

On the Universal Rigidity of Tensegrity Frameworks

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A tensegrity framework has **two** aspects: a **geometric one** (p) and a **combinatorial one** (G).

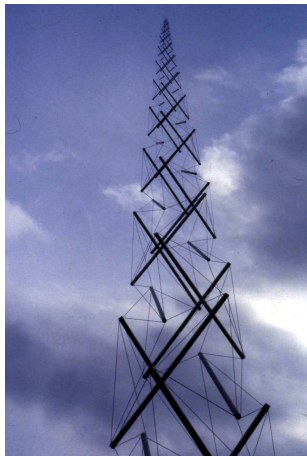
Applications

tensegrities have important applications in:

- 1 Molecular conformation theory.
- 2 Wireless sensor network localization problem.
- 3 Art.

Tensegrity as an Artwork

Kenneth Snelson **needle tower** sculpture in Washington D.C.



Tensegrity as an Artwork Cont'd

Kenneth Snelson [Indexer II](#) sculpture at the University of Michigan, Ann Arbor



Domination and Affine-Domination

Definition

Tensegrity (G, q) in \mathbb{R}^s is said to be **dominated by** tensegrity (G, p) in \mathbb{R}^r if

$$\|q^i - q^j\| = \|p^i - p^j\| \text{ for all bar } \{i, j\}.$$

$$\|q^i - q^j\| \leq \|p^i - p^j\| \text{ for all cable } \{i, j\}.$$

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Definition

Tensegrity (G, q) in \mathbb{R}^r is said to be **affinely-dominated by** tensegrity (G, p) in \mathbb{R}^r if (G, q) is dominated by (G, p) and

$$q^i = Ap^i + b \text{ for all } i = 1, \dots, n$$

for some $r \times r$ matrix A and an r -vector b .

Dimensional and Universal Rigidities

Definition

Tensegrity (G, q) in \mathbb{R}^r is said to be **congruent** to tensegrity (G, p) in \mathbb{R}^r if $\|q^i - q^j\| = \|p^i - p^j\|$ for every $i = 1, \dots, n$.

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Definition

An r -dimensional tensegrity (G, p) in \mathbb{R}^r is said to be **dimensionally rigid** if no s -dimensional tensegrity (G, q) , **for any $s \geq r + 1$** , is dominated by (G, p) .

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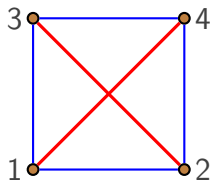
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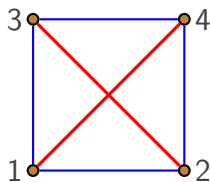
Definition

An r -dimensional tensegrity (G, p) in \mathbb{R}^r is said to be **universally rigid** if every s -dimensional tensegrity (G, q) , **for any s** , that is dominated by (G, p) **is in fact congruent to (G, p)** .

Example



Example

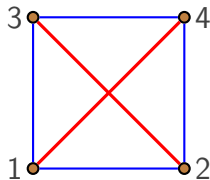


universally
rigid.

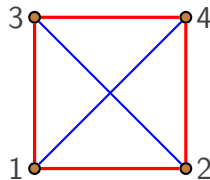
Example

 Cable

 Strut



universally
rigid.



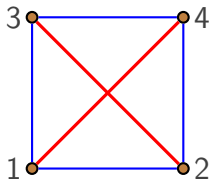
Example



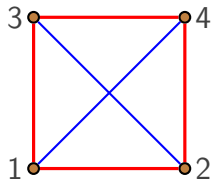
Cable



Strut



universally
rigid.



Not universally rigid. It folds
on the diagonal.

Characterization of Universal Rigidity

Theorem

An r -dimensional Tensegrity (G, p) in \mathbb{R}^r is *universally rigid* if and only if

- 1 (G, p) is *dimensionally rigid*.
- 2 There *does not exist* an r -dimensional tensegrity (G, q) in \mathbb{R}^r *affinely-dominated* by, but not congruent to, (G, p) .

Condition 2 is known as the “no conic at infinity” condition.

In This Talk, I'll:

- 1 Present the well-known sufficient condition for dimensional rigidity.

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- 1 Present the well-known sufficient condition for dimensional rigidity.
- 2 Present conditions under which the “no conic at infinity” holds.

Stress Matrices

- A **stress** of a tensegrity (G, p) is a real-valued function ω on $E(G) = B \cup C \cup S$ such that:

$$\sum_{j:\{i,j\} \in E(G)} \omega_{ij}(p^i - p^j) = 0 \text{ for all } i = 1, \dots, n.$$

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- A stress ω is **proper** if $\omega_{ij} \geq 0$ for every $\{i, j\} \in C$ and $\omega_{ij} \leq 0$ for every $\{i, j\} \in S$.

Stress Matrices

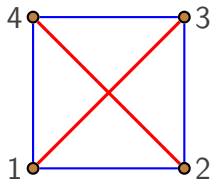
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- A stress ω is **proper** if $\omega_{ij} \geq 0$ for every $\{i, j\} \in C$ and $\omega_{ij} \leq 0$ for every $\{i, j\} \in S$.
- The **stress matrix** associated with stress ω is the $n \times n$ **symmetric matrix** Ω where

$$\Omega_{ij} = \begin{cases} -\omega_{ij} & \text{if } (i, j) \in E(G), \\ 0 & \text{if } (i, j) \notin E(G), \\ \sum_{k:\{i,k\} \in E(G)} \omega_{ik} & \text{if } i = j. \end{cases}$$

Example



$$\omega_{12} = 1, \omega_{14} = 1,$$

$$\omega_{13} = -1.$$

$$\Omega = \begin{bmatrix} 1 & -1 & 1 & -1 \\ -1 & 1 & -1 & 1 \\ 1 & -1 & 1 & -1 \\ -1 & 1 & -1 & 1 \end{bmatrix}.$$

Ω is proper positive semidefinite of rank 1.

Sufficient Condition for Dimensional Rigidity

Theorem (Connelly '82)

An r -dimensional Tensegrity (G, p) on n nodes in \mathbb{R}^r ($r \leq n - 2$) is *dimensionally rigid* if there exists a *proper positive semidefinite stress matrix* Ω of (G, p) of *rank* $n - r - 1$.

Example



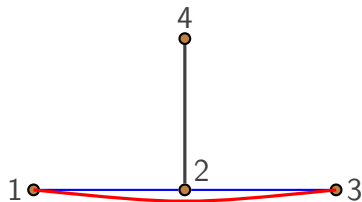
bar



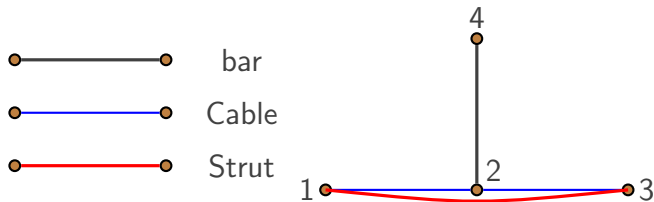
Cable



Strut

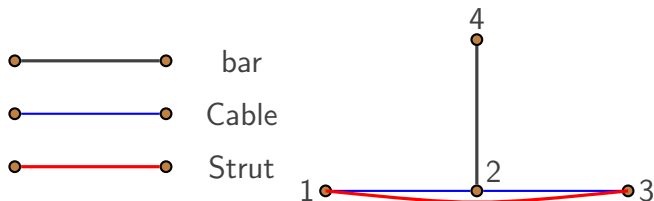


Example



A dimensionally **but not universally rigid** tensegrity.

Example



A dimensionally **but not universally rigid** tensegrity.
The “No Conic at Infinity” Condition does not hold.
In the sequel we concentrate on this condition.

Generic Configurations

Definition

A configuration $p = (p^1, \dots, p^n)$ in \mathbb{R}^r is **generic** if the coordinates of p^1, \dots, p^n are **algebraically independent over the rationals**, i.e., the coordinates of p^1, \dots, p^n do not satisfy any nonzero polynomial with rational coefficients.

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Lemma (Connelly '05)

Let (G, p) be an r -dimensional tensegrity. If **configuration p is generic** and every node of G has degree at least r , then the “no conic at infinity” condition holds. Consequently, **dimensional rigidity implies universal rigidity**.

Configurations in General Position

Definition

A configuration $p = (p^1, \dots, p^n)$ in \mathbb{R}^r is in **general position** if every subset of $\{p^1, \dots, p^n\}$ of **cardinality $r + 1$** is affinely independent.

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Definition

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Definition

A **bar framework** (G, p) is a tensegrity framework where **all the edges are bars**, i.e., $E(G) = B$ and $C = S = \emptyset$.

Lemma (A. and Ye '13)

Let (G, p) be an r -dimensional **bar framework**. If (G, p) admits a **stress matrix Ω of rank $n - r - 1$** and configuration p is in **general position**, then the “no conic at infinity” condition holds. Consequently, **dimensional rigidity implies universal rigidity**.

Let C^* and S^* be the sets of **stressed cables** and **stressed struts** respectively, i.e,

$$C^* = \{\{i, j\} \in C : \omega_{ij} \neq 0\} \text{ and } S^* = \{\{i, j\} \in S : \omega_{ij} \neq 0\}.$$

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Theorem (A. and V-T Nguyen '13)

Let (G, p) be an r -dimensional tensegrity in \mathbb{R}^r . If the following conditions hold:

- 1 there exists a **proper** stress matrix Ω of (G, p) of **rank $n - r - 1$** .
- 2 for each node i , the set $\{p^i\} \cup \{p^j : \{i, j\} \in B \cup C^* \cup S^*\}$ **affinely span \mathbb{R}^r** .

Then the “no conic at infinity” condition holds. Consequently, **dimensional rigidity implies universal rigidity**.

Corollary (A. and V-T Nguyen '13)

Let (G, p) be an r -dimensional tensegrity in \mathbb{R}^r . If the following conditions hold:

- 1 there exists a *proper* stress matrix Ω of (G, p) of rank $n - r - 1$.
- 2 for each node i , the set $\{p^i\} \cup \{p^j : \{i, j\} \in B \cup C^* \cup S^*\}$ is in *general position* in \mathbb{R}^r .

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Theorem (A. and V-T Nguyen '13)

Let (G, p) be an r -dimensional *bar framework* in \mathbb{R}^r . If the following conditions hold:

- 1 there exists a stress matrix Ω of (G, p) of *rank* $n - r - 1$.
- 2 for each node i , the set $\{p^i\} \cup \{p^j : \{i, j\} \in E(G)\}$ *affinely span* \mathbb{R}^r .

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The Idea Behind the Proof

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Then the Gram matrix is PP^T .

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- 3 Thus the universal rigidity problem becomes amenable to semi-definite programming.

Theorem (A. and V-T Nguyen '13)

Let (G, p) be an r -dimensional tensegrity in \mathbb{R}^r and let Ω be a proper positive semidefinite stress matrix of (G, p) . Then Ω is a proper stress matrix for all tensegrities (G, p') dominated by (G, p) .

Gale Matrices

- A **Gale matrix** of r -dimensional tensegrity (G, p) in \mathbb{R}^r is any $n \times (n - r - 1)$ matrix Z such that the **columns of Z form a basis of the null space** of :

$$\begin{bmatrix} p^1 & p^2 & \cdots & p^n \\ 1 & 1 & \cdots & 1 \end{bmatrix} = \begin{bmatrix} P^T \\ e^T \end{bmatrix}.$$

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- The Gale matrix Z encodes the **affine dependencies** among the points p^1, \dots, p^n .

Gale Matrix Z and Stress Matrix Ω

Theorem (A '07)

Let Ω and Z be, respectively, a stress matrix and a Gale matrix of (G, ρ) . Then

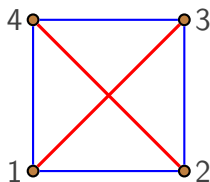
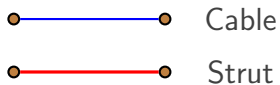
$$\Omega = Z\Psi Z^T \text{ for some symmetric matrix } \Psi.$$

On the other hand, let Ψ' be any symmetric matrix such that

$$z^{i^T} \Psi' z^j = 0 \text{ for all } \{i, j\} \notin E,$$

where z^i is the i th row of Z . Then $Z\Psi' Z^T$ is a stress matrix of (G, ρ) .

Example



Gale matrix is

$$Z = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}.$$

and stress matrix $\Omega = ZZ^T$.

Properties of Gale Transform

Lemma

Let (G, p) be an r -dimensional tensegrity in \mathbb{R}^r and let z^1, \dots, z^n be, respectively, Gale transforms of p^1, \dots, p^n . Let $J \subseteq \{1, \dots, n\}$ and assume that the set of vectors $\{p^i : i \in J\}$ affinely span \mathbb{R}^r . Then the set $\{z^i : i \in \bar{J}\}$ is linearly independent, where $\bar{J} = \{1, \dots, n\} \setminus J$.

Affine-Domination

Let $F^{ij} = (e^i - e^j)(e^i - e^j)^T$, e^i is the i th standard unit vector in \mathbb{R}^n .
Recall that the configuration matrix $P^T = [p^1 \cdots p^n]$.

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Lemma

Let (G, p) be an r -dimensional tensegrity in \mathbb{R}^r . Then the “no conic at infinity” holds iff there **does not exist a nonzero symmetric matrix Φ** such that:

$$\text{trace}(F^{ij}(P\Phi P^T)) = 0 \text{ for all } \{i, j\} \in B.$$

$$\text{trace}(F^{ij}(P\Phi P^T)) \leq 0 \text{ for all } \{i, j\} \in C.$$

$$\text{trace}(F^{ij}(P\Phi P^T)) \geq 0 \text{ for all } \{i, j\} \in S.$$

Affine-Domination

E^{ij} is the matrix with 1s in the ij th and ji th entries and 0's elsewhere.

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Lemma

Let (G, p) be an r -dimensional tensegrity in \mathbb{R}^r and let Z be a Gale matrix of (G, p) . Then the “no conic at infinity” holds iff there **does not exist a nonzero** $y = (y_{ij}) \in \mathbb{R}^{|\bar{E}|+|C|+|S|}$ and $\xi = (\xi_i) \in \mathbb{R}^{n-r-1}$ where $y_{ij} \geq 0$ for all $\{i, j\} \in C$ and $y_{ij} \leq 0$ for all $\{i, j\} \in S$ such that:

$$\mathcal{E}(y)Z = e\xi^T,$$

where $\mathcal{E}(y) = \sum_{\{i,j\} \in \bar{E} \cup C \cup S} y_{ij} E^{ij}$.

Affine-Domination when a proper Ω is Known

The following are equivalent:

- 1 the ‘no conic at infinity’ holds.
- 2 (Whiteley unpublished) \exists symmetric $\Phi \neq 0$ such that:

$$\text{trace}(F^{ij}(P\Phi P^T)) = 0 \text{ for all } \{i, j\} \in B \cup C^* \cup S^*.$$

$$\text{trace}(F^{ij}(P\Phi P^T)) \leq 0 \text{ for all } \{i, j\} \in C^0.$$

$$\text{trace}(F^{ij}(P\Phi P^T)) \geq 0 \text{ for all } \{i, j\} \in S^0.$$

- 3 $\exists y = (y_{ij}) \neq 0 \in \mathbb{R}^{|\bar{E}|+|C^0|+|S^0|}$ and $\xi = (\xi_i) \in \mathbb{R}^{n-r-1}$ where $y_{ij} \geq 0 \forall \{i, j\} \in C^0$ and $y_{ij} \leq 0 \forall \{i, j\} \in S^0$ such that:

$$\mathcal{E}^0(y)Z = e\xi^T,$$

$$\text{where } \mathcal{E}^0(y) = \sum_{\{i, j\} \in \bar{E} \cup C^0 \cup S^0} y_{ij} E^{ij}.$$

Lemma

Assume that $\Omega = Z\Psi Z^T$ is a proper stress matrix of (G, p) of rank $n - r - 1$. Then the following are equivalent:

- 1 the “no conic at infinity” holds
- 2 $\exists y = (y_{ij}) \neq 0 \in \mathbb{R}^{|\bar{E}|+|C^0|+|S^0|}$ and $\xi = (\xi_i) \in \mathbb{R}^{n-r-1}$ where $y_{ij} \geq 0$ for all $\{i, j\} \in C^0$ and $y_{ij} \leq 0$ for all $\{i, j\} \in S^0$ such that:

$$\mathcal{E}^0(y)Z = 0,$$

$$\text{where } \mathcal{E}^0(y) = \sum_{\{i,j\} \in \bar{E} \cup C^0 \cup S^0} y_{ij} E^{ij}.$$

Outline of the Proof of the main Theorem

It suffices to prove that under the theorem assumptions, the **only solution** of

$$\mathcal{E}^0(y)Z = 0 \quad (1)$$

is the **trivial solution** $y = 0$. Hence, the “no conic at infinity” condition holds.

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Equation (1) can be written as

$$\sum_{j=1}^n (\mathcal{E}^0(y))_{ij} z^j = 0 \text{ for all } i = 1, \dots, n.$$

which reduces to

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Thus the result follows from the **linear independence of** $\{z^i : \{i,j\} \in \overline{E} \cup C^0 \cup S^0\}$.

Thank You