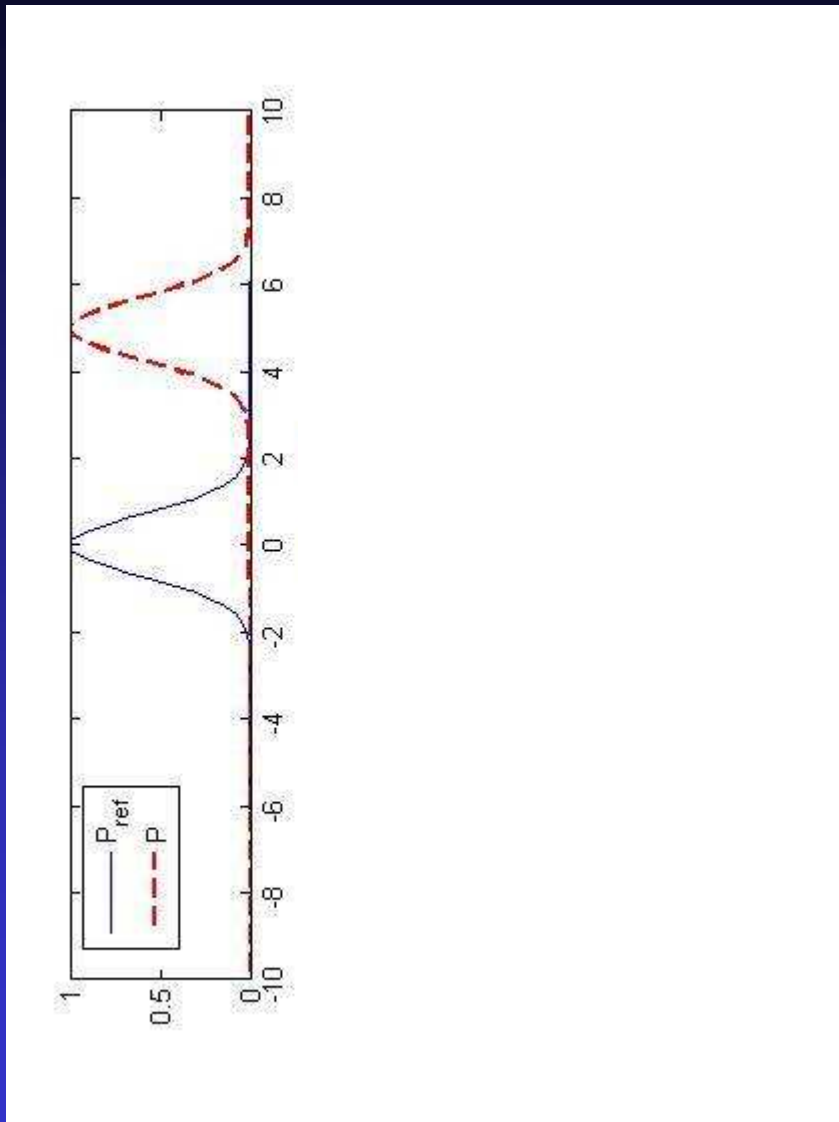


# MONITORING MOTION

- To track motion, need to determine the relative displacement between 1D projections



# TEMPLATE MATCHING



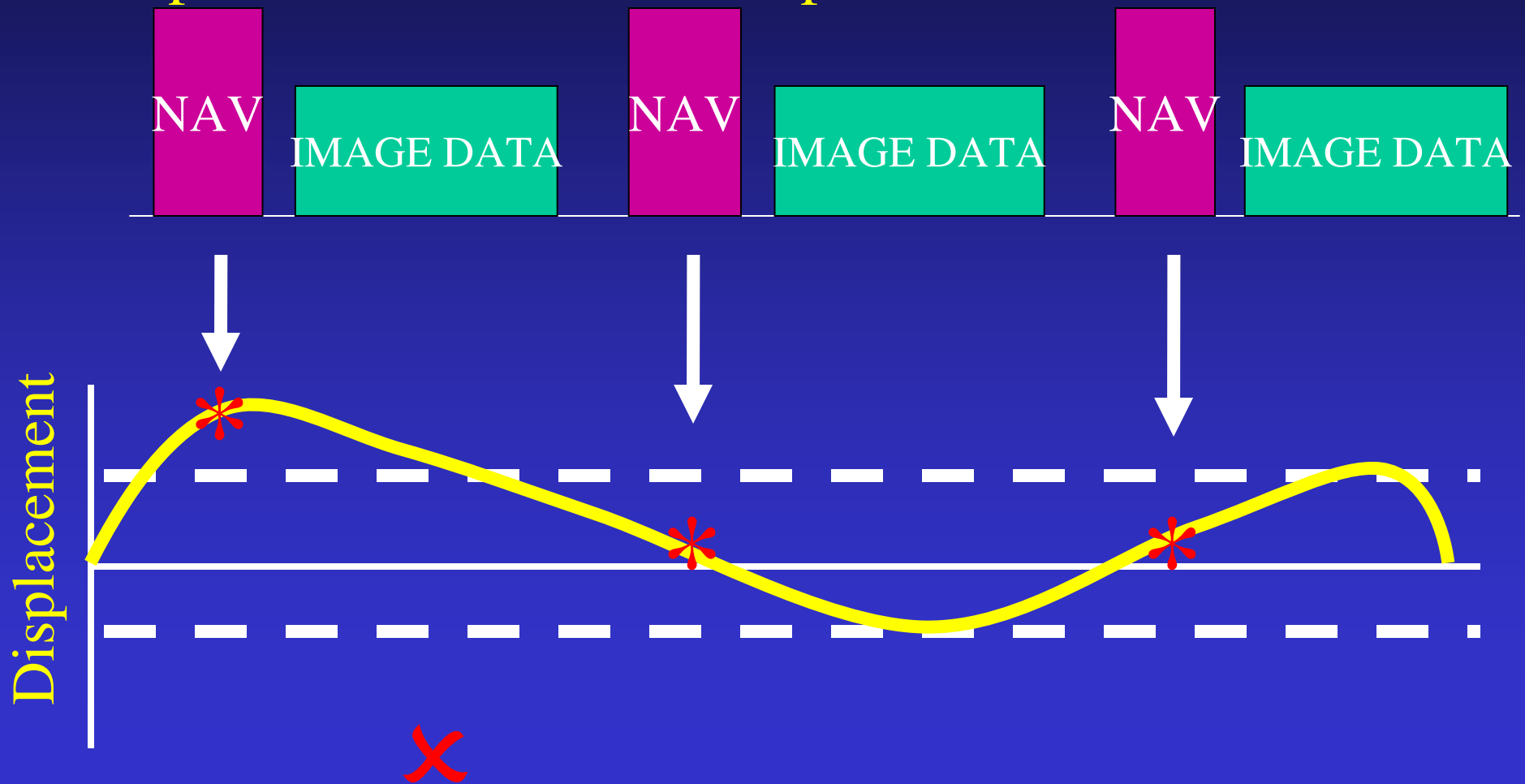
$\Delta x = 0,$        $\Delta x = 3,$        $\Delta x = 5,$   
 $LSQ(\Delta x) = 25$     $LSQ(\Delta x) = 10$     $LSQ(\Delta x) = 0$

$$LSQ(\Delta x) = [P_{\text{ref}}(x) - P(\Delta x)]^2$$

$\Rightarrow$  displacement = 5

# CORRECTING FOR MOTION

- Using template matching, can determine relative displacement of anatomy during navigator echoes
- Accept data with minimal displacement

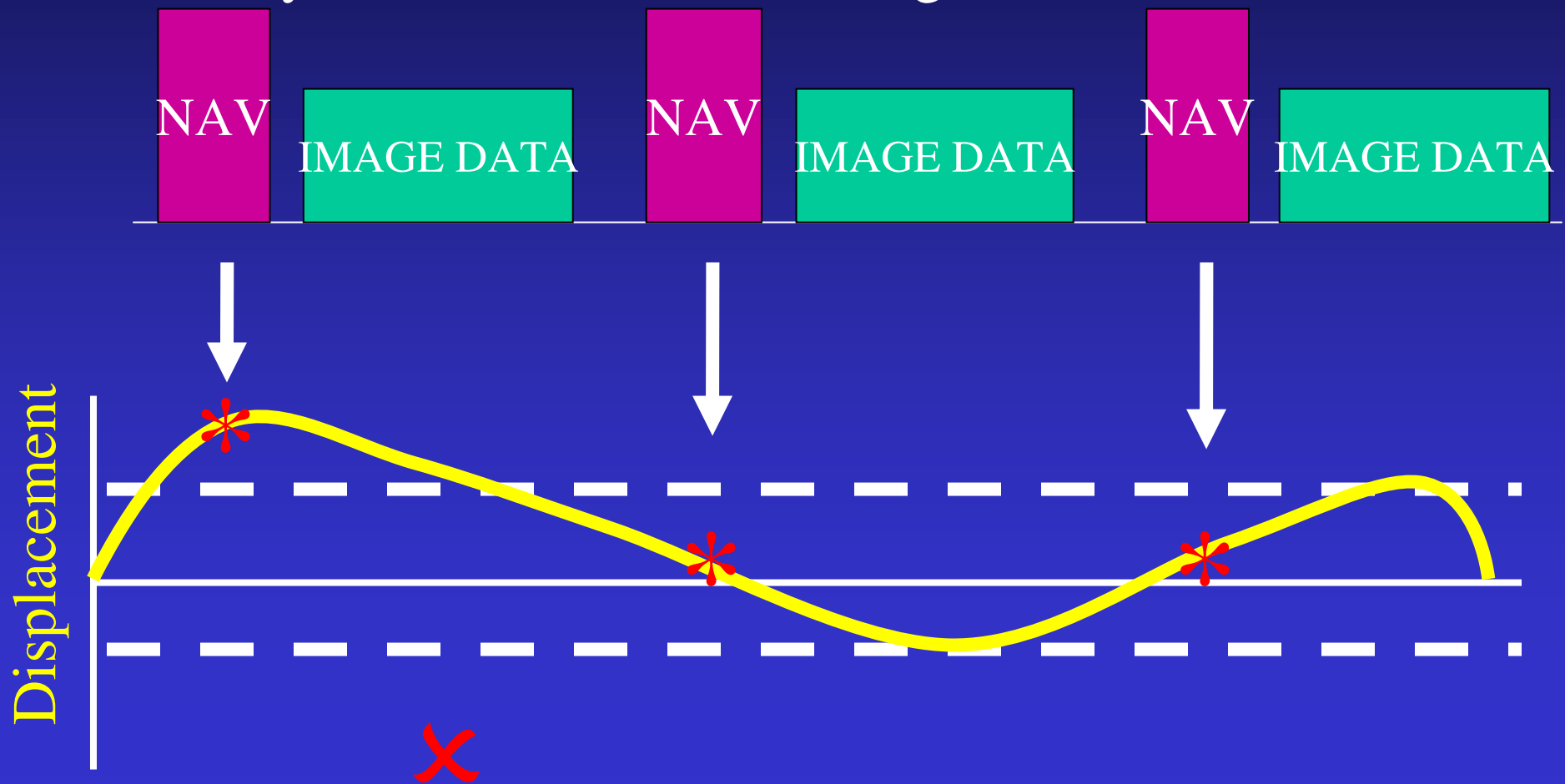


# CORRECTING FOR MOTION

- Using template matching, can identify a complete set of image data with minimal relative displacement

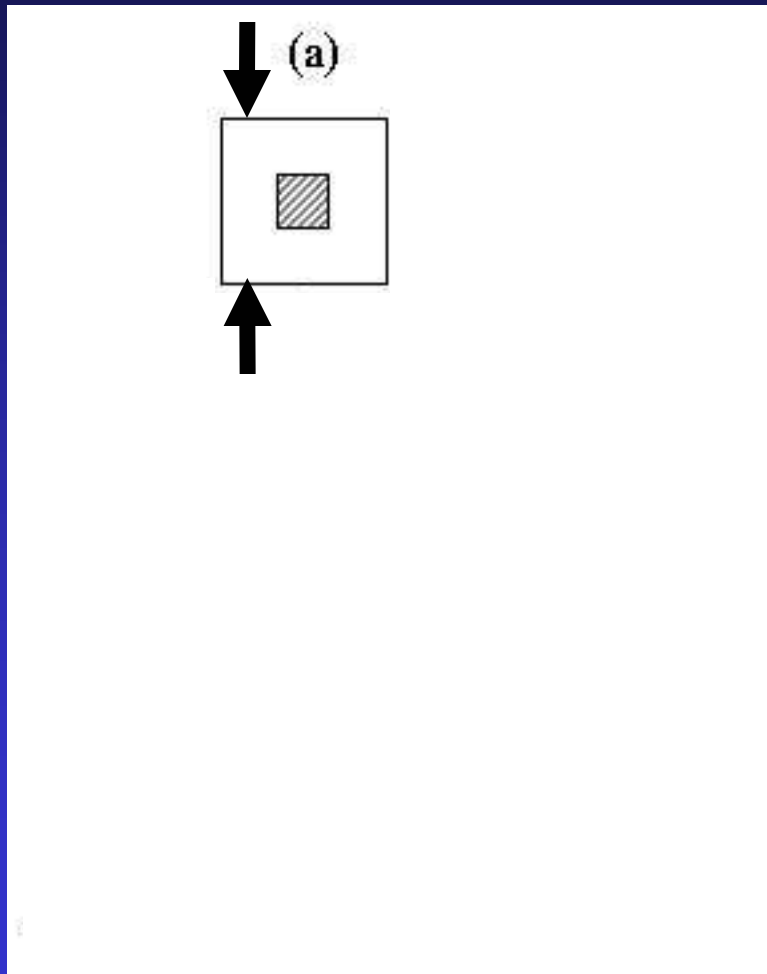
Minimize artifacts in the image

- But:** Only works if motion tracking is accurate



# IS MOTION TRACKING ACCURATE?

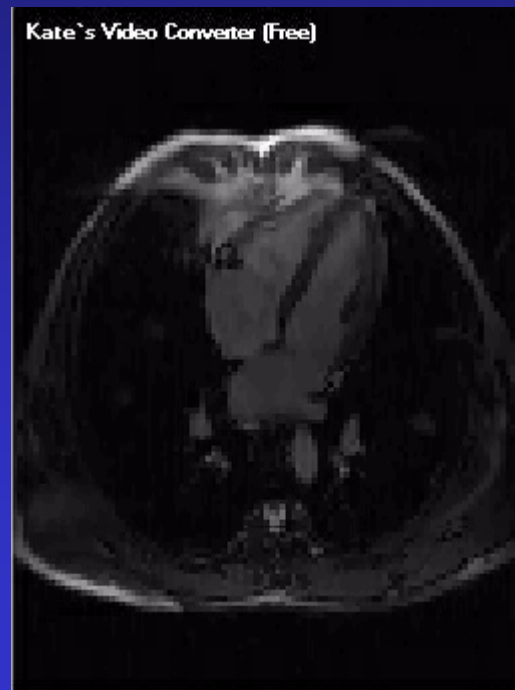
- Depends on the type of motion



# IS MOTION TRACKING ACCURATE?

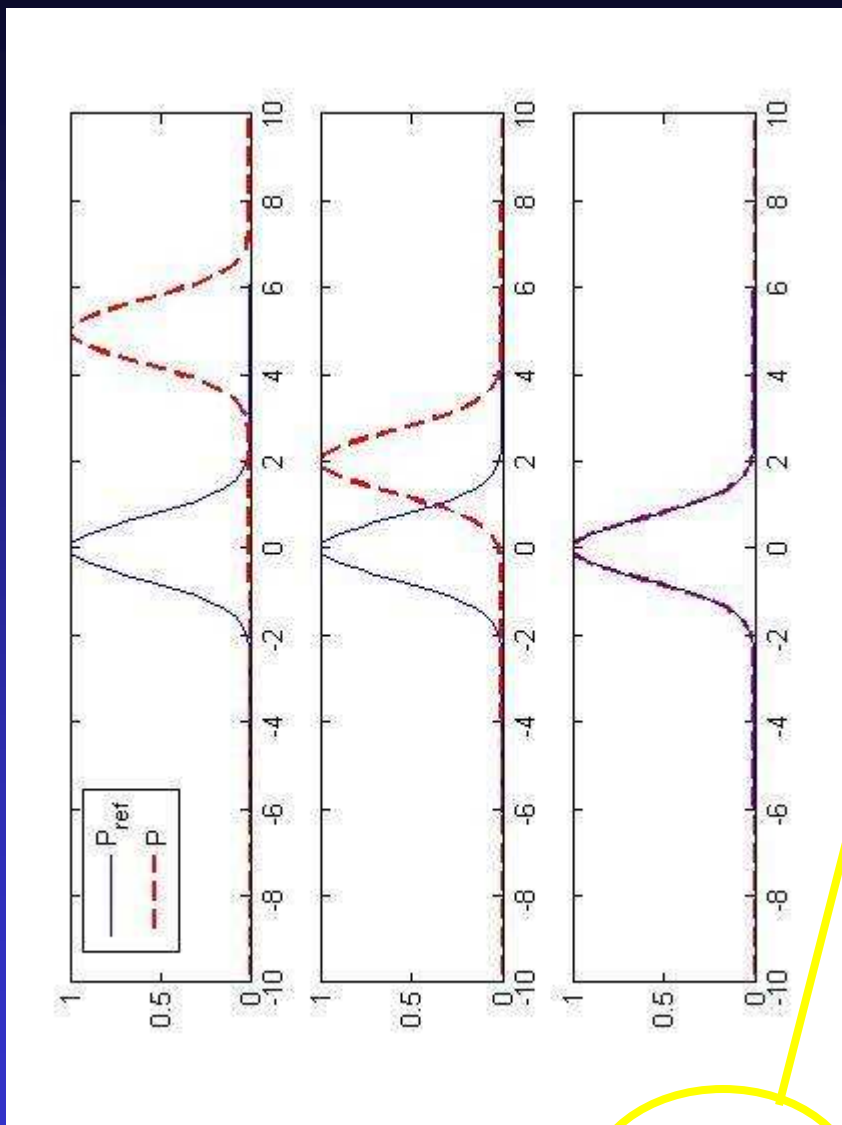
- Two problems:

- 1) Template matching only works well for rigid-body translation
- 2) From a 1D projection, there is limited information available about the motion



Example

# TEMPLATE MATCHING



$\Delta x = 0,$        $\Delta x = 3,$        $\Delta x = 5,$   
 $LSQ(\Delta x) = 25$     $LSQ(\Delta x) = 10$     $LSQ(\Delta x) = 0$

$$LSQ(\Delta x) = [P_{ref}(x) - P(\Delta x)]^2$$

- This implies a rigid-body displacement of 5 pixels
- If we know the motion is rigid-body, can easily correct for it.

Displacement doesn't really matter

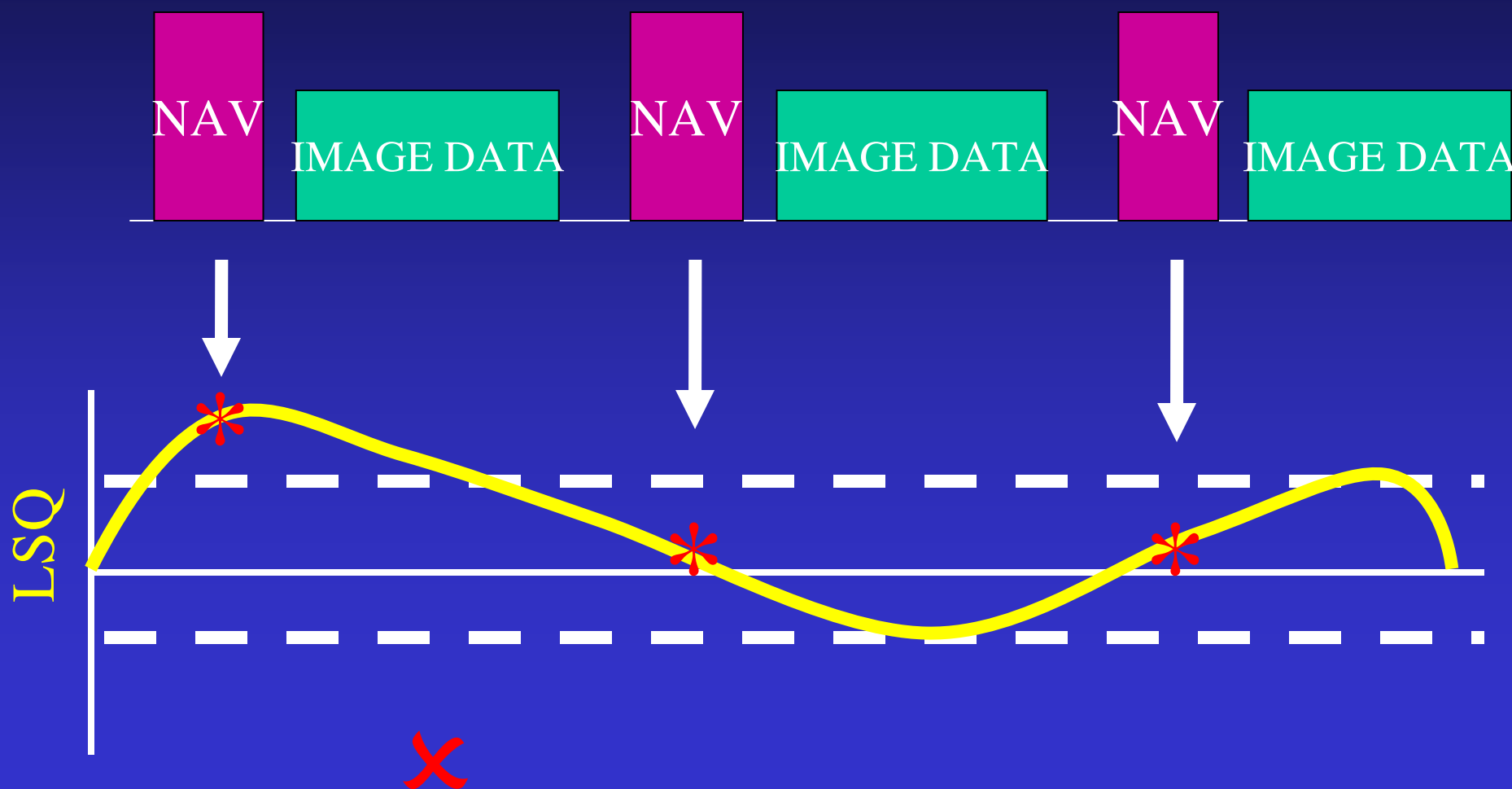
$\Rightarrow$  displacement = 5



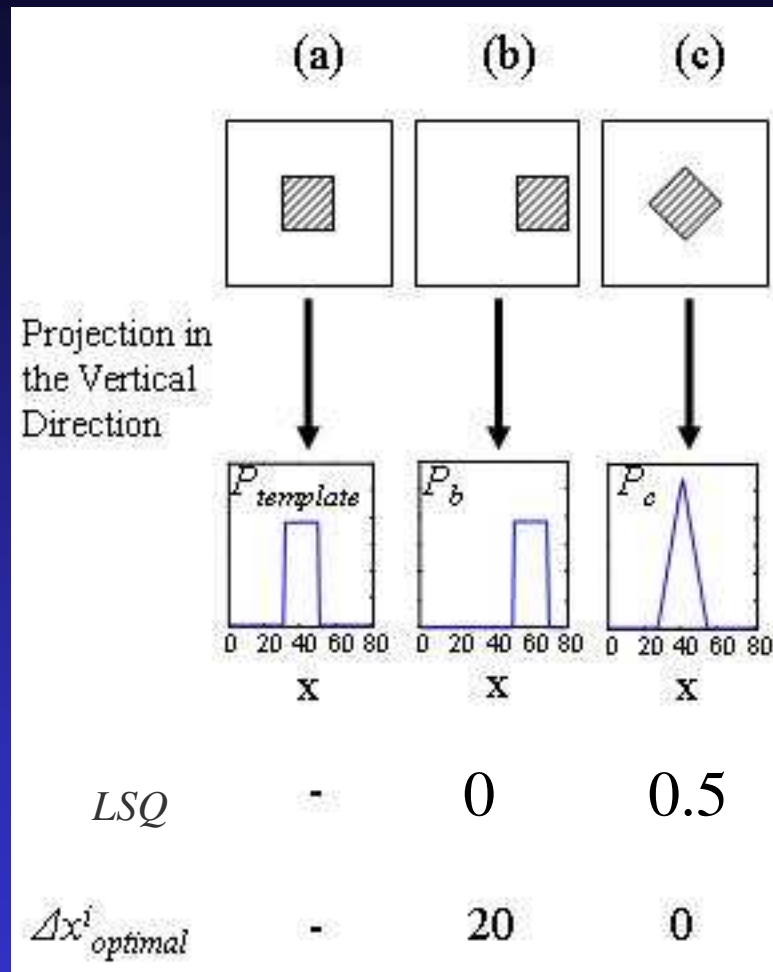
# CORRECTING FOR MOTION

- IDEA: Select data acquired when  $LSQ_i(\Delta x)$  is minimal for the corresponding navigator  $LSQ_i(\Delta x) = [P_{\text{ref}}(x) - P_i(\Delta x)]^2; i = 1, \dots, n$

Correct for displacement

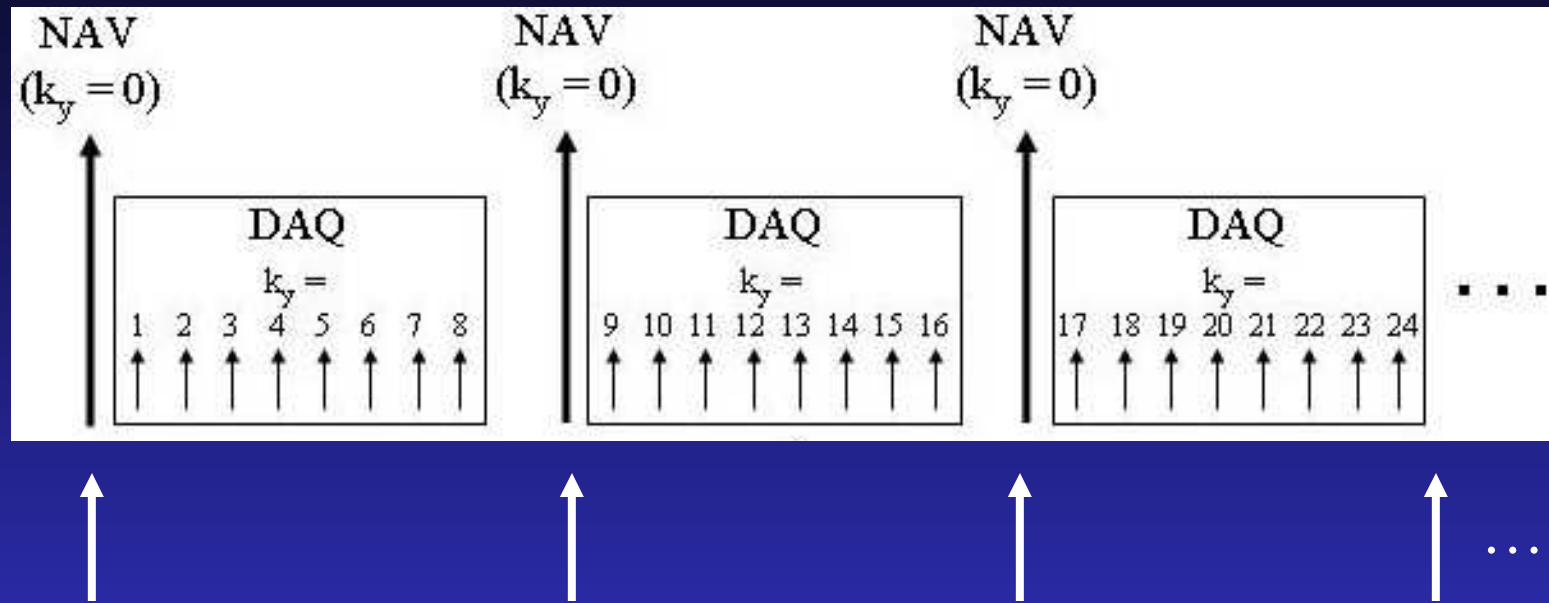


# SIMILARITY-BASED NAVIGATOR ECHO



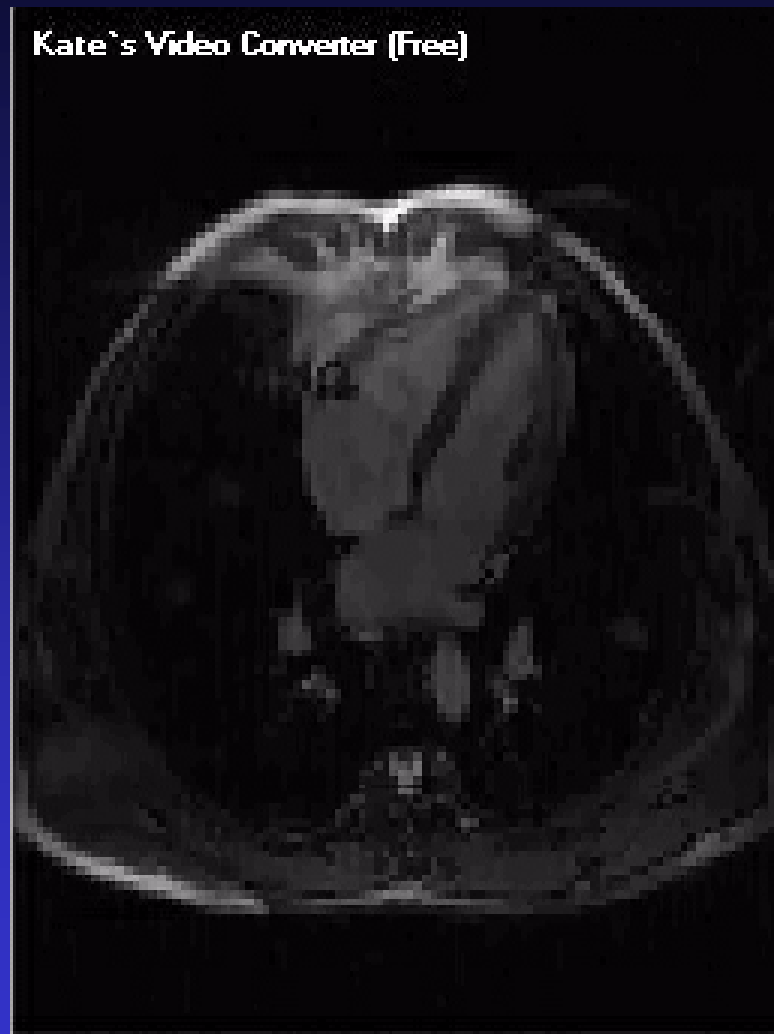
- Can set similarity threshold (as opposed to displacement threshold) for selecting data

# ADDING IN TEMPORAL INFORMATION



- Can use any or all navigator lines as a reference
  - Select data independently for each reference
  - Movies!

# EXAMPLES



Example

# EXAMPLES



Arrhythmia

# EXAMPLES



WRIST



HEAD

## SUMMARY

- Motion during an MR scan leads to errors in the images
- Conventional methods of dealing with cardiac motion search for data with minimal relative displacement
  - May not be adequate to deal with complex, 3D deformable cardiac displacement
- Searching for similar data allows one to suppress the effect of motion of almost arbitrary complexity

Funding provided by: Ontario Research and Development Challenge Fund (ORDCF)  
Ontario Research Fund (ORF)