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Multiple differentiation processes in differential geometry

Kirill Mackenzie

Sheffield, UK

Focused Research Workshop on Exterior Differential Systems and Lie Theory

Fields Institute

December 13, 2013

1. *Introduction*

Charles Ehresmann (1905–79) :

- ▶ Lie groupoids (*groupoïdes différentiables*)
- ▶ Jets
- ▶ multiple categories
- ▶ (and much else)

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- ▶ Most basic: manifold M to TM , Lie group G to Lie algebra \mathfrak{g} .
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- ▶ Foliation \mathcal{F} on M to tangent distribution.
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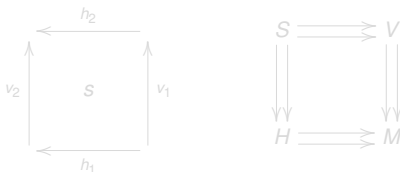
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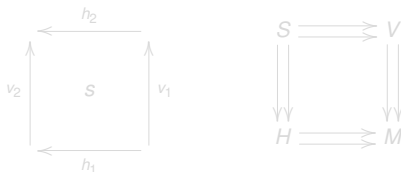


Horizontal composition (when $v'_1 = v_2$) has vertical sources and targets as follows :



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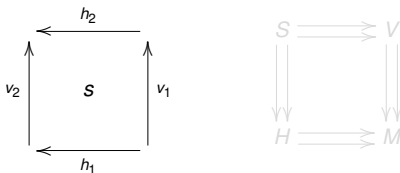


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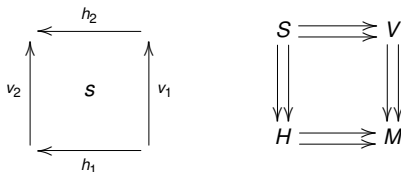


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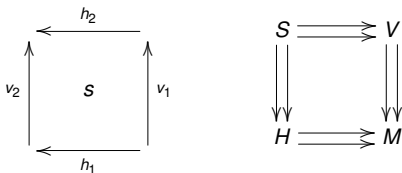


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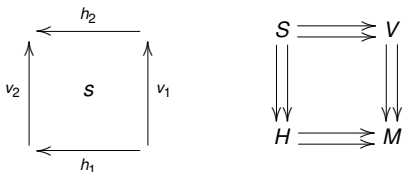


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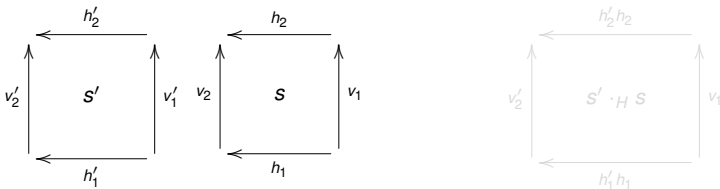


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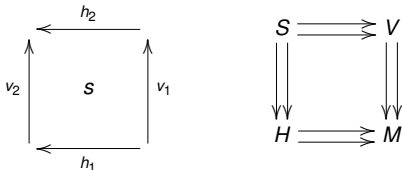


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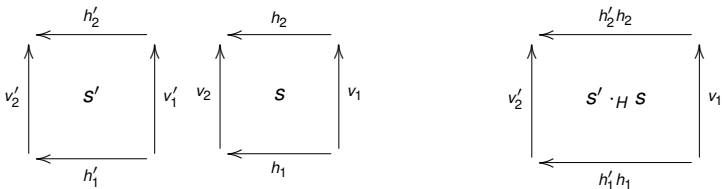


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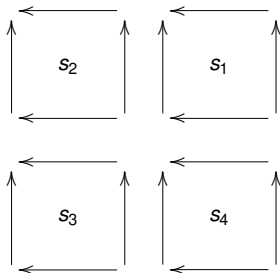


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4. Double Lie groupoids, p2

The main compatibility condition between the two structures is that products of the form



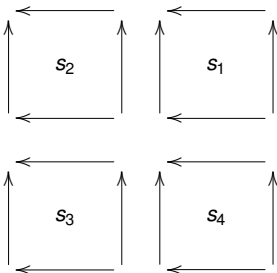
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composing each row horizontally and then the results vertically
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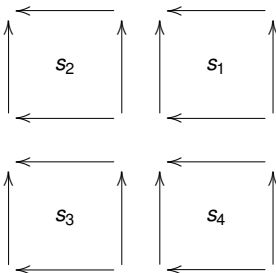
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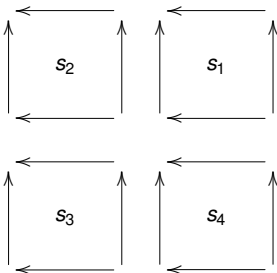
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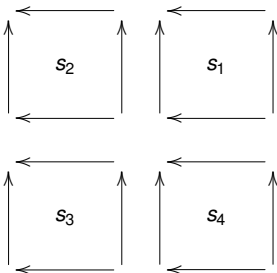
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The main compatibility condition between the two structures is that products of the form



are well-defined:

composing each row horizontally and then the results vertically
and

composing each column vertically and then the results horizontally
give the same result.

5. Lie algebroids of a double Lie groupoid

Given a double Lie groupoid, one can take the Lie algebroid of either groupoid structure on S .

$$\begin{array}{ccc} S & \rightrightarrows & V \\ \Downarrow & & \Downarrow \\ H & \rightrightarrows & M \end{array}$$

Take the Lie algebroid of the vertical structure; the horizontal groupoid structure prolongs to the vertical Lie algebroid.

$$\begin{array}{ccc} A_V S & \rightrightarrows & AV \\ \downarrow & & \downarrow \\ H & \rightrightarrows & M \end{array}$$

Take the Lie algebroid of the horizontal groupoid.

$$\begin{array}{ccc} A_H(A_V S) & \longrightarrow & AV \\ \downarrow & & \downarrow \\ AH & \longrightarrow & M \end{array}$$

$A_H(A_V S)$ is a Lie algebroid over base AV .

The vertical structure $A_H(A_V S) \rightarrow AH$ is at present just a vector bundle.

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6. Lie algebroids of a double Lie groupoid, p2

Recap from previous frame:

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Now do it the other way:

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Every manifold has a canonical involution $T^2 S \rightarrow T^2 S$ which 'interchanges the order of differentiation'. It restricts to a diffeomorphism $A_H(A_V S) \cong A_V(A_H S)$.

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Use this to transfer one structure to the other.

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Use this to transfer one structure to the other.

The result is the *double Lie algebroid* of S .

7. Basic example

For $G \rightrightarrows M$ any Lie groupoid, take $S = G \times G$

$$\begin{array}{ccc} G \times G & \rightrightarrows & G \\ \downarrow & & \downarrow \\ M \times M & \rightrightarrows & M \end{array}$$

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There is a canonical diffeomorphism $T(AG) \cong A(TG)$.

8. In particular ...

Put $G = M \times M$. Then the preceding example is $S = M^4$ and the two forms of the double Lie algebroid are

$$\begin{array}{ccc} T(TM) & \xrightarrow{\rho_{TM}} & TM \\ T(\rho) \downarrow & & \downarrow \rho \\ TM & \xrightarrow{\rho} & M \end{array}$$

$$\begin{array}{ccc} T(TM) & \xrightarrow{T(\rho)} & TM \\ \rho_{TM} \downarrow & & \downarrow \rho \\ TM & \xrightarrow{\rho} & M \end{array}$$

and the canonical diffeomorphism $T^2M \rightarrow T^2M$ is the standard 'interchange of order of differentiation' J which also interchanges the bundle structures on T^2M .

$$\begin{array}{ccccc} T^2M & \xrightarrow{T(\rho)} & TM & & \\ \rho_{TM} \downarrow & \searrow J & \downarrow \rho & & \\ TM & \xrightarrow{\rho} & M & & \\ & & & & T^2M \xrightarrow{\rho_{TM}} TM \\ & & & & \downarrow T(\rho) \\ & & & & TM \xrightarrow{\rho} M \end{array}$$

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9. Local representation

Take $\xi \in T^2M$ with projections

$$\begin{array}{ccc} \xi & \xrightarrow{p_{TM}} & Y \\ T(p) \downarrow & & \downarrow p \\ X & \xrightarrow{p} & m \end{array}$$

If $X = 0$ then ξ is vertical and if $Y = 0$ then ξ is at a zero.

So if $X = Y = 0$ then ξ can be identified with an element Z of TM .

Represent elements of T^2M 'locally' as (X, Y, Z) where the Z is called a *core element*.

Write T^2M 'locally' as $TM * TM * TM$.

Then $J: T^2M \rightarrow T^2M$ is 'locally',

$$J(X, Y, Z) = (Y, X, Z).$$

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Represent elements of T^2M 'locally' as (X, Y, Z) where the Z is called a *core element*.

Write T^2M 'locally' as $TM * TM * TM$.

Then $J: T^2M \rightarrow T^2M$ is 'locally',

$$J(X, Y, Z) = (Y, X, Z).$$

9. Local representation

Take $\xi \in T^2M$ with projections

$$\begin{array}{ccc} \xi & \xrightarrow{p_{TM}} & Y \\ T(\rho) \downarrow & & \downarrow \rho \\ X & \xrightarrow{\rho} & m \end{array}$$

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10. Local representation, p2

More generally, for any vector bundle E on M , there is a double vector bundle

$$\begin{array}{ccc} TE & \xrightarrow{p_E} & E \\ T(q) \downarrow & & \downarrow q \\ TM & \xrightarrow{\rho} & M \end{array}$$

Write elements as

$$\begin{array}{ccc} \xi & \xrightarrow{p_{TM}} & e \\ T(q) \downarrow & & \downarrow q \\ X & \xrightarrow{\rho} & m \end{array}$$

If $X = 0$ and $e = 0$ then ξ can be identified with an element of E .

Write TE 'locally' as $TM * E * E$ and elements as (X, e_1, e_2) .

The e_2 is the core element.

Now dualize TE over E and we get $T^*E \xrightarrow{p_E} E$ written locally as $E * E^* * T^*M$.

$$\begin{array}{ccc} T^*E & \xrightarrow{p_E} & E \\ T(q) \downarrow & & \downarrow q \\ E^* & \xrightarrow{\rho} & M \end{array}$$

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$$\begin{array}{ccc}
 T^*(E^*) & \longrightarrow & E^* \\
 \downarrow & \searrow & \downarrow \\
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 \end{array}
 \xrightarrow{R}
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 \downarrow & & \downarrow \\
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 \end{array}$$

Locally this is $(\varphi, e, \theta) \mapsto (e, \varphi, -\theta)$ where $\varphi \in E^*$, $e \in E$, $\theta \in T^*M$.

Apply this to $E = TM$ and we get $R: T^*(T^*M) \rightarrow T^*(TM)$,

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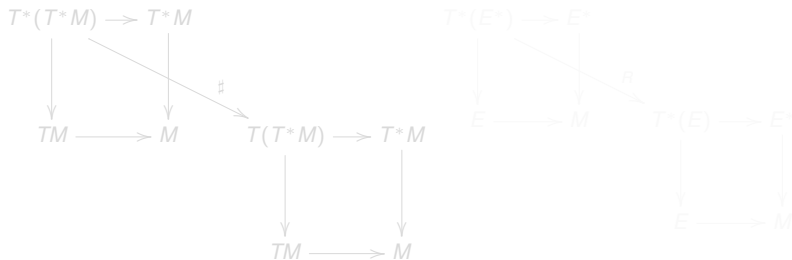
12. Canonical diffeomorphism \sharp

The canonical symplectic structure $d\lambda$ on T^*M induces an isomorphism

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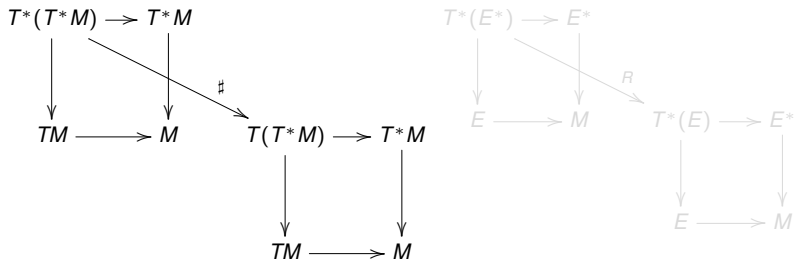
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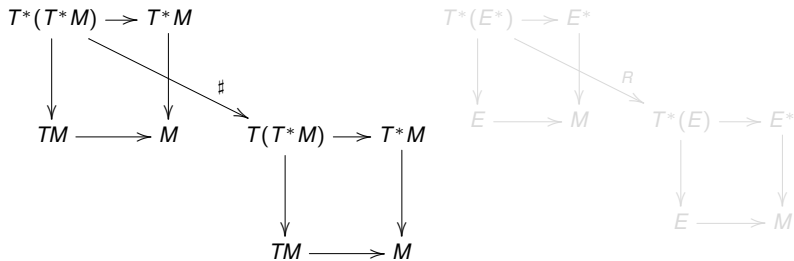
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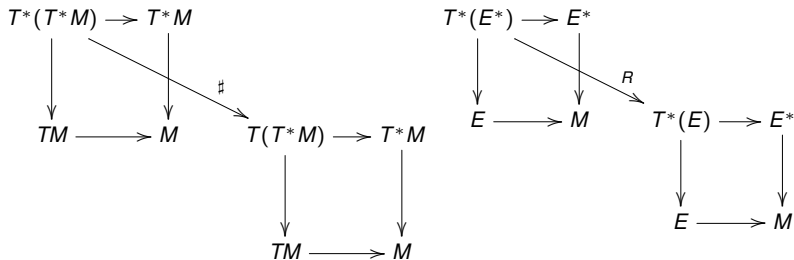
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$$\begin{array}{ccc} T^*T^*M & \xrightarrow{R} & T^*TM \\ \downarrow \sharp & \nearrow \Theta & \\ TT^*M & & \end{array}$$

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Dualizing over X gives $(X, \varphi_1, \varphi_2) \rightarrow (\varphi_1, X, \varphi_2)$.

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This all extends to double Lie groupoids. The question is, why do we want to ?

14. Double Lie groupoids again

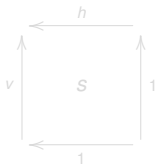
Take the Lie algebroids of a double Lie groupoid S :

$$\begin{array}{ccc}
 A_V S & \rightrightarrows & AV \\
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 H & \rightrightarrows & M
 \end{array}
 \qquad
 \begin{array}{ccc}
 A_H S & \longrightarrow & V \\
 \Downarrow & & \Downarrow \\
 AH & \longrightarrow & M
 \end{array}$$

In each case take the dual. We get

$$\begin{array}{ccc}
 A_V^* S & \rightrightarrows & A^* K \\
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The groupoid $K \rightrightarrows M$ here is the 'core groupoid' of S . The elements of K are the $s \in S$ for which both sources are identity elements.



14. Double Lie groupoids again

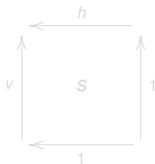
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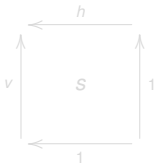
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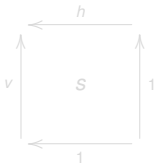
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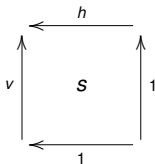
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15. Theorem :

$A_V^*S \rightrightarrows A^*K$ and $A_H^*S \rightrightarrows A^*K$ are Poisson groupoids with respect to the Lie-Poisson structures, and are in duality as Poisson groupoids.

In particular, there is an isomorphism of Lie algebroids

$$\tilde{\sharp}: A^*(A_V^*S) \rightarrow A(A_H^*S).$$

For $S = M^4$ this is $\sharp: T^*(T^*M) \rightarrow T(T^*M)$.

Further there is a commutative diagram.

$$\begin{array}{ccc} A^*(A_V^*S) & \xrightarrow{\tilde{R}} & A^*(A_V S) \\ \tilde{\sharp} \downarrow & \nearrow \tilde{\Theta} & \\ A(A_H^*S) & & \end{array}$$

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The commutative diagram is essential for working with the bialgebroid structure.

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$$\begin{array}{ccc} A^*(A_V^*S) & \xrightarrow{\tilde{R}} & A^*(A_V S) \\ \downarrow \tilde{\sharp} & \nearrow \tilde{\Theta} & \\ A(A_H^*S) & & \end{array}$$

and $\tilde{\Theta}$ may be regarded as the dual of

$$\tilde{J}: A(A_V S) \rightarrow A(A_H S).$$

The commutative diagram is essential for working with the bialgebroid structure.

15. Theorem :

$A_V^*S \rightrightarrows A^*K$ and $A_H^*S \rightrightarrows A^*K$ are Poisson groupoids with respect to the Lie-Poisson structures, and are in duality as Poisson groupoids.

In particular, there is an isomorphism of Lie algebroids

$$\tilde{\sharp}: A^*(A_V^*S) \rightarrow A(A_H^*S).$$

For $S = M^4$ this is $\sharp: T^*(T^*M) \rightarrow T(T^*M)$.

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The commutative diagram is essential for working with the bialgebroid structure.

16. Remark on Poisson group(oid)s

For G a Poisson Lie group:

$$\begin{array}{ccc}
 \Sigma \rightrightarrows G^* & & T^*G \rightrightarrows \mathfrak{g}^* \\
 \Downarrow & \xleftarrow{\text{int}} & \downarrow \\
 G \rightrightarrows \{\cdot\} & & G \rightrightarrows \{\cdot\} \\
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 & & \mathfrak{g} \longrightarrow \{\cdot\}
 \end{array}
 \xrightarrow{\text{diff}}
 \begin{array}{ccc}
 \mathfrak{g} \times \mathfrak{g}^* \longrightarrow \mathfrak{g}^* & & \\
 \downarrow & & \downarrow \\
 \mathfrak{g} \longrightarrow \{\cdot\} & & \{\cdot\}
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For $\mathcal{G} \rightrightarrows M$ a Poisson Lie groupoid:

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 \Sigma \rightrightarrows \mathcal{G}^* & & T^*\mathcal{G} \rightrightarrows A^*\mathcal{G} \\
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For S a double Lie groupoid:

$$\begin{array}{ccc}
 T^*S \rightrightarrows A_H^*S & & T^*(A(A_V^*S)) \longrightarrow A(A_H^*S) \\
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17. n -fold Lie algebroids; super formulation (Th. Voronov)

A Q -manifold is a super vector bundle E on M with a homological vector field Q of weight 1. 'Homological' means $Q^2 = 0$.

Write $A = \Pi E$ for the parity reversed bundle.

Write i for the natural odd injection

$$i: \Gamma A \rightarrow \mathcal{X}(A),$$

Then Q defines a Lie algebroid structure on A with anchor

$$a(u)f := [[Q, i(u)], f]$$

and bracket

$$i([u, v]) := (-1)^{|u|} [[Q, i(u)], i(v)].$$

for $f \in C^\infty(M)$, and $u, v \in \Gamma A$. (Vaïntrob.)

In local coordinates (x^a in the base, ξ^i in the parity-reversed fibres)

$$Q = \xi^i Q_i^a(x) \frac{\partial}{\partial x^a} + \frac{1}{2} \xi^i \xi^j Q_{ij}^k(x) \frac{\partial}{\partial \xi^k}.$$

Given a super double vector bundle, and writing D for the double-parity-reversed double vector bundle, two homological vector fields Q_1, Q_2 define a double Lie algebroid structure on D if

$$[Q_1, Q_2] = 0.$$

This extends in a ready fashion to the n -fold case.

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18. A few references

For double Lie groupoids and double Lie algebroids see

- KM, Ehresmann doubles and Drinfel'd doubles for Lie algebroids and Lie bialgebroids. *J. Reine Angew. Math.*, 658:193–245, 2011.

and earlier KM papers cited there.

- Lie bialgebroids were introduced in

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- The formulation of Lie algebroids in terms of Q -manifolds is from

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19. *End frame*